Optimal Streaming Approximations for all Boolean Max 2-CSPs and Max k-SAT



Chi-Ning Chou

Sasha Golonev

Harvard University

FOCS 2020



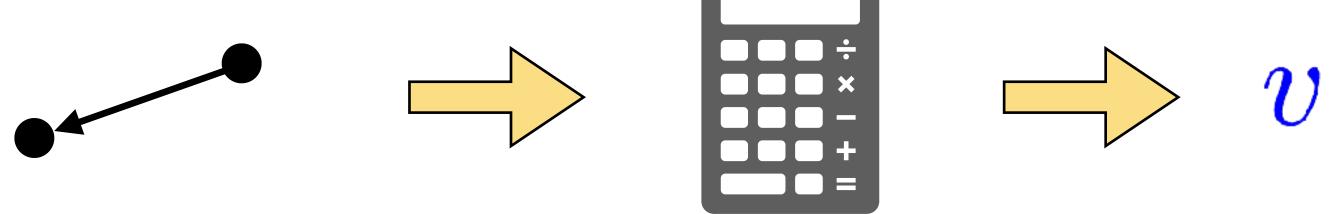
Santhoshini Velusamy

Constraint satisfaction problem (CSP) in the streaming model.

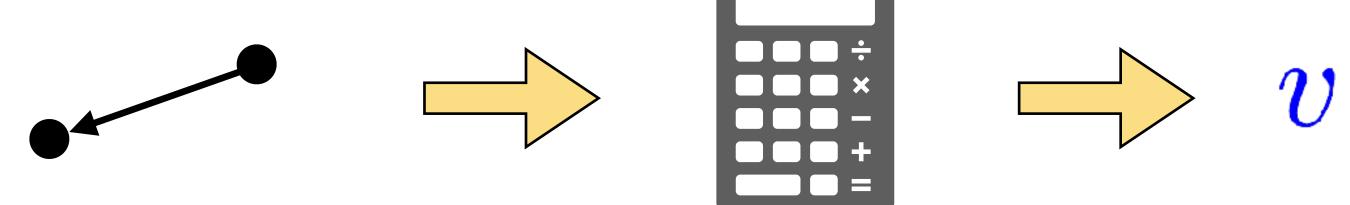
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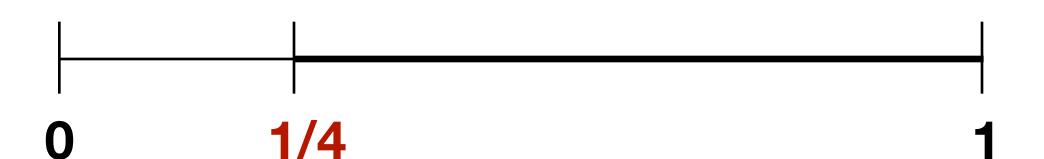
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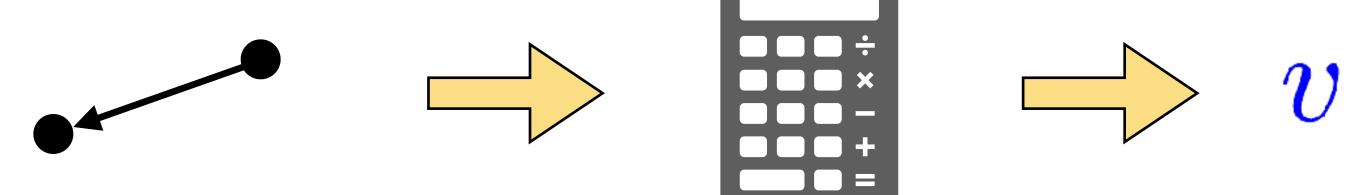


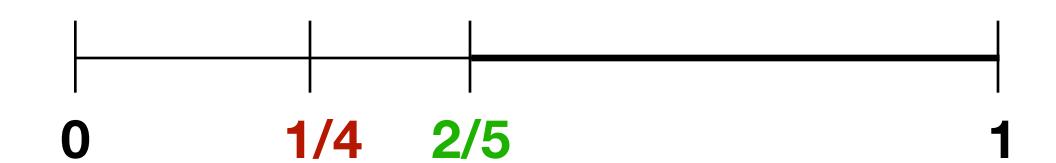
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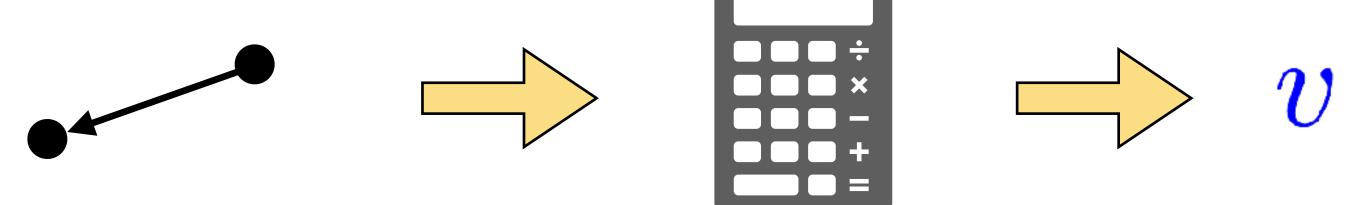


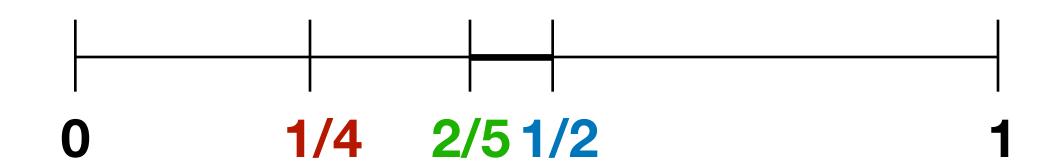
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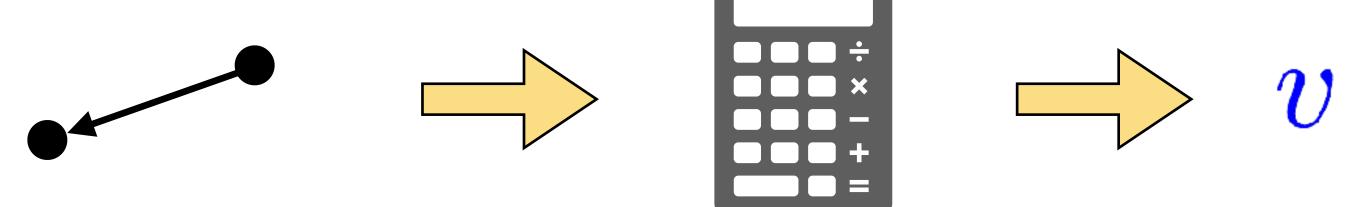


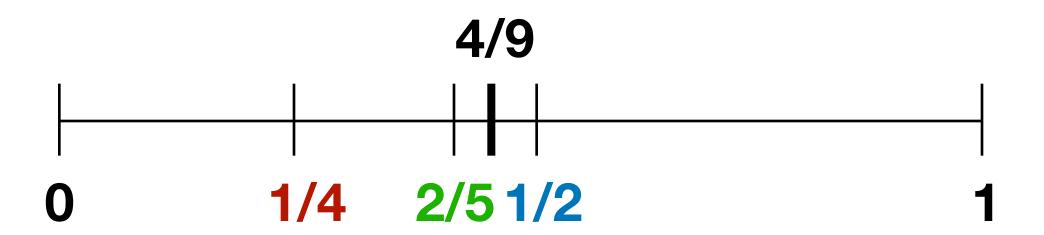
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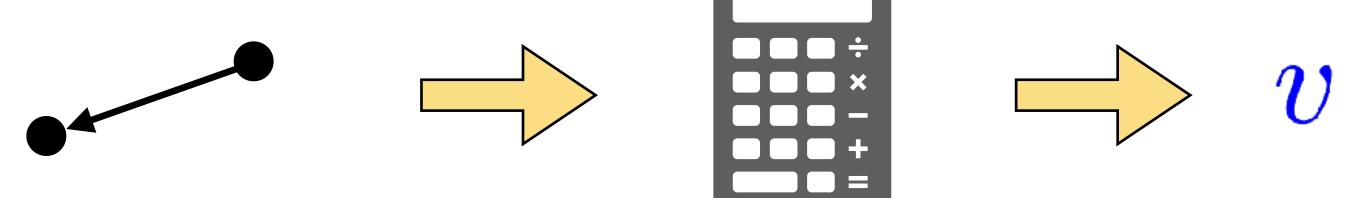


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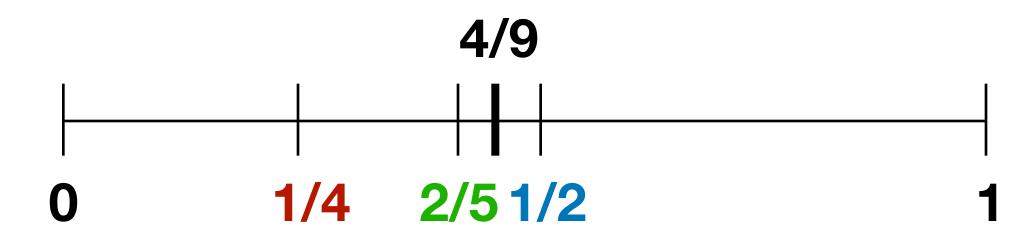




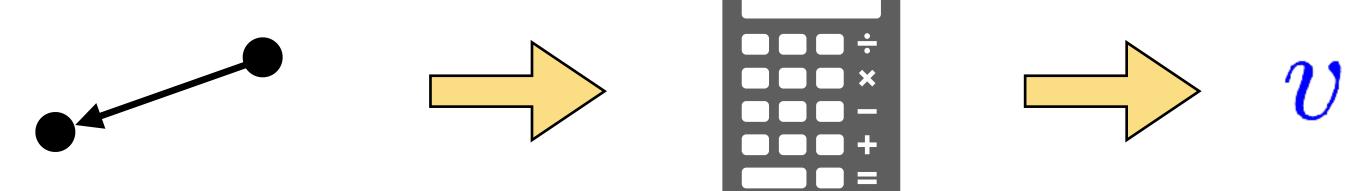
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- Further, we characterize the approximation ratio of every boolean 2-CSP!

Definitions

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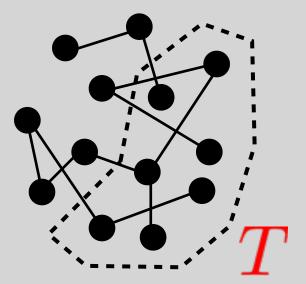
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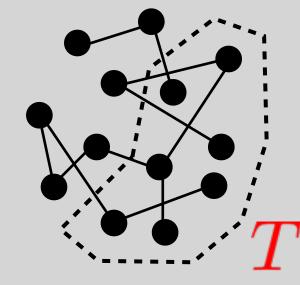
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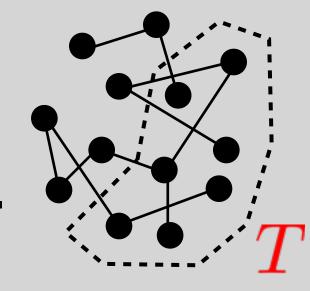
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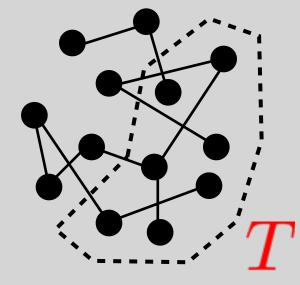
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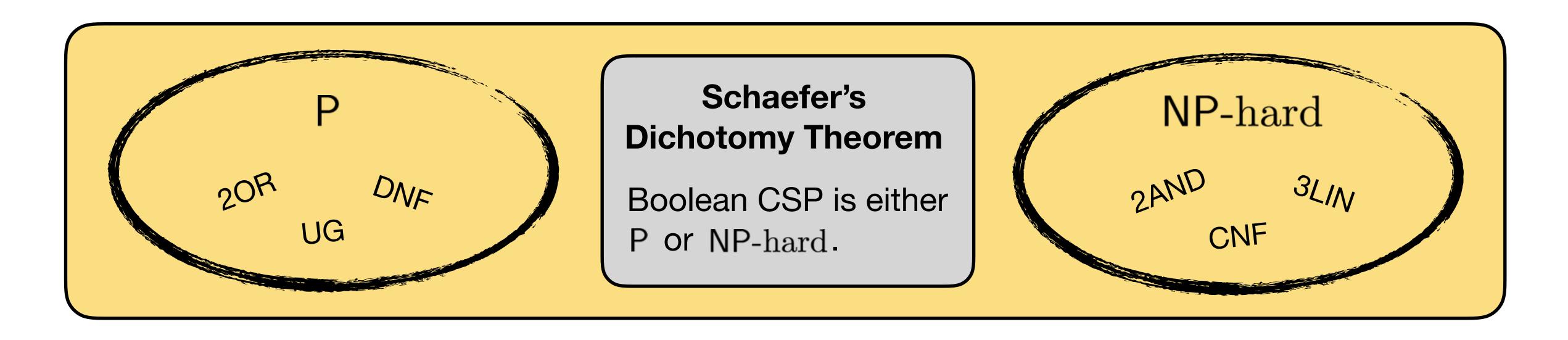


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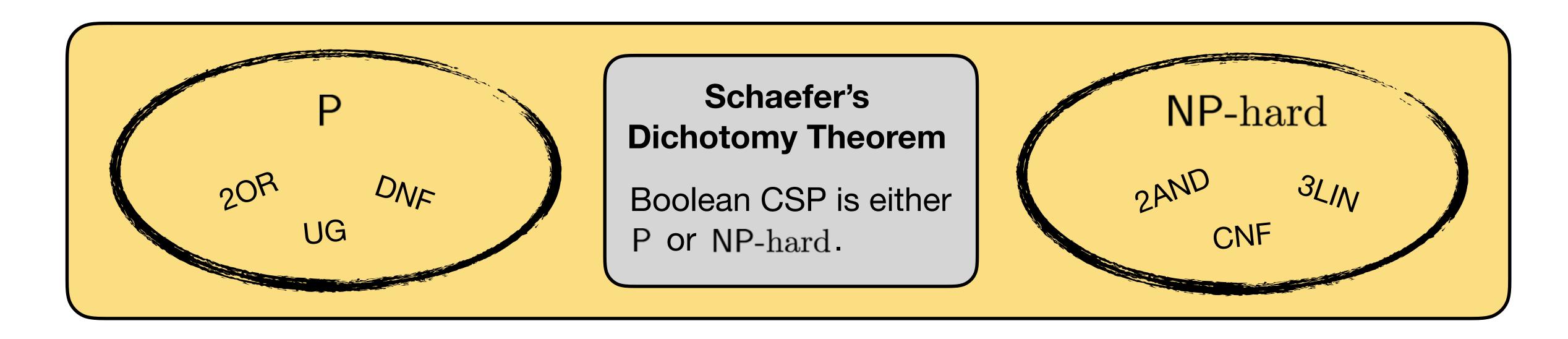
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What about solving CSP approximately?

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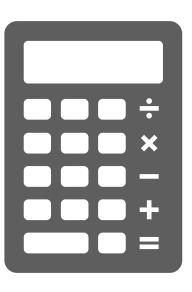
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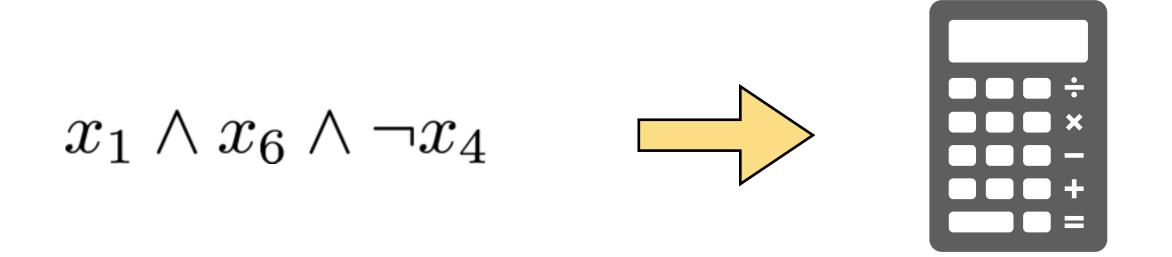
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- Many fascinating results and open problems!

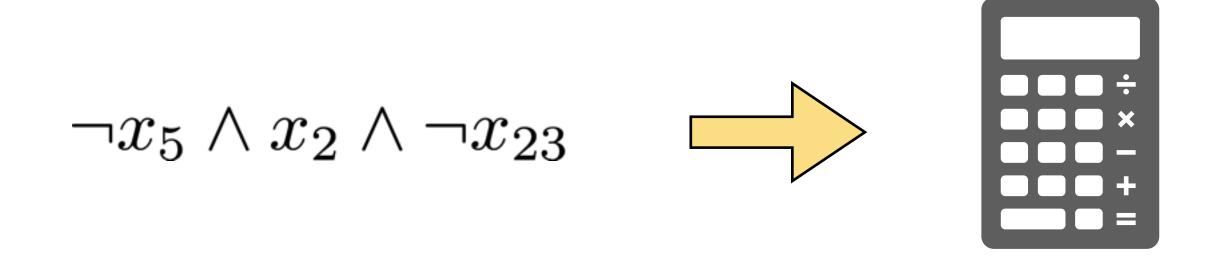
Unifying Theory for Approx. CSP!?

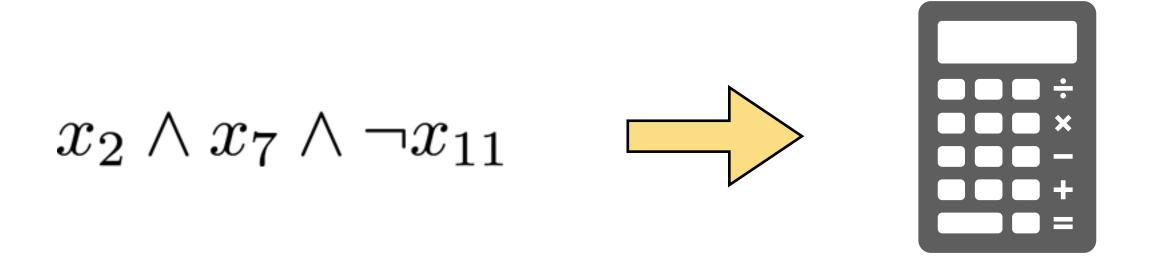
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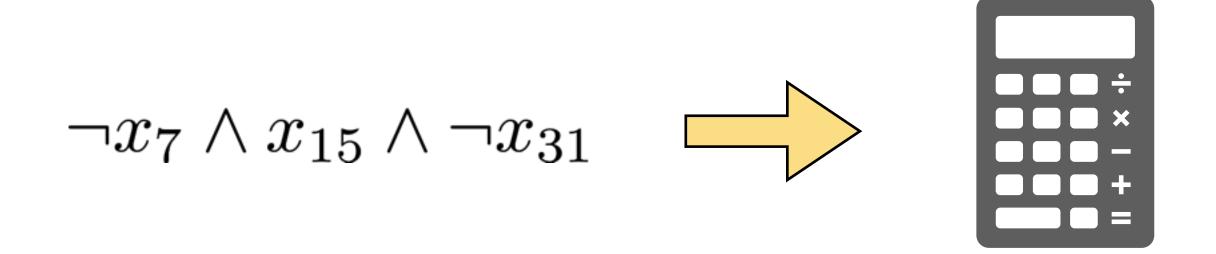
Through the Lens of Streaming Model

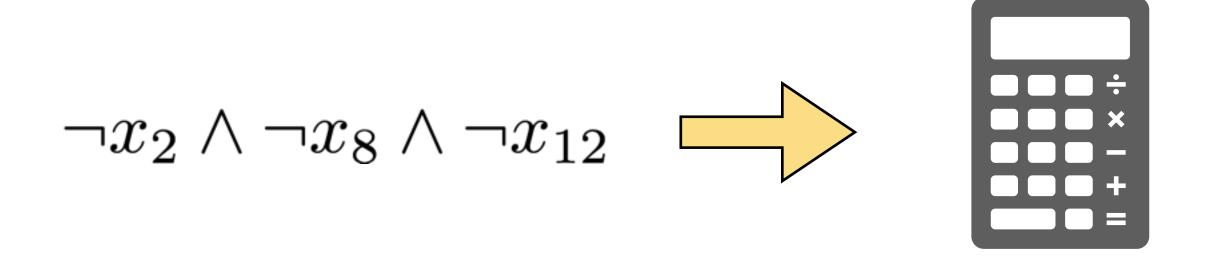




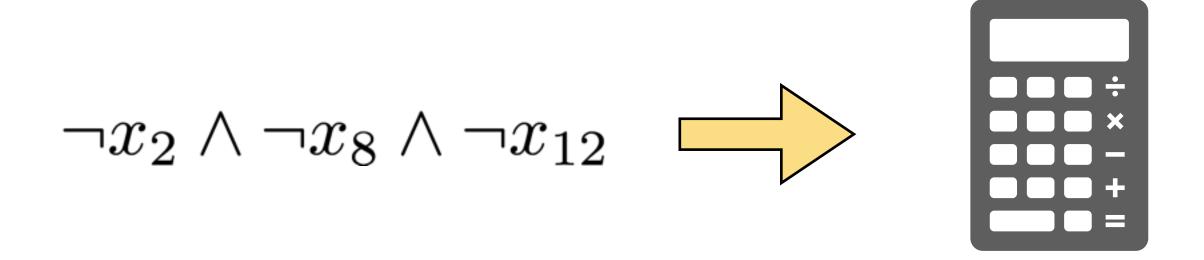




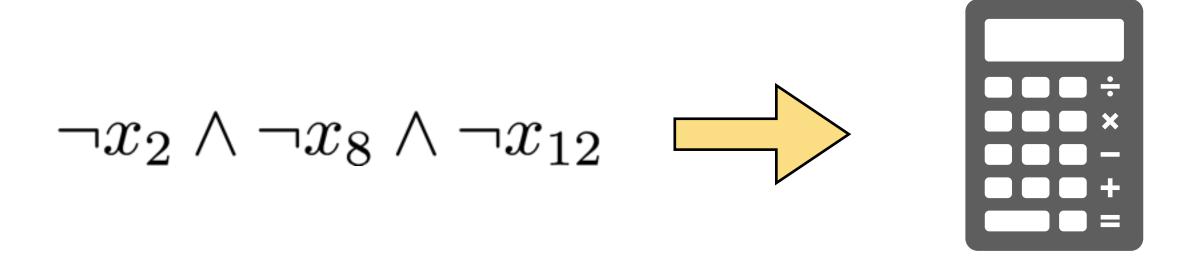




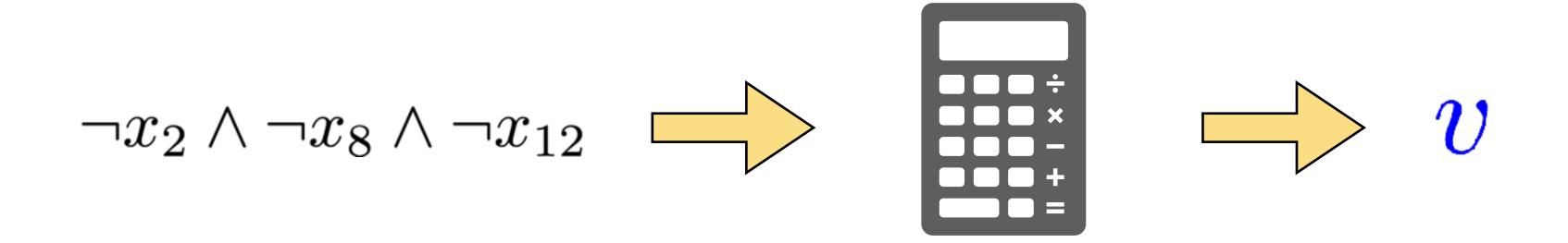
• The input (each constraint) arrives in a stream.



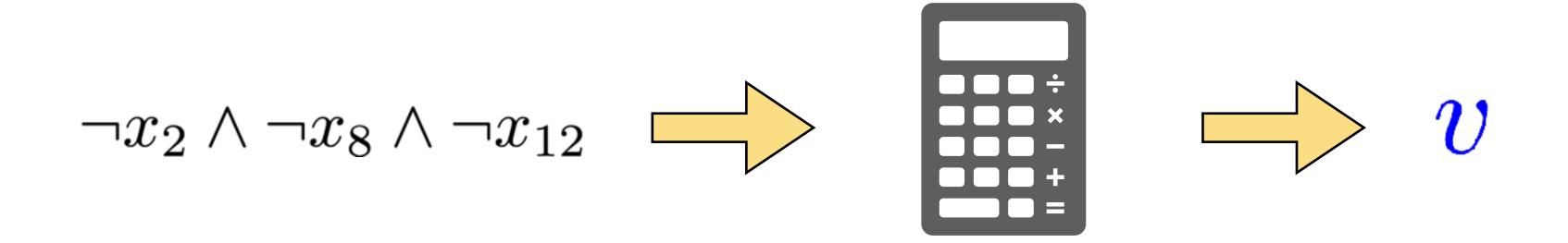
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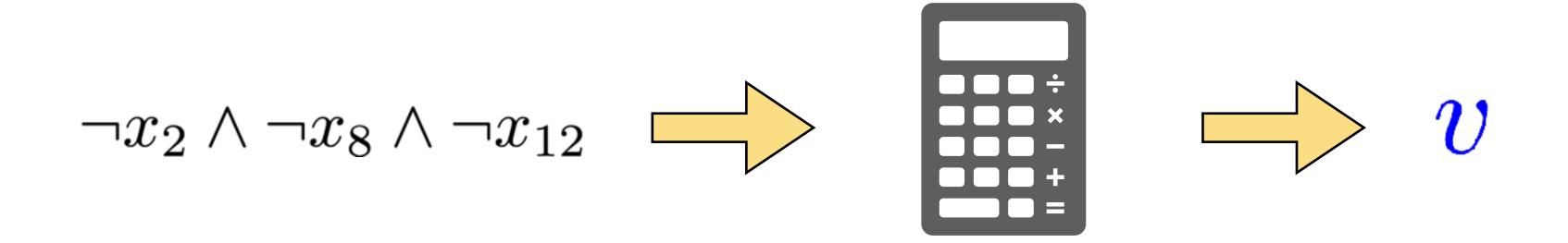
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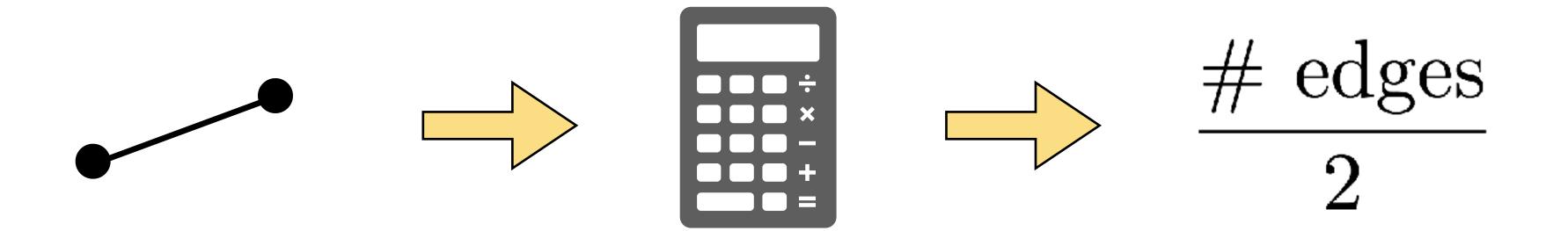
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 - $v \geq \alpha \cdot \mathsf{val}_{\mathcal{C}}$.



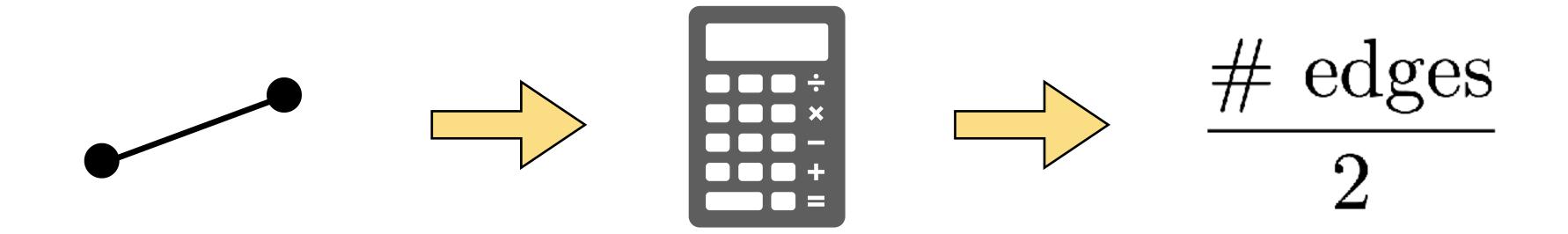
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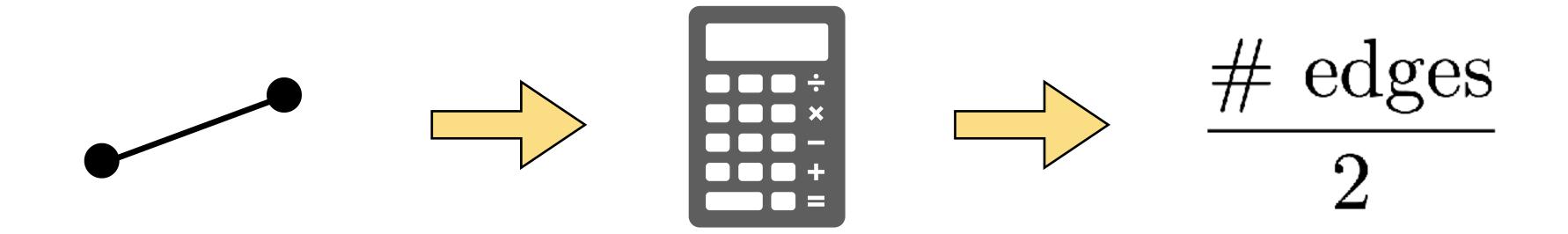
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 - + [Kapralov-Khanna-Sudan 15]: $\tilde{\Omega}(\sqrt{n})$ space.

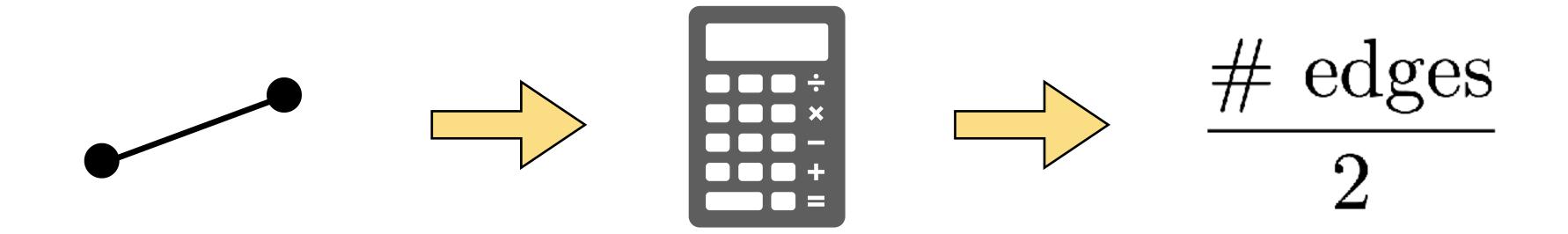


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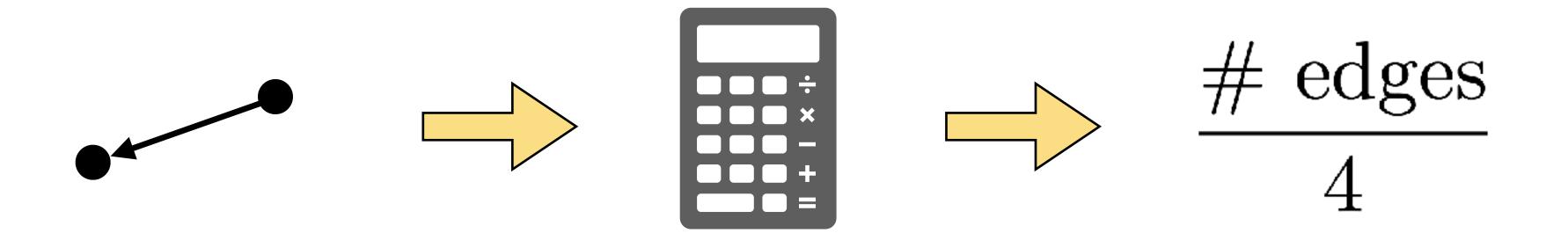
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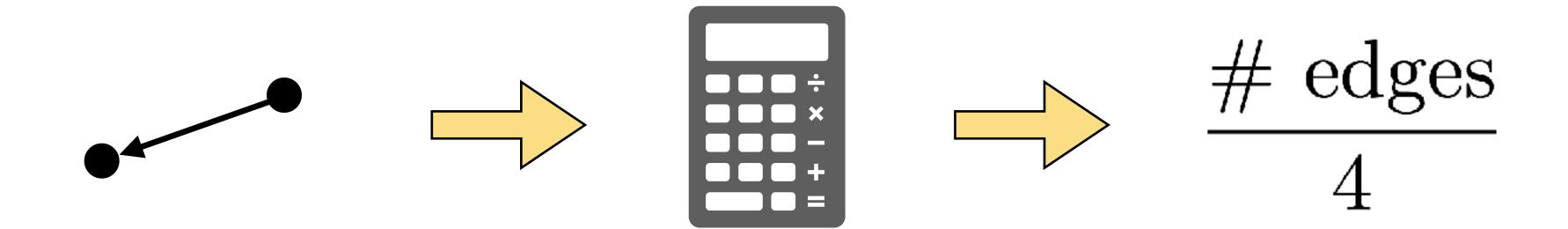


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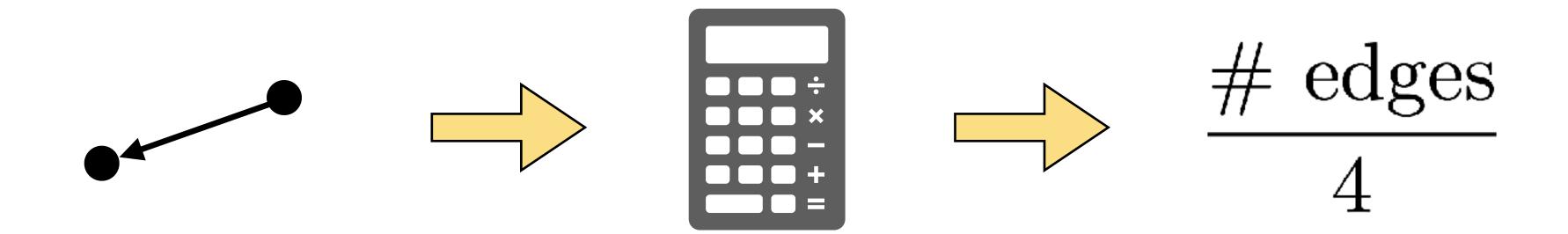
There's a SDP-based algorithm which gives **0.878**-approx.



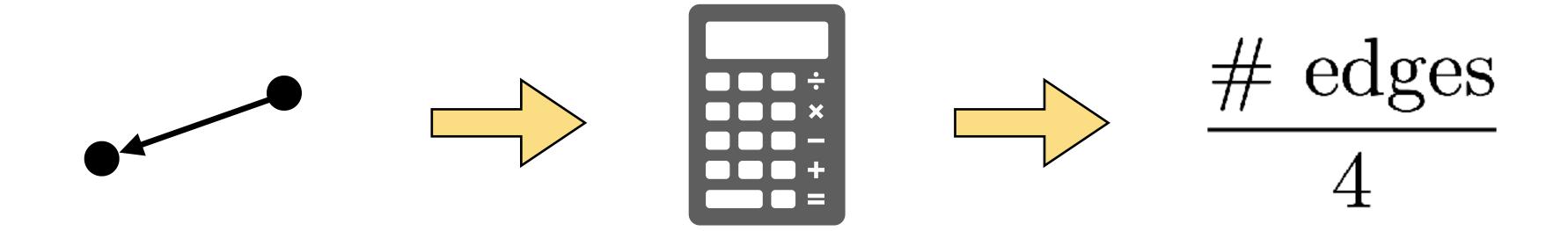
• Trivial random sampling now gives 1/4-approximation using $O(\log n)$ space.



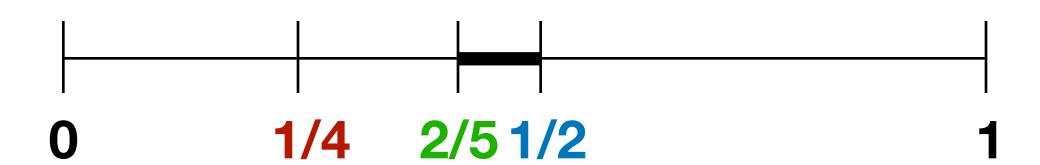
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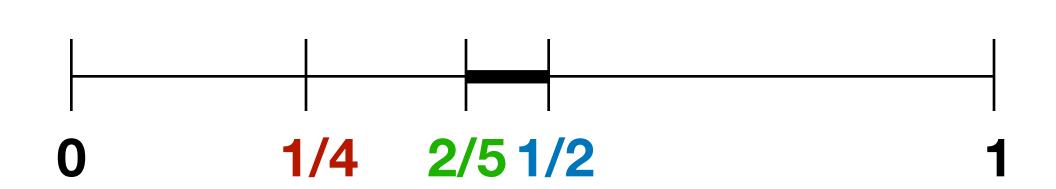


Max-DICUT in the Streaming Model

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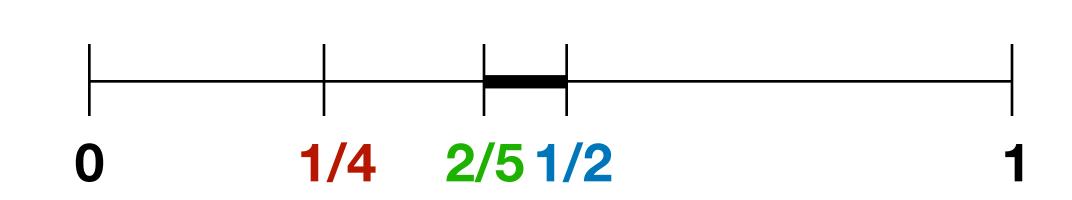


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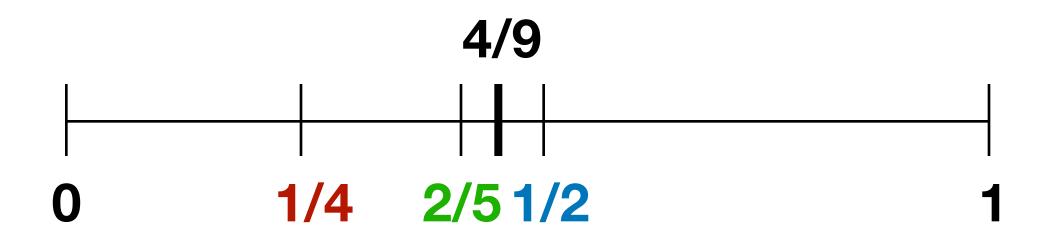
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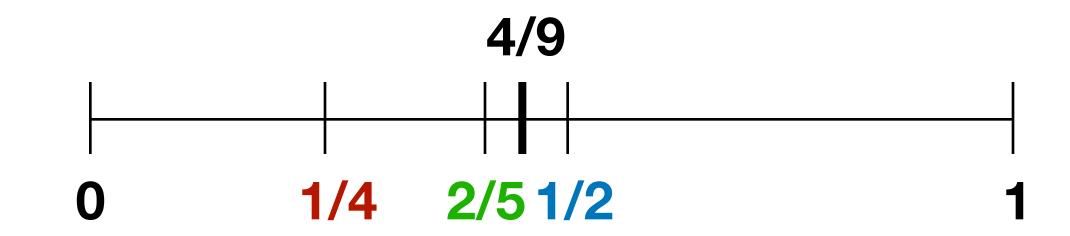
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- What's the "right approximation ratio"?
- What about other CSP?



• The answer of Max-DICUT is 4/9 @

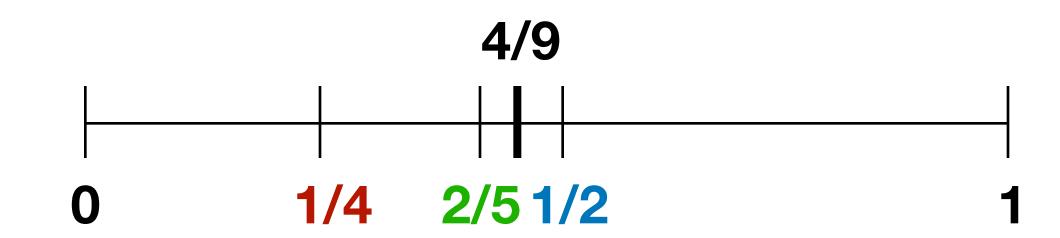


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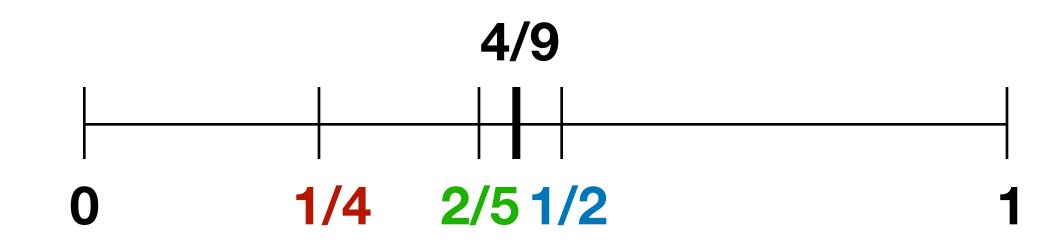
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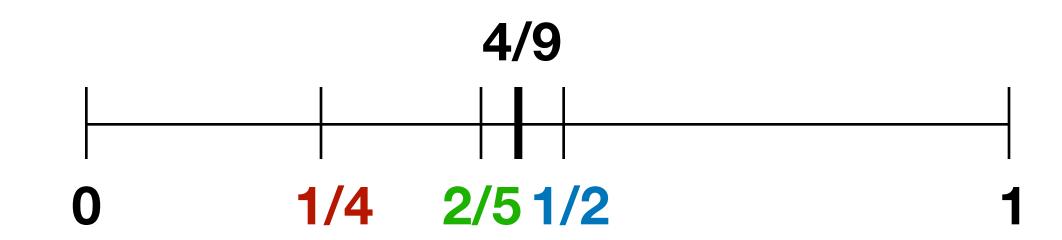
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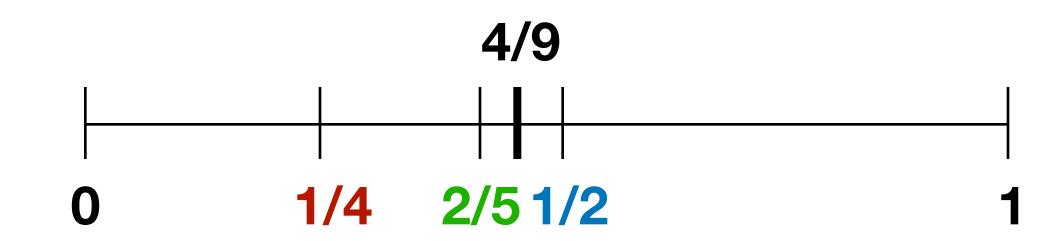
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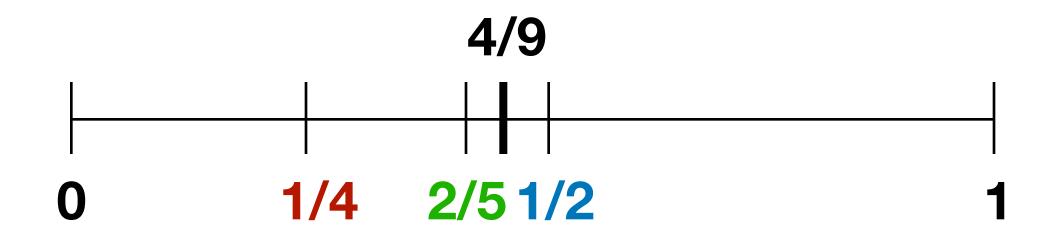


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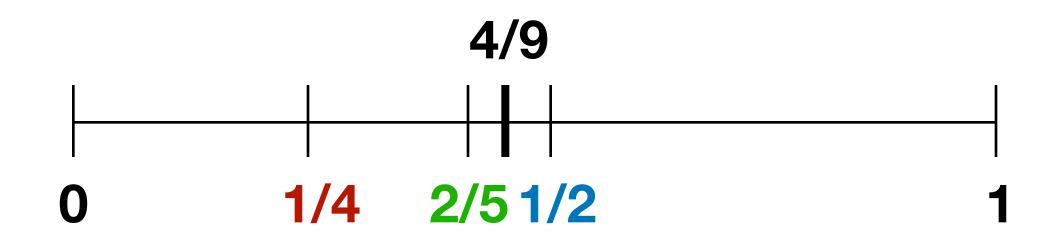
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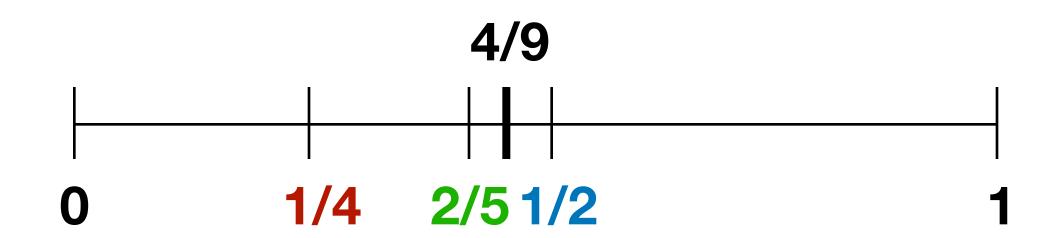
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Λ	α_{Λ}	$ au_{f \Lambda}$	Reference
XOR	$\frac{1}{2}$	1	[KK19]

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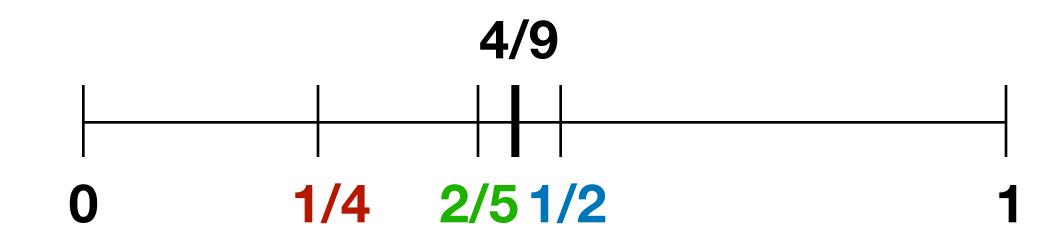
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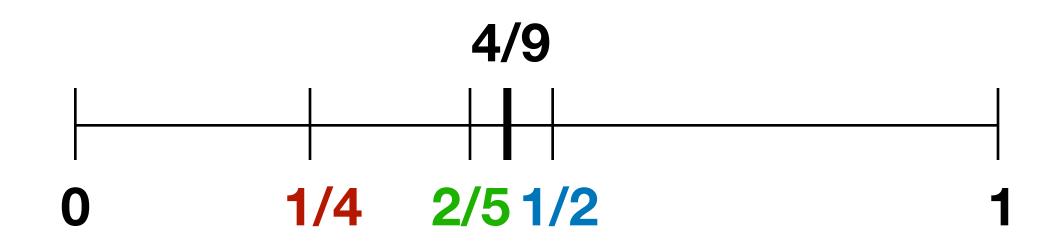
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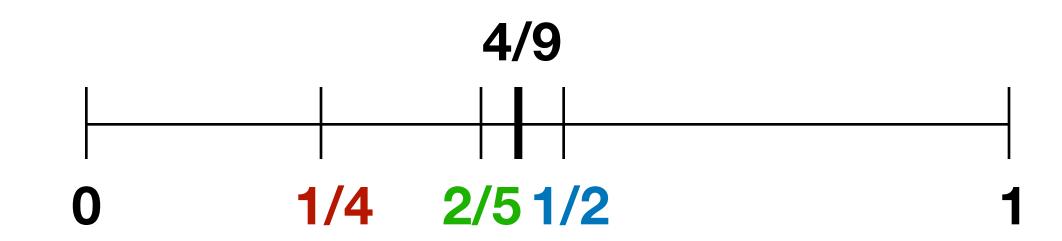
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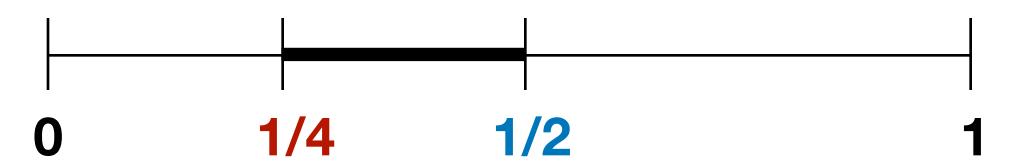
Can be extended to Max k-SAT!

Algorithms

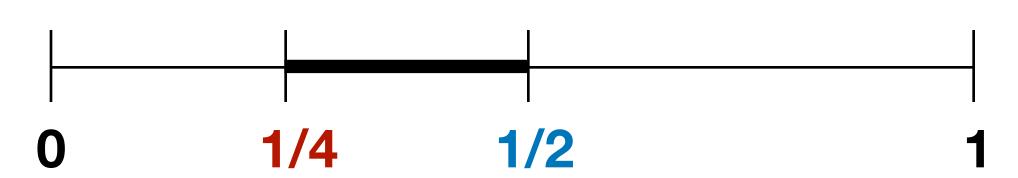
Algorithms

with a focus on Max-DICUT

• Recall: Trivial algorithm gives 1/4-approx. while 1/2-approx. is hard.

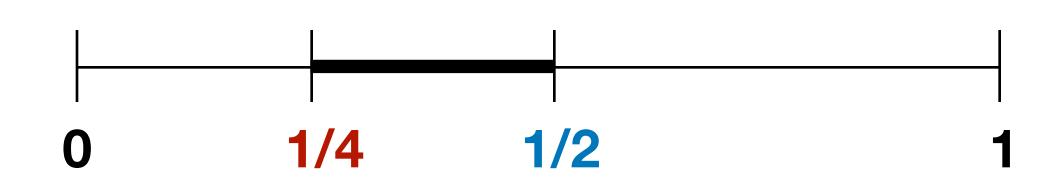


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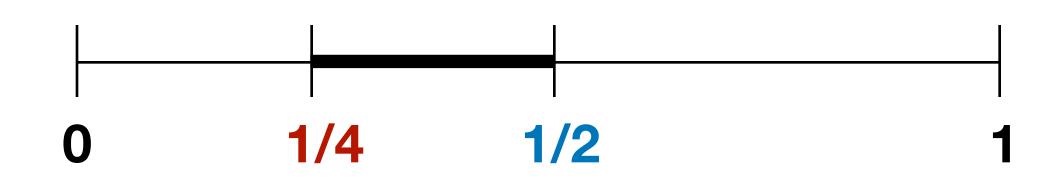
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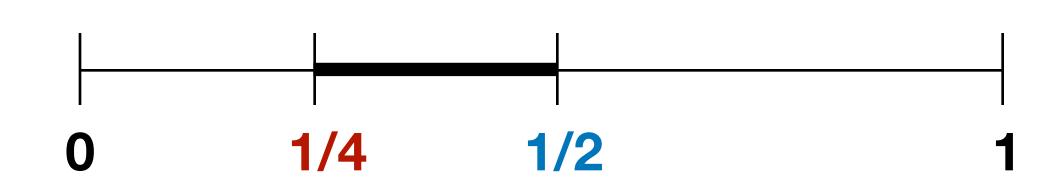
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Example:

$$\mathsf{bias}(2) = -1$$

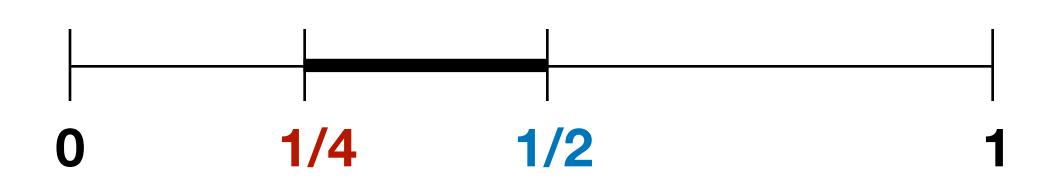
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$$\mathsf{bias}\left(\mathbf{X}\right) = -1$$



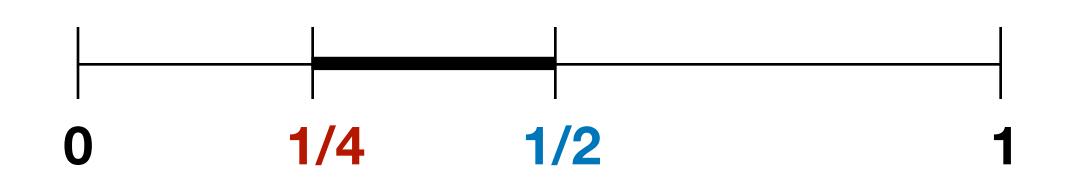
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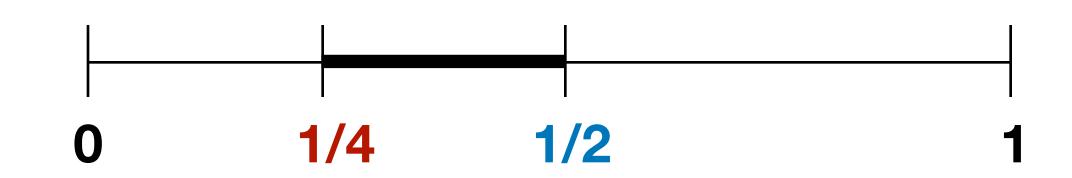
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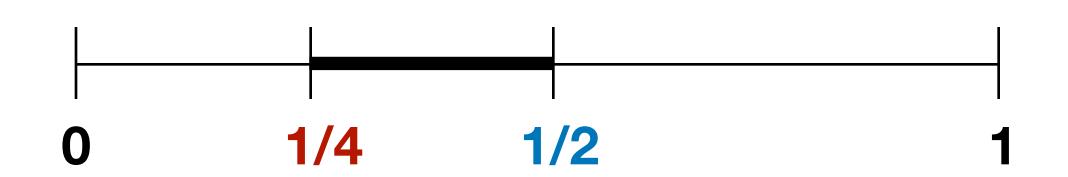
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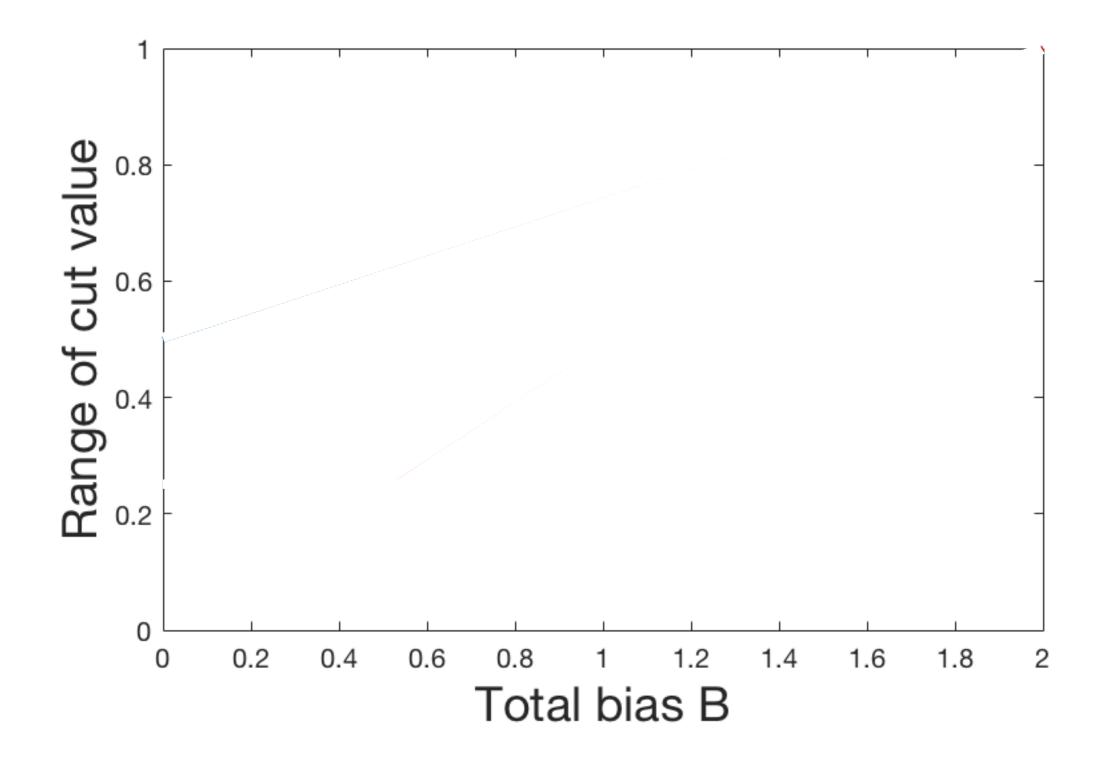
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- Understand the relation between B and $val_{\mathcal{C}}$ could give approximation.

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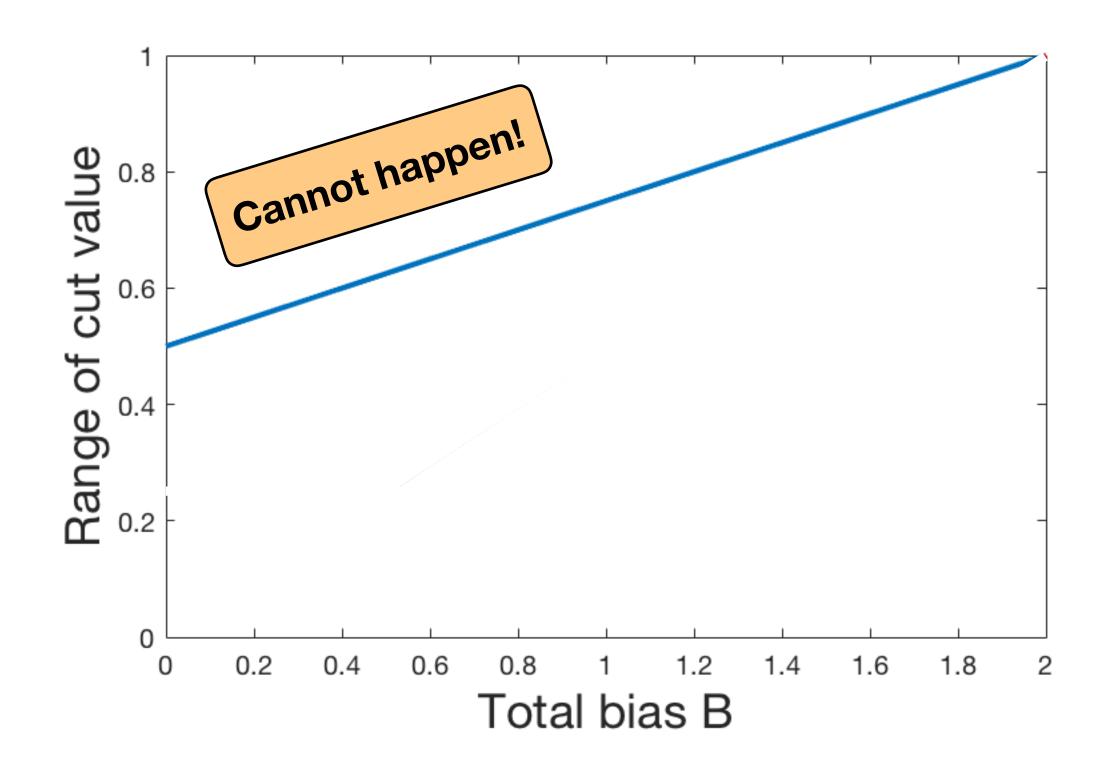
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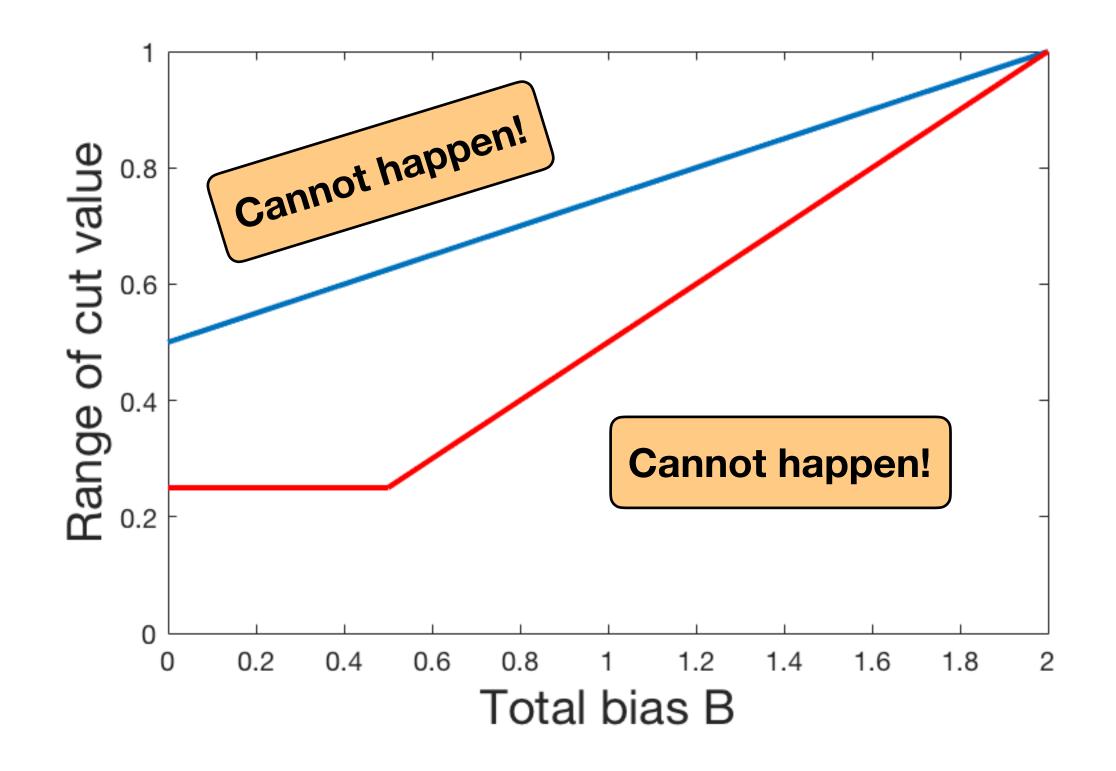
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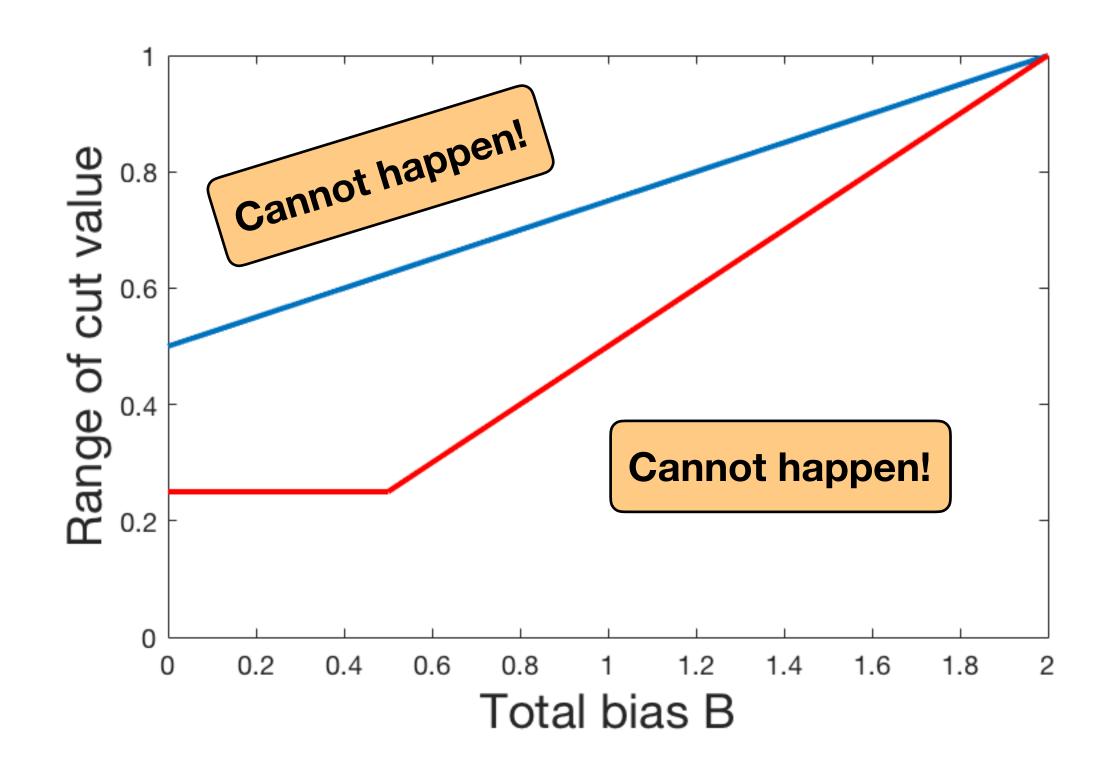


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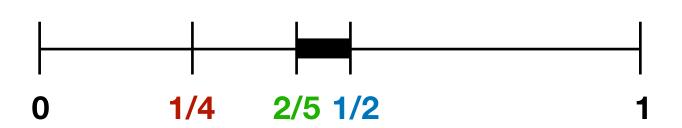
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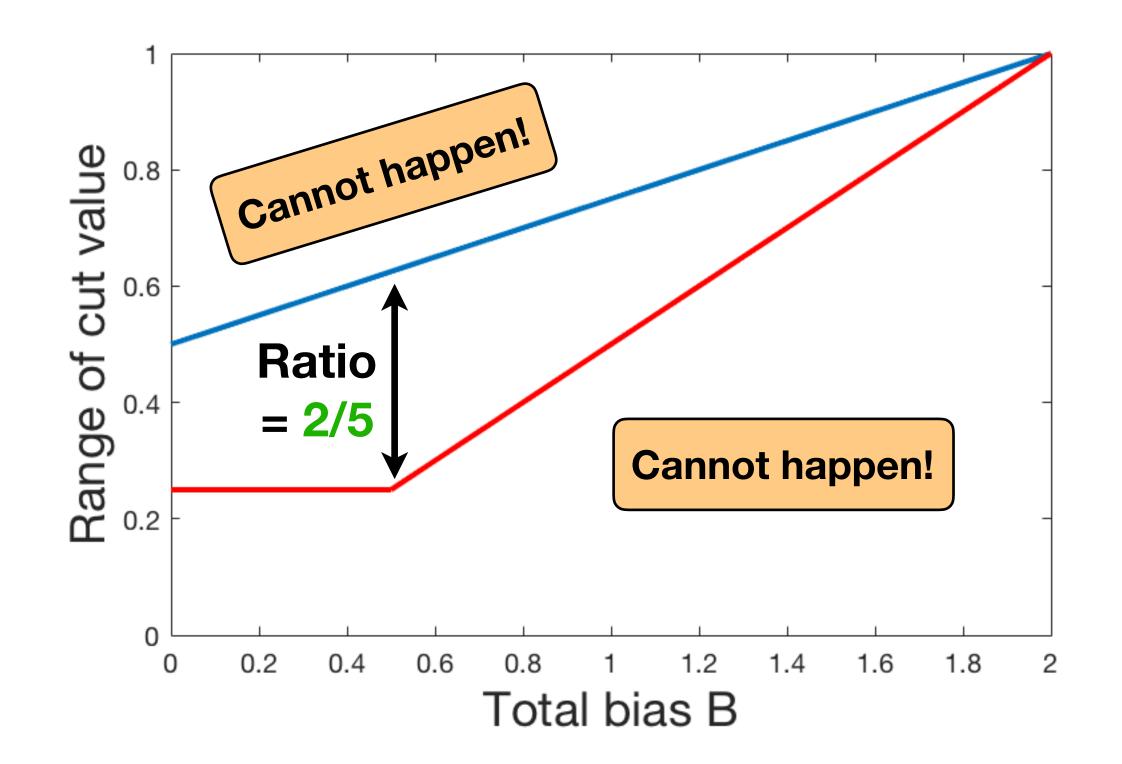
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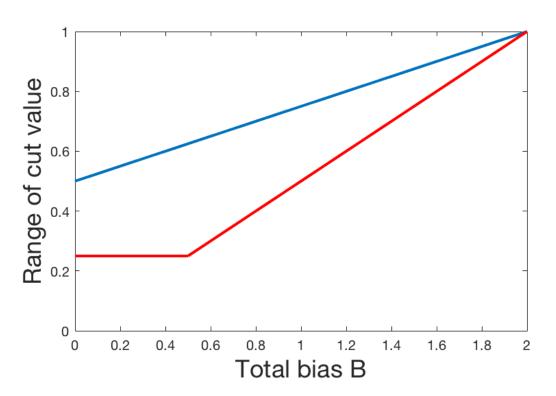
New Idea: Random Sampling

New Idea: Random Sampling with Bias

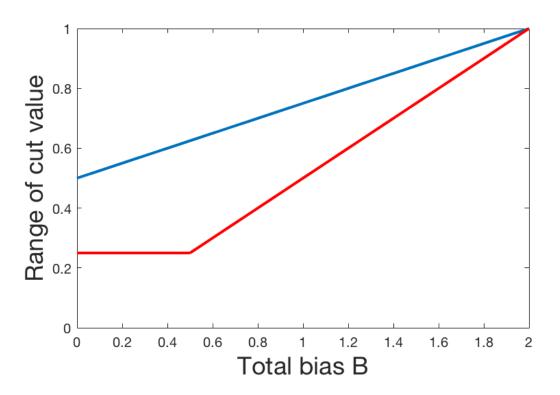
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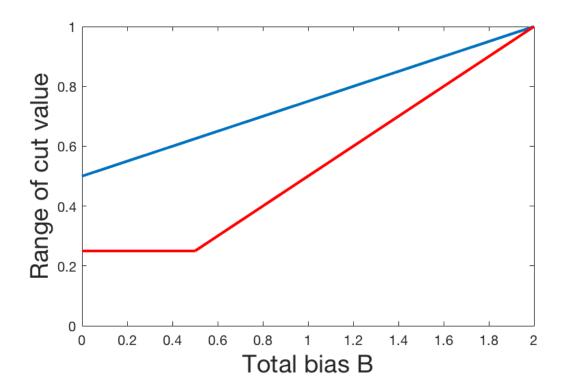
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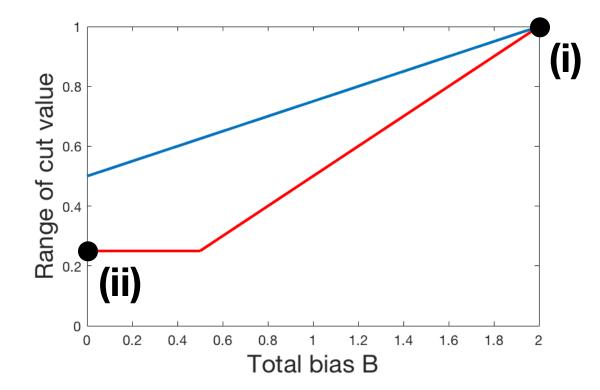
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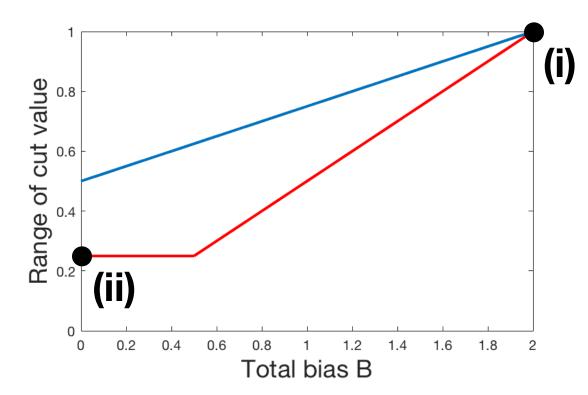


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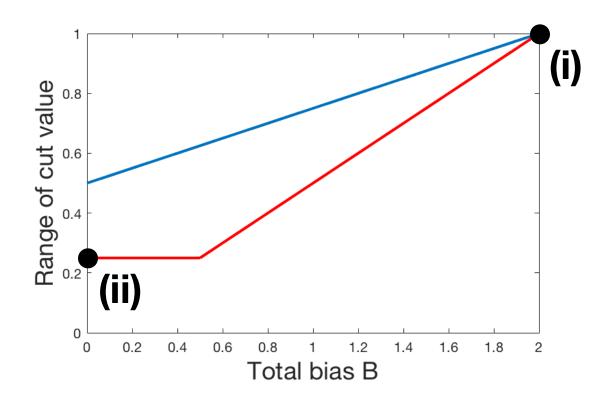
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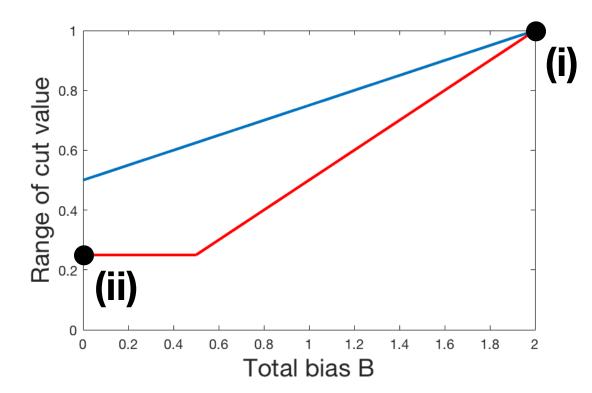
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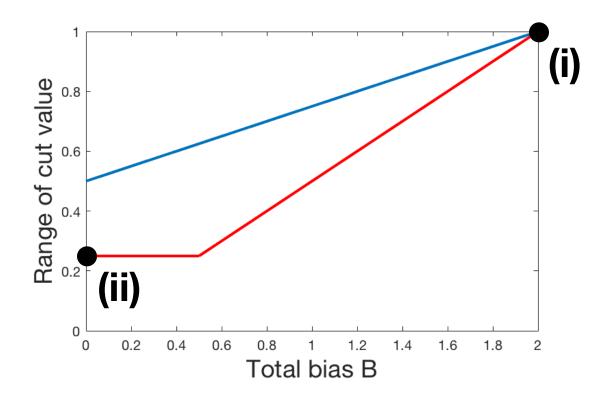
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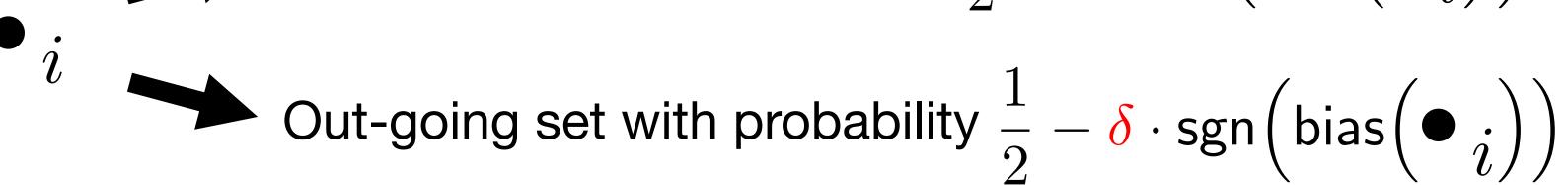
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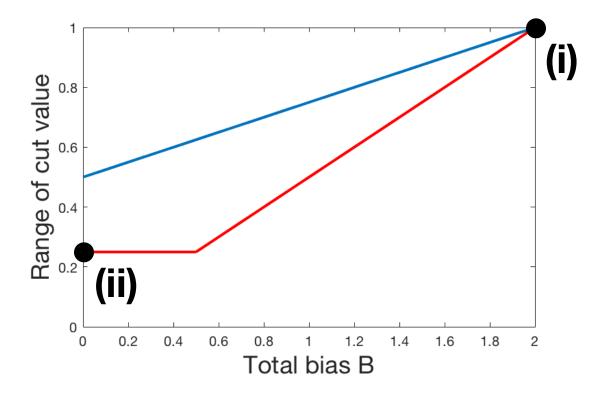


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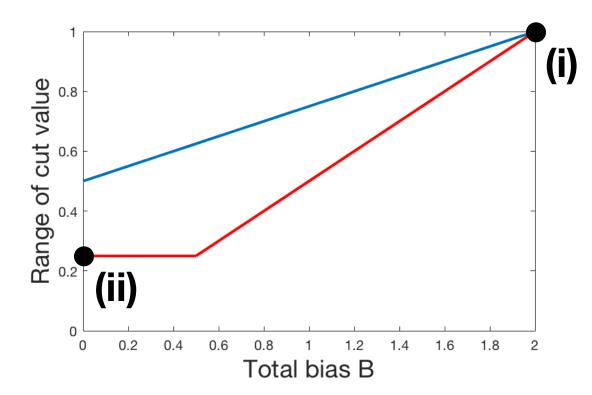
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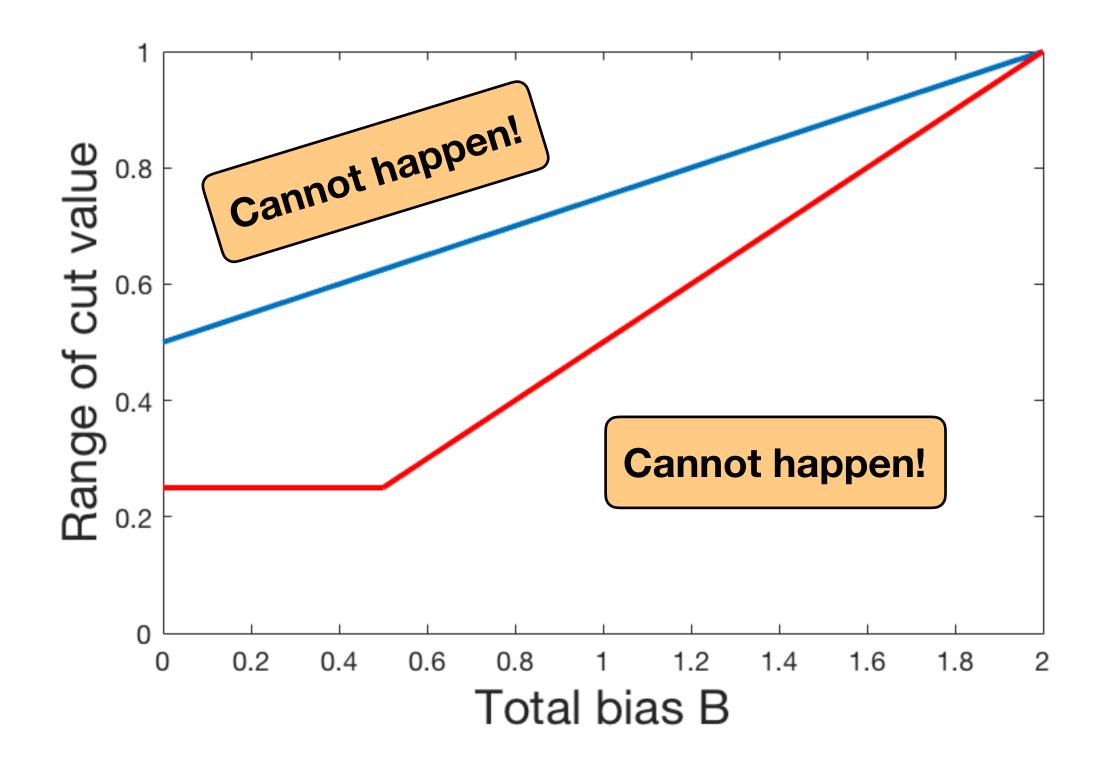
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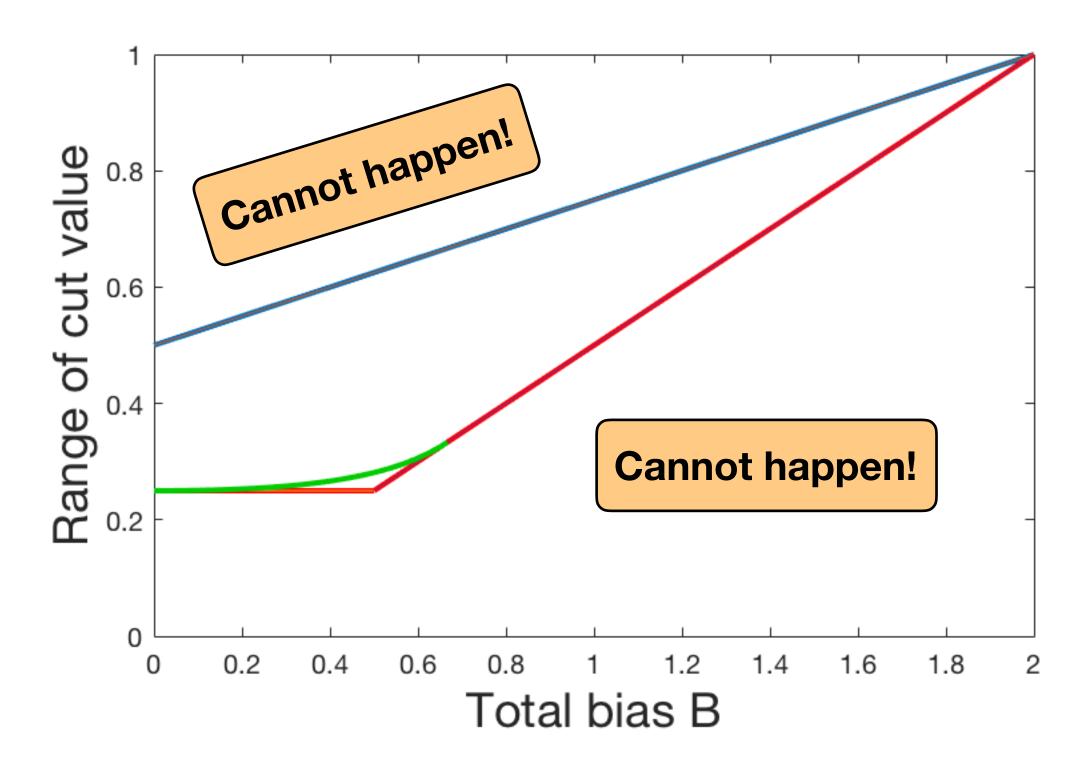
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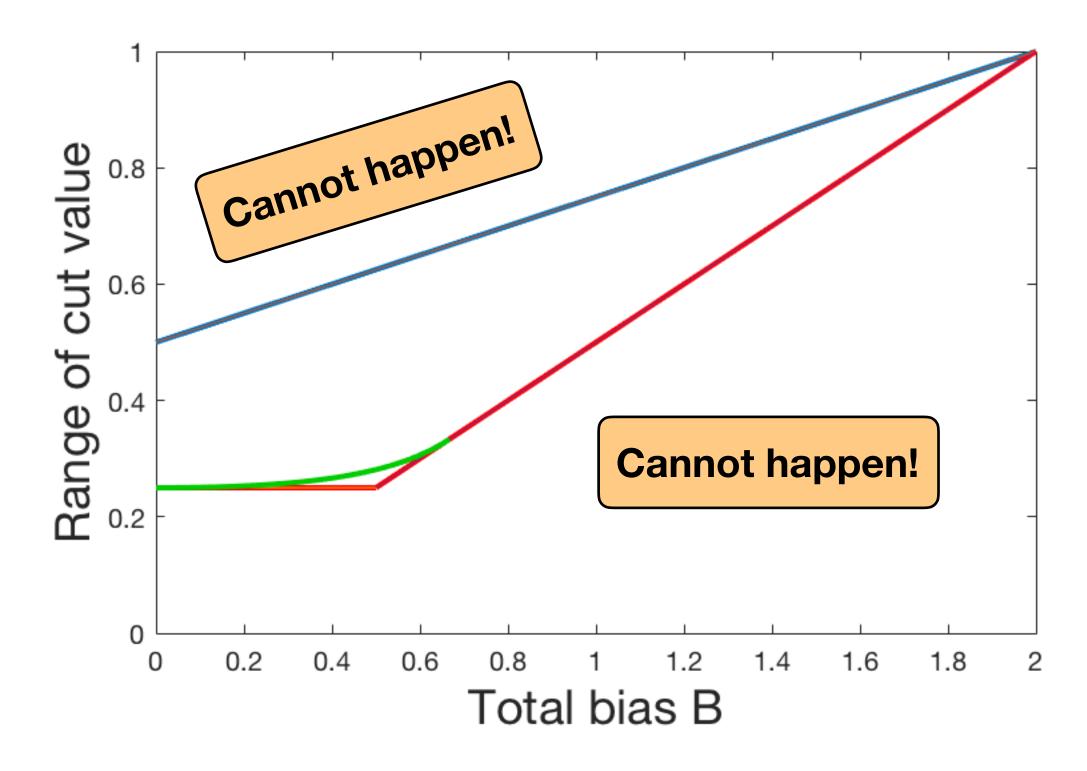
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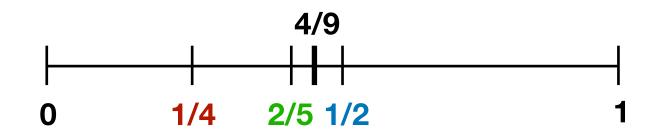


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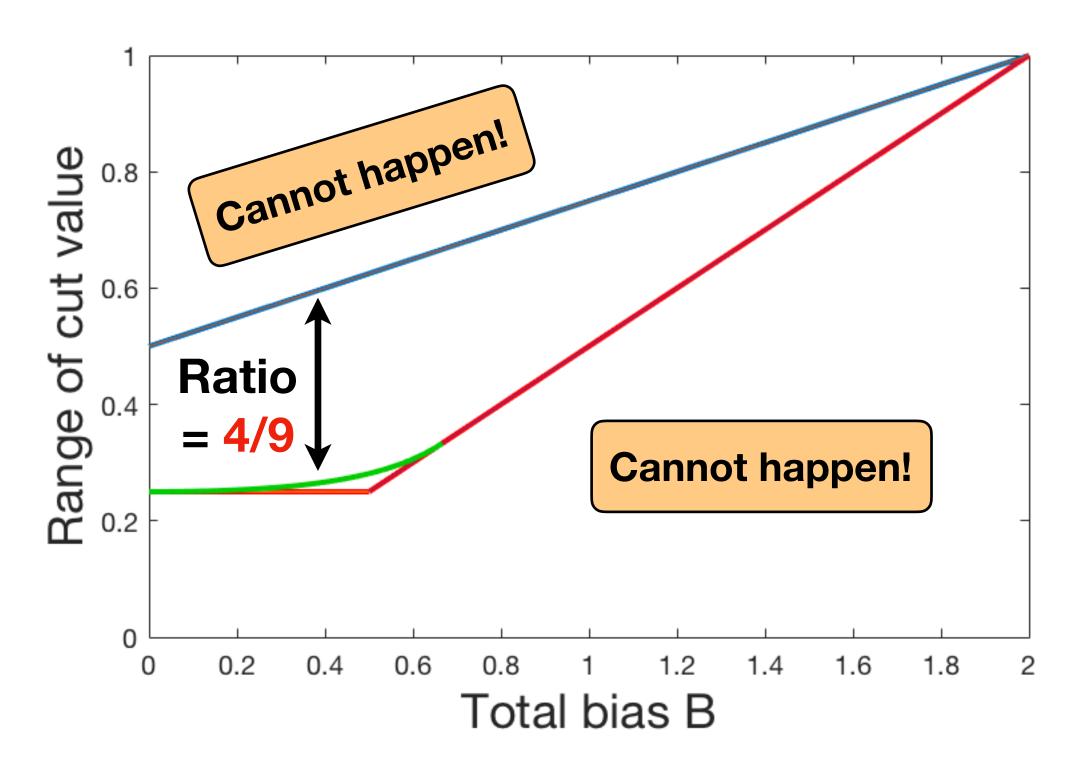
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- Red line: The cut value of greedy cut.
- Green line: Cut value achieved by random sampling with bias.
- Streaming algorithm: Estimate B and output max {green line, red line}.



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- Red line: The cut value of greedy cut.
- Green line: Cut value achieved by random sampling with bias.
- Streaming algorithm: Estimate *B* and output max {green line, red line}.
- Ratio: When B = 2/5, the ratio is 4/9.

Λ	Previous	Reference
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Λ	α_{Λ}	Previous	Reference
2XOR	$\frac{1}{2}$	$\frac{1}{2}$	Trivial

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20R	$\frac{\sqrt{2}}{2}$	$\left[rac{1}{2},1 ight]$	Biased sampling

• It turns out that the optimal approx. ratio of all the boolean 2CSP can be achieved by local random sampling analysis.

Λ	α_{Λ}	Previous	Reference
2XOR	$\frac{1}{2}$	$rac{1}{2}$	Trivial
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See our paper for more details!

Hardness

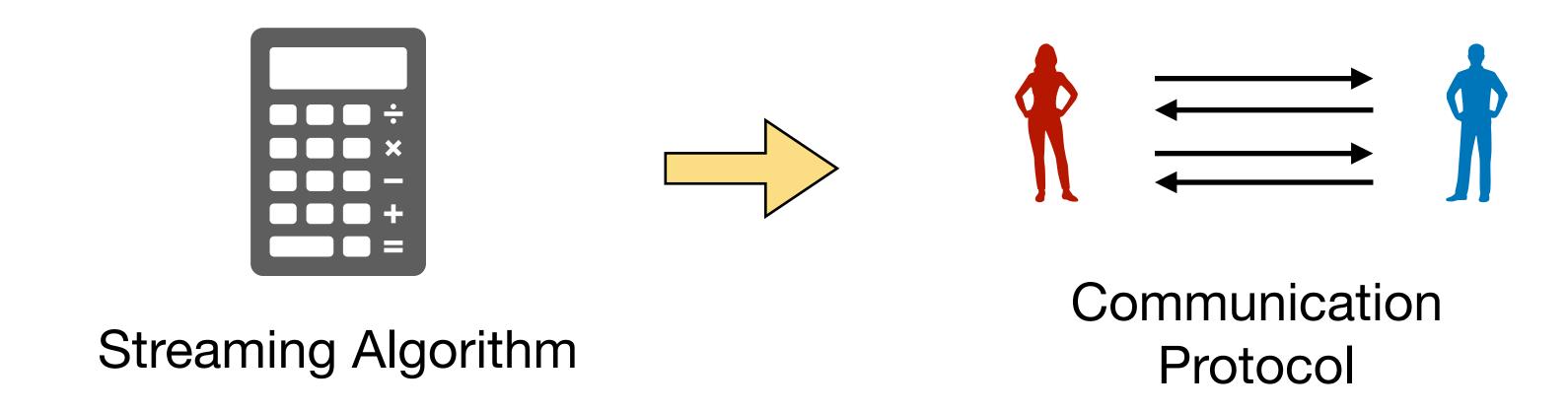
Hardness

Find Instances Matching Random Sampling's Bounds

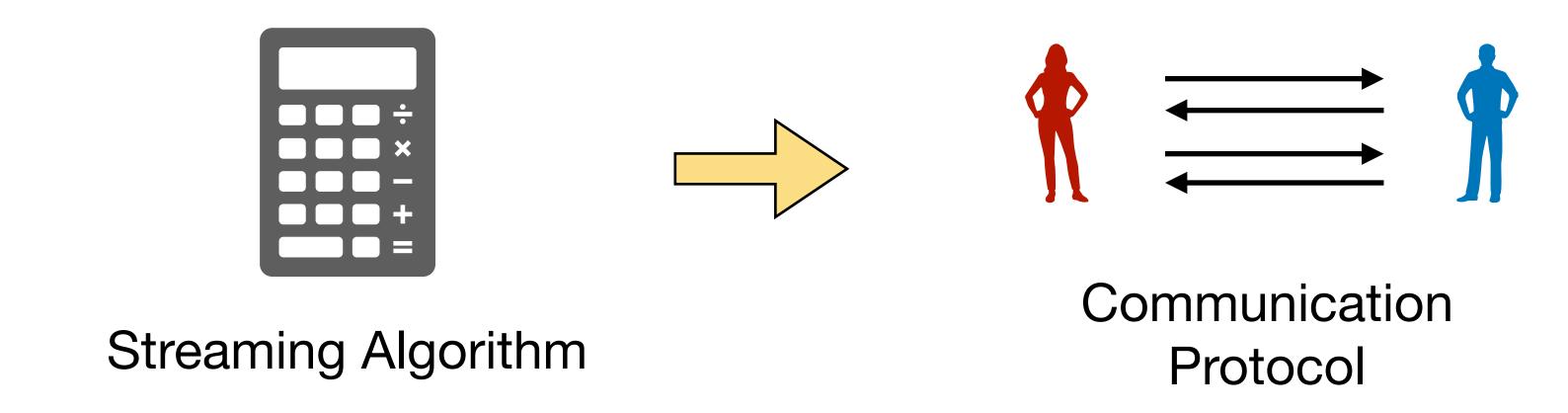
Unconditional lower bounds from communication games.

- Unconditional lower bounds from communication games.
- High-level idea:

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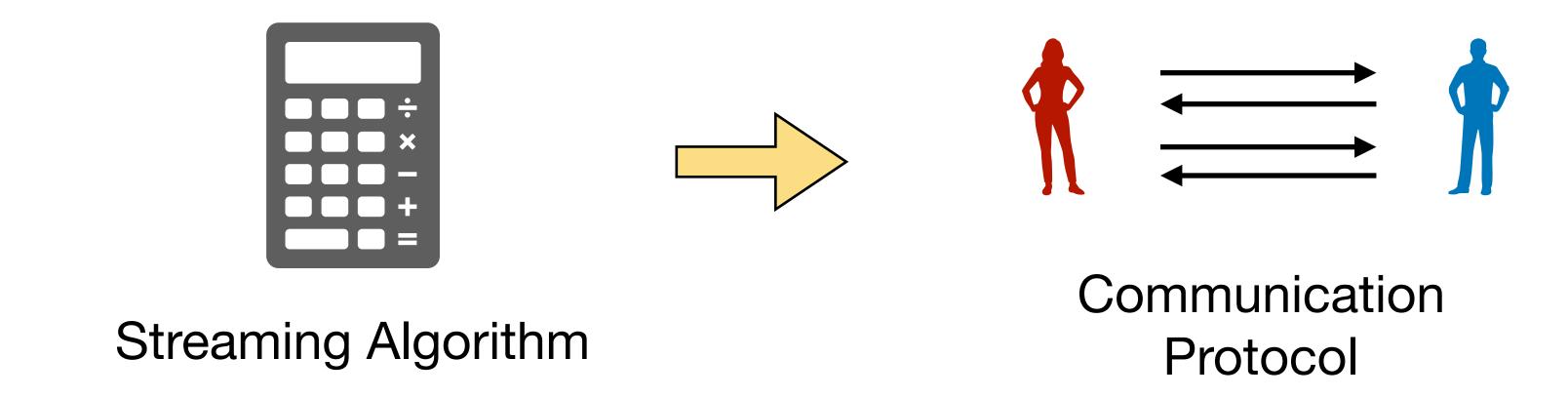


- Unconditional lower bounds from communication games.
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• **Usage**: Alice and Bob insert some inputs to the streaming algorithm and send the "*configuration*" as the message.

- Unconditional lower bounds from communication games.
- High-level idea:



- **Usage**: Alice and Bob insert some inputs to the streaming algorithm and send the "*configuration*" as the message.
- Space complexity of streaming algorithm >= communication complexity.

Distributional Boolean Hidden Partition (DBHP) Problem

Distributional Boolean Hidden Partition (DBHP) Problem

• Used by [Kapralov-Khanna-Sudan-15] in proving hardness of Max-Cut.

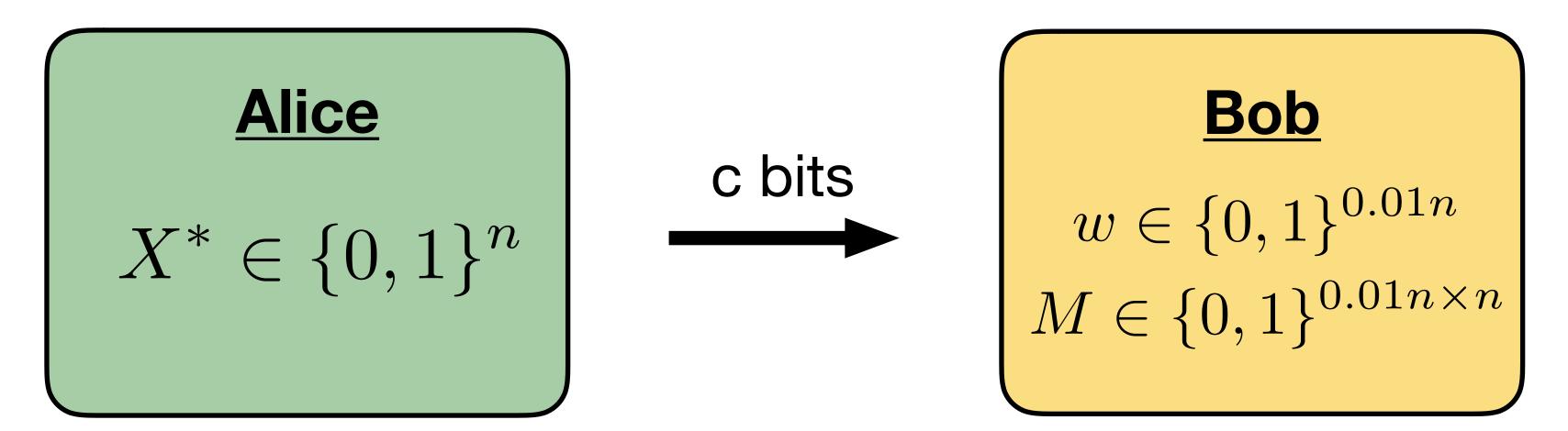
Distributional Boolean Hidden Partition (DBHP) Problem

Used by [Kapralov-Khanna-Sudan-15] in proving hardness of Max-Cut.

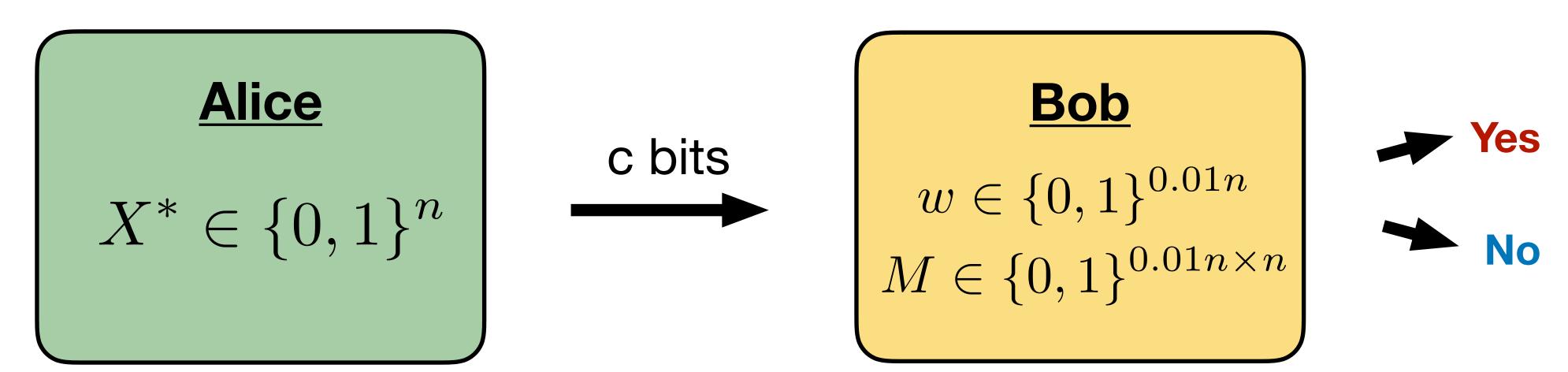
Alice

$$X^* \in \{0, 1\}^n$$

* Each row of M contains exactly two 1s.

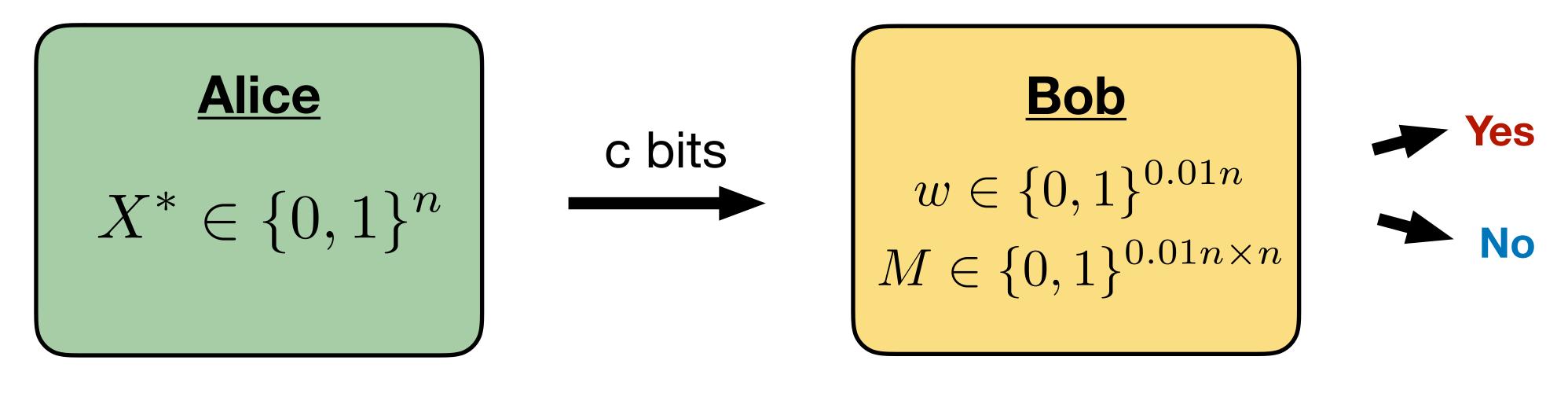


* Each row of M contains exactly two 1s.



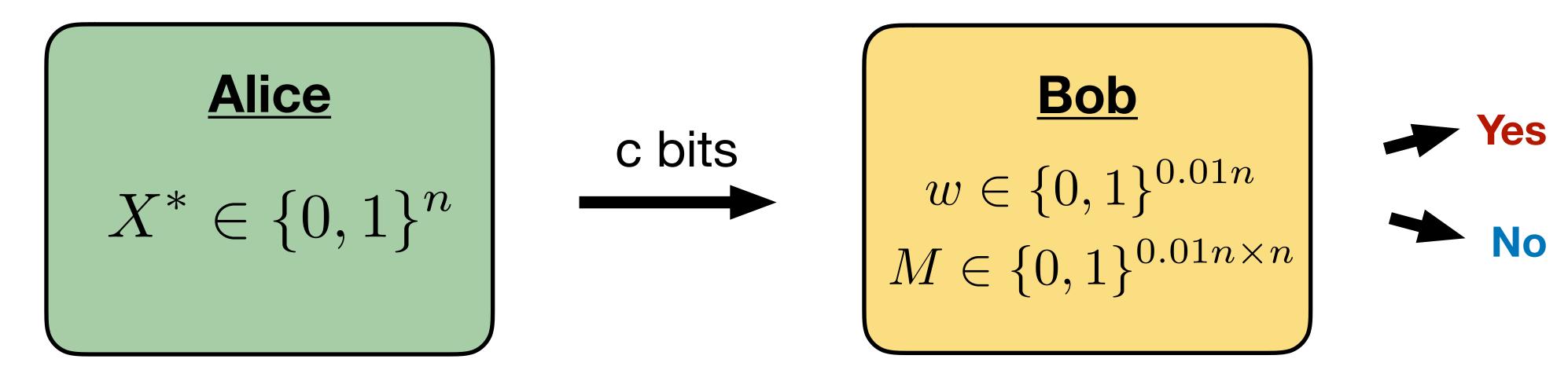
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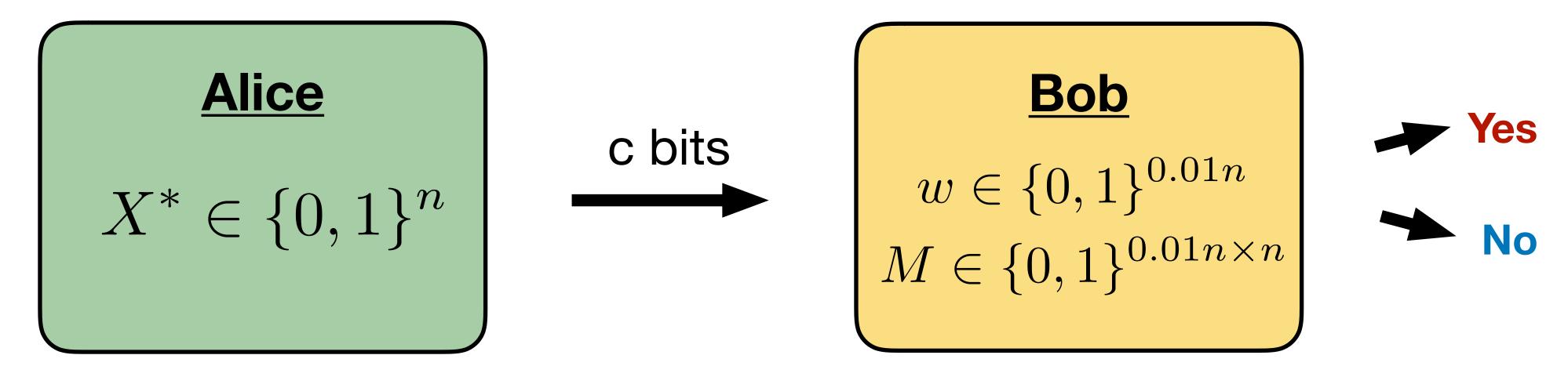
• Yes distribution: Exists $X^* \in \{0,1\}^n$ such that $w_t = M_t X^*, \ \forall t \in [T]$.

* Each row of M contains exactly two 1s.



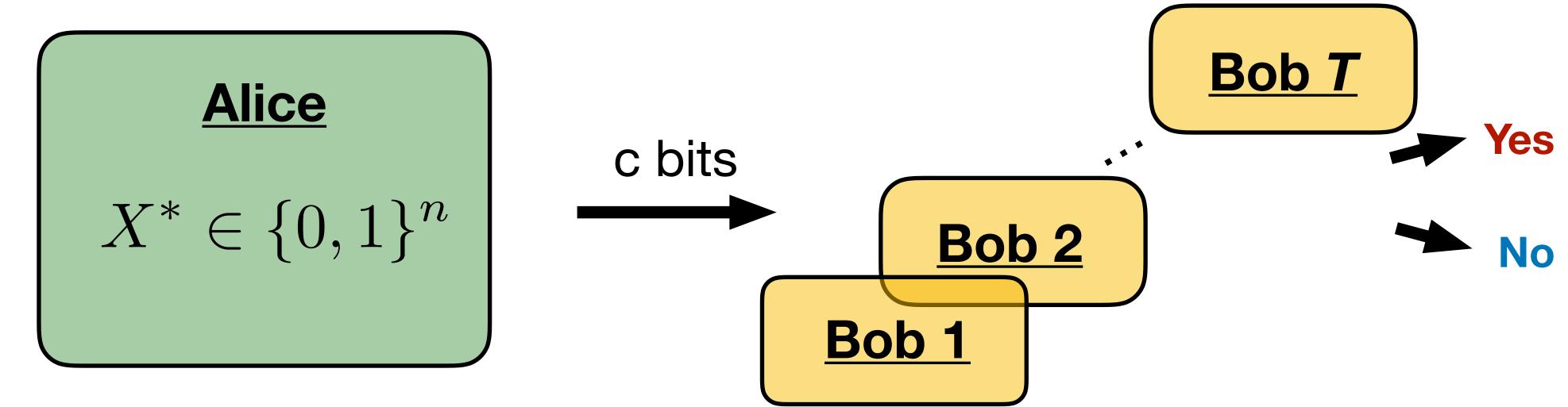
- Yes distribution: Exists $X^* \in \{0,1\}^n$ such that $w_t = M_t X^*, \ \forall t \in [T]$.
- No distribution: w_t is uniformly random $\forall t \in [T]$.

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- [Gavinsky et al. 07] showed that DBHP needs $\Omega(\sqrt{n})$ communication.

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- Yes distribution: Exists $X^* \in \{0,1\}^n$ such that $w_t = M_t X^*, \ \forall t \in [T]$.
- No distribution: w_t is uniformly random $\forall t \in [T]$.
- [Gavinsky et al. 07] showed that DBHP needs $\Omega(\sqrt{n})$ communication.
- Parallel repetition: constant many copies to increase the number of edges.

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}$$
 $M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$

$$egin{aligned} \mathbf{Bob} \ \mathbf{1} \ w_1 &= \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^ op \ M_1 &= \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \ 1 & 0 & 0 & 1 & 0 \ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \end{aligned} \qquad egin{aligned} \mathbf{W}_2 &= \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^ op \ M_2 &= \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \ 0 & 1 & 0 & 1 & 0 \ 1 & 0 & 0 & 0 & 1 \end{bmatrix} \end{aligned}$$

Bob 3

$$egin{aligned} egin{aligned} egi$$

$$egin{aligned} egin{aligned} egi$$

$$w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}$$
 $M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix}$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

- Can you see this is a Yes case or No case?
 - Yes distribution: Exists $X^* \in \{0,1\}^n$ such that $w_t = M_t X^*, \ \forall t \in [T]$.
 - No distribution: w_t is uniformly random $\forall t \in |T|$.

$$w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}$$
 $M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix}$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

- Can you see this is a Yes case or No case?
- The answer is **Yes**. The hidden partition is $X^* = \begin{bmatrix} 0 & 0 & 1 & 0 & 1 \end{bmatrix}^{\top}$.

Bob 1 Bob 2 Bob 3 $w_1 = [1 \ 0 \ 0]^\top$ $w_2 = [1 \ 0 \ 1]^\top$ $w_3 = [1 \ 1 \ 0]^\top$

$$M_1 = egin{bmatrix} 0 & 1 & 1 & 0 & 0 \ 1 & 0 & 0 & 1 & 0 \ 1 & 0 & 1 & 0 & 1 \end{bmatrix} egin{bmatrix} M_2 = egin{bmatrix} 0 & 0 & 1 & 1 & 0 \ 0 & 1 & 0 & 1 & 0 \ 1 & 0 & 0 & 0 & 1 \end{bmatrix} egin{bmatrix} M_3 = egin{bmatrix} 0 & 1 & 0 & 0 & 1 \ 0 & 0 & 0 & 1 & 1 \ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

$$M_2 = egin{bmatrix} 0 & 0 & 1 & 1 & 0 \ 0 & 1 & 0 & 1 & 0 \ 1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

- Can you see this is a Yes case or No case?
- The answer is **Yes**. The hidden partition is $X^* = \begin{bmatrix} 0 & 0 & 1 & 0 & 1 \end{bmatrix}^{\top}$.
- Can you see the connection to Max-CUT?

<u>Bob 1</u>

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top}$$
 $M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$

Bob 2

$$w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{ op}$$
 $M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \ 0 & 1 & 0 & 1 & 0 \ 1 & 0 & 0 & 0 & 1 \end{bmatrix}$

<u>Bob 1</u>

Bob 2

$$w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{ op}$$
 $M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix}$

$$w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}}$$
 $M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$

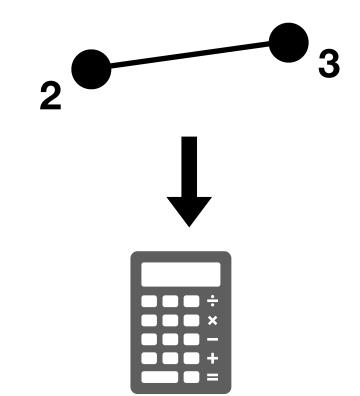


<u>Bob 1</u>

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top}$$
 $M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$

Bob 2

$$w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top}$$
 $M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$



<u>Bob 1</u>

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top}$$
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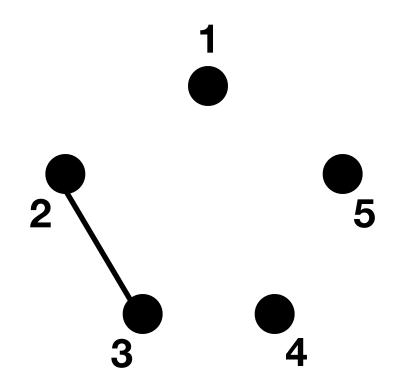
Bob 2

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top} \qquad w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\top} \qquad w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top}$$

$$M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \qquad M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix} \qquad M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{array}{c} \mathbf{BOD 3} \\ w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \end{bmatrix}^{\top} \\ \mathbf{V}_3 = \begin{bmatrix}$$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$





<u>Bob 1</u>

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top}$$

$$M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$$

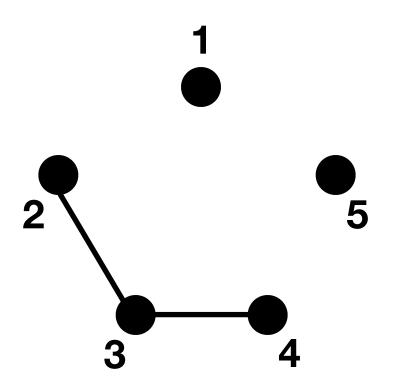
Bob 2

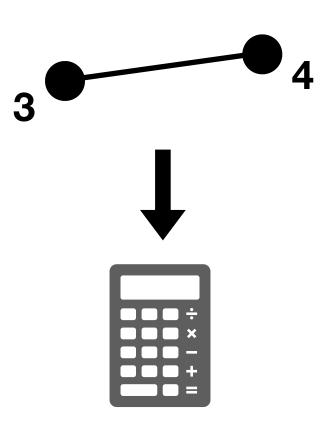
$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top} \qquad w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\top} \qquad w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top}$$

$$M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \qquad M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix} \qquad M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

$$w_3 = [1 \ 1 \ 0]^{\top}$$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$





Bob 1

Bob 2

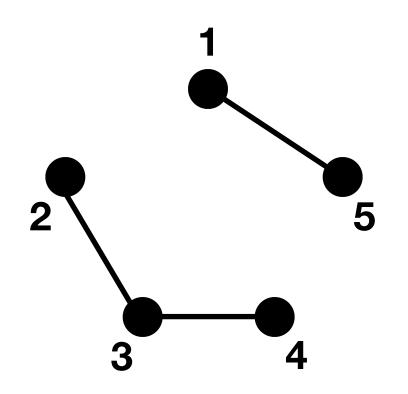
 $w_2 = [1 \ 0 \ 1]^{\top}$

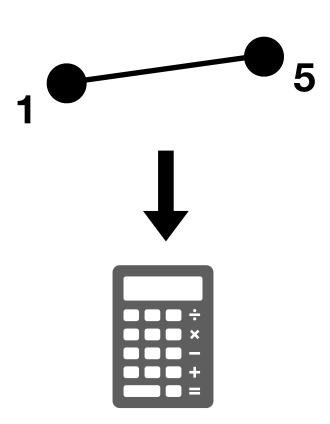
$$M_2 = egin{bmatrix} 0 & 0 & 1 & 1 & 0 \ 0 & 1 & 0 & 1 & 0 \ 1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Bob 3

$$w_3 = [1 \ 1 \ 0]^{\top}$$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$





Bob 1

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{ op}$$
 $M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$

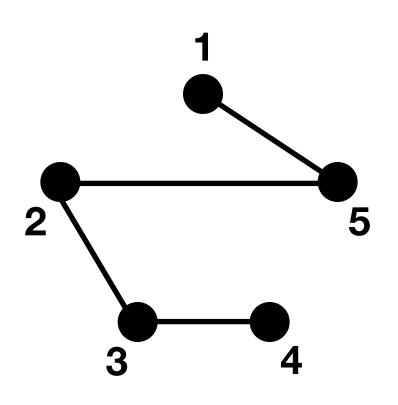
Bob 2

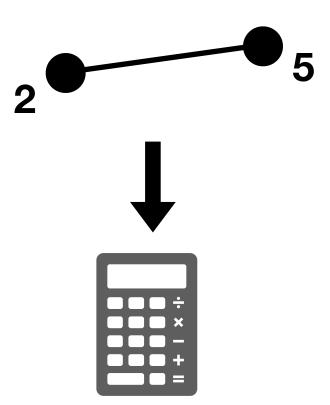
$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top} \qquad w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\top} \qquad w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top}$$

$$M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \qquad M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix} \qquad M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

$$w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top}$$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$



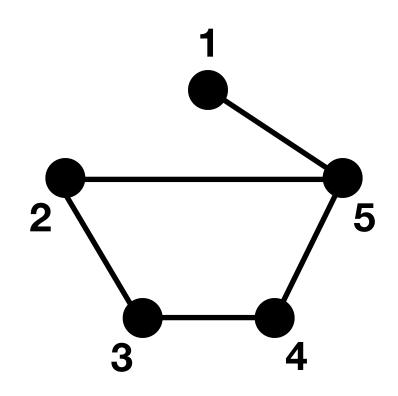


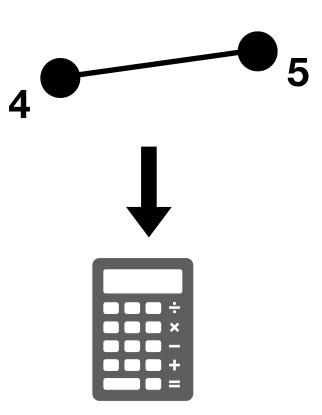
Bob 1

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top}$$
 $M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$

Bob 2

$$w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\mathsf{T}}$$
 $M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix}$





<u>Bob 1</u>

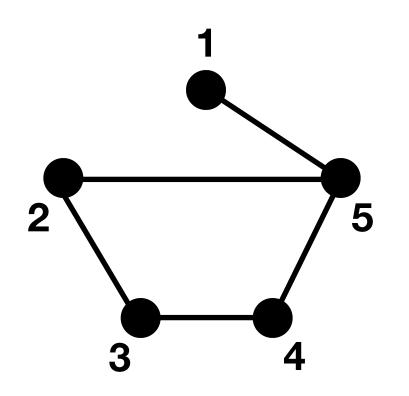
$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top}$$

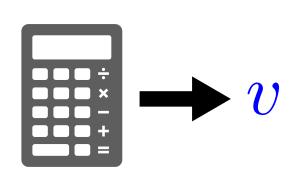
$$M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$$

Bob 2

$$w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}}$$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$





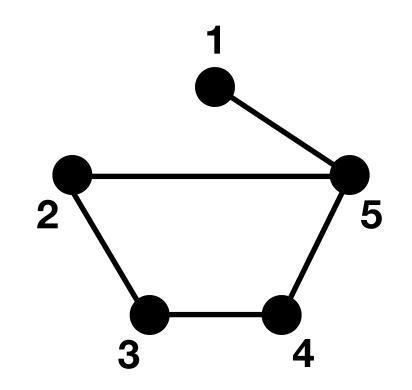
<u>Bob 1</u>

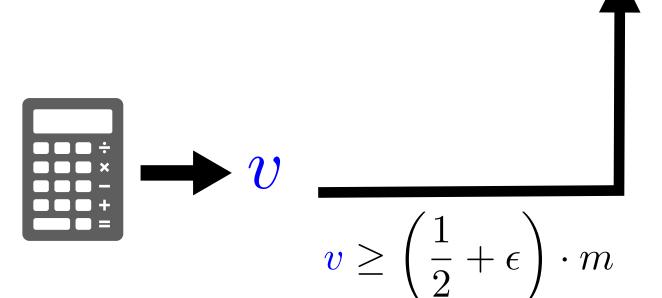
Bob 2

$$w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\top}$$
 $M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix}$

$$w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top}$$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$





Bob 1

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top}$$

$$M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$$

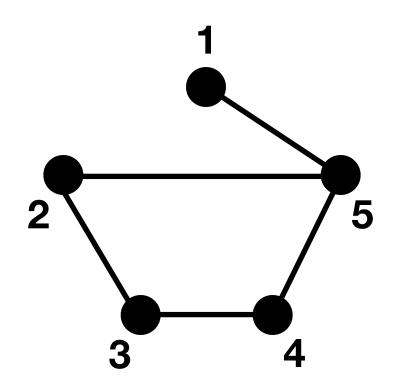
Bob 2

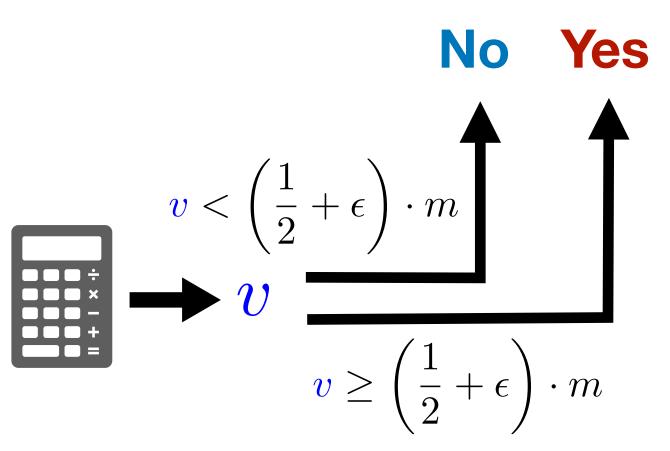
$$w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\top}$$

$$M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top} \qquad w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\top} \qquad w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top}$$

$$M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \qquad M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix} \qquad M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$





Bob 1

$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$$
 $M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$

Bob 2

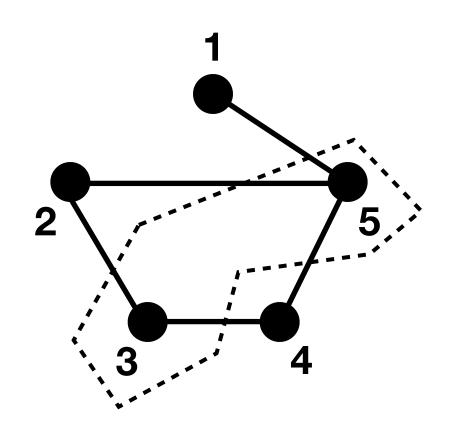
$$w_1 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^{\top} \qquad w_2 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\top} \qquad w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top}$$

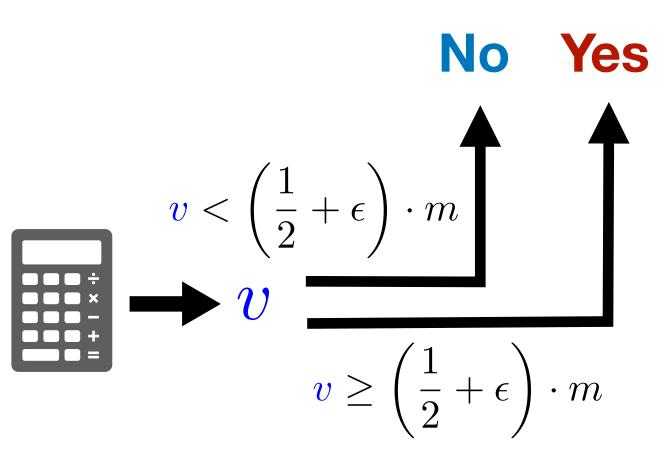
$$M_1 = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \qquad M_2 = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix} \qquad M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Bob 3

$$w_3 = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\top}$$

$$M_3 = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$





• Think of each row of M_t as a random edge and w_t picks the edges.

• Think of each row of M_t as a random edge and w_t picks the edges.

Yes Distribution No Distribution

• Think of each row of M_t as a random edge and w_t picks the edges.

Yes Distribution

 $\exists X^* \text{ s.t. } w_t = M_t X^*$

No Distribution

• Think of each row of M_t as a random edge and w_t picks the edges.

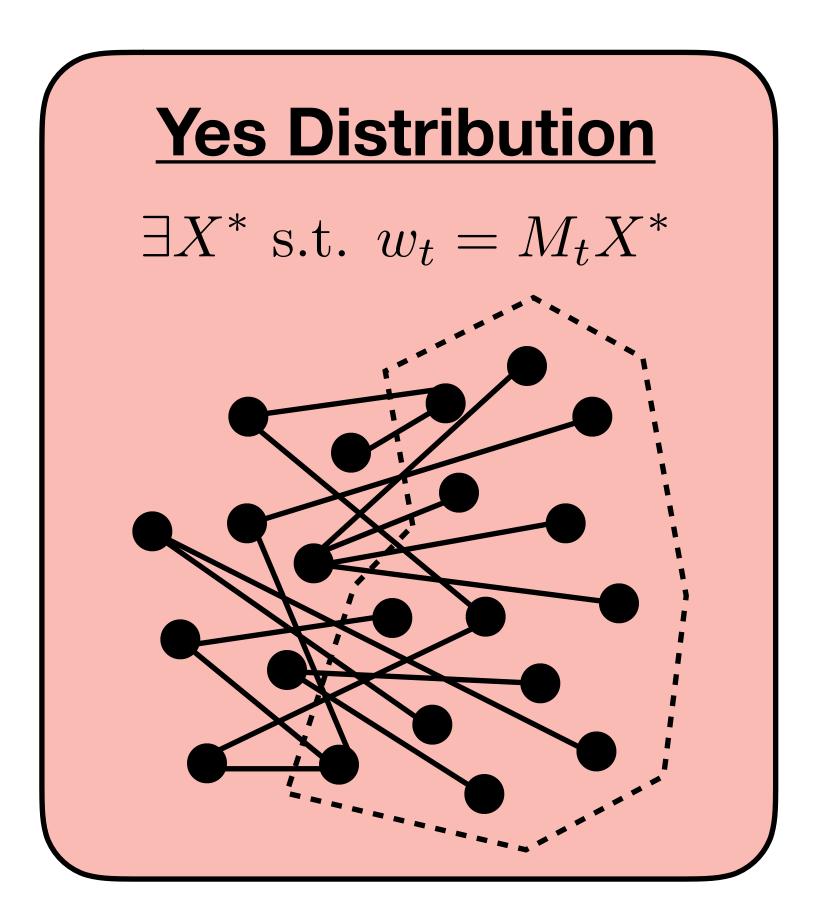
Yes Distribution

 $\exists X^* \text{ s.t. } w_t = M_t X^*$

No Distribution

 w_t is uniformly random

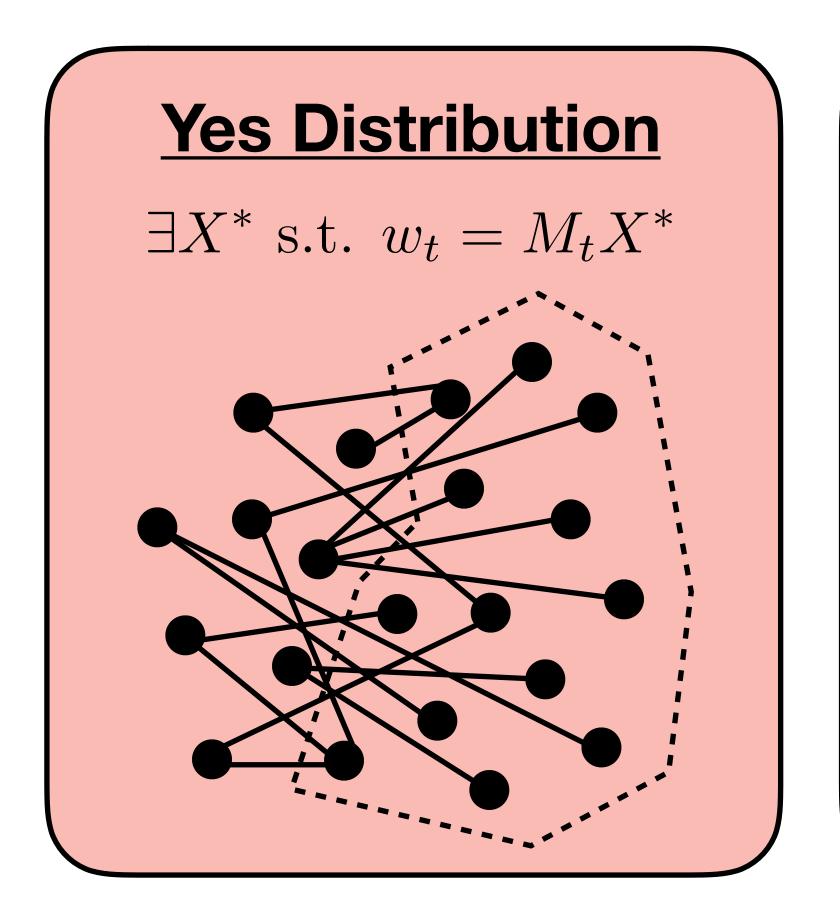
• Think of each row of M_t as a random edge and w_t picks the edges.

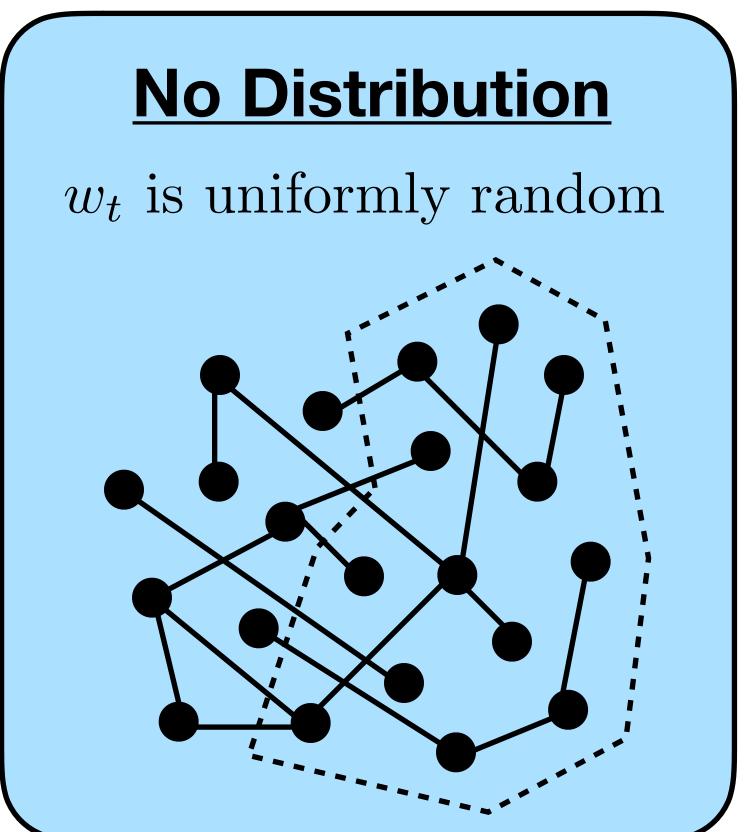


No Distribution

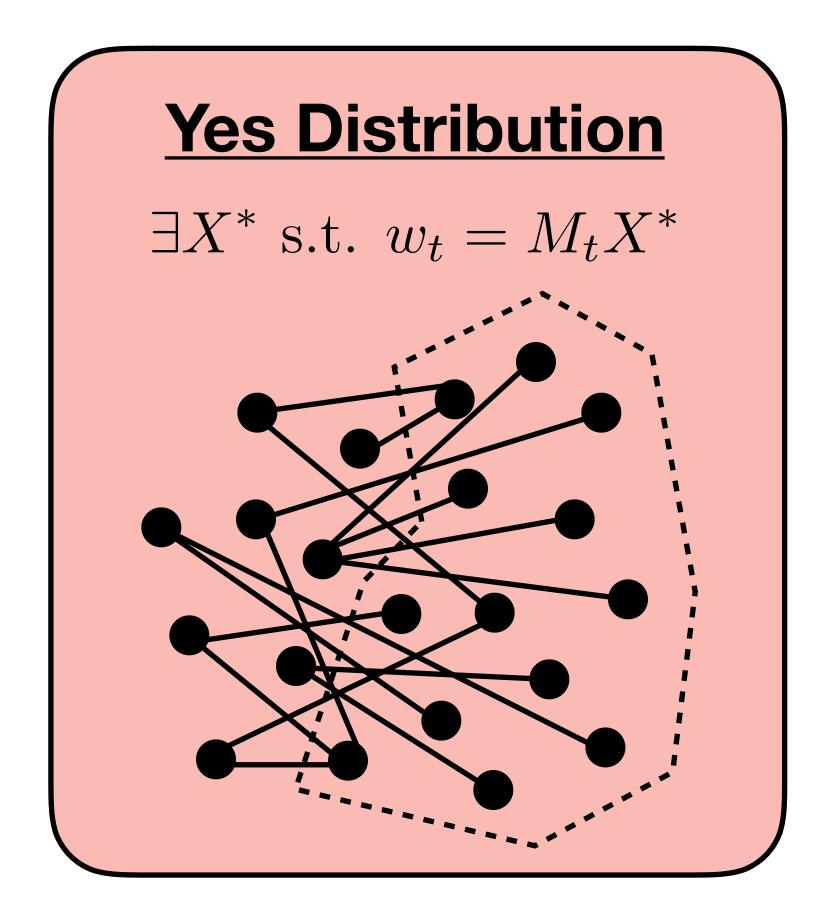
 w_t is uniformly random

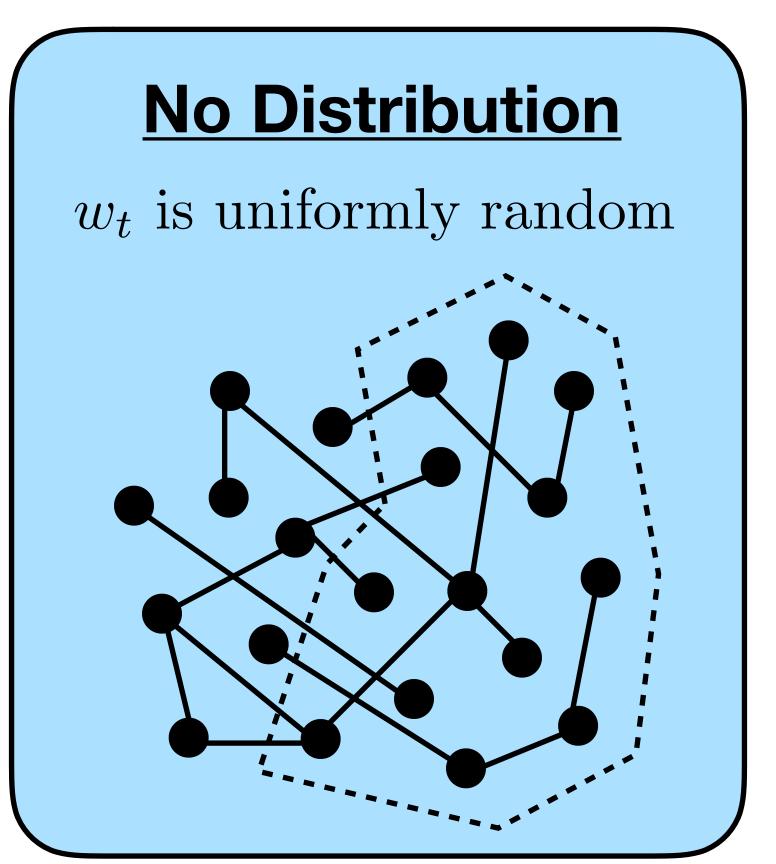
• Think of each row of M_t as a random edge and w_t picks the edges.





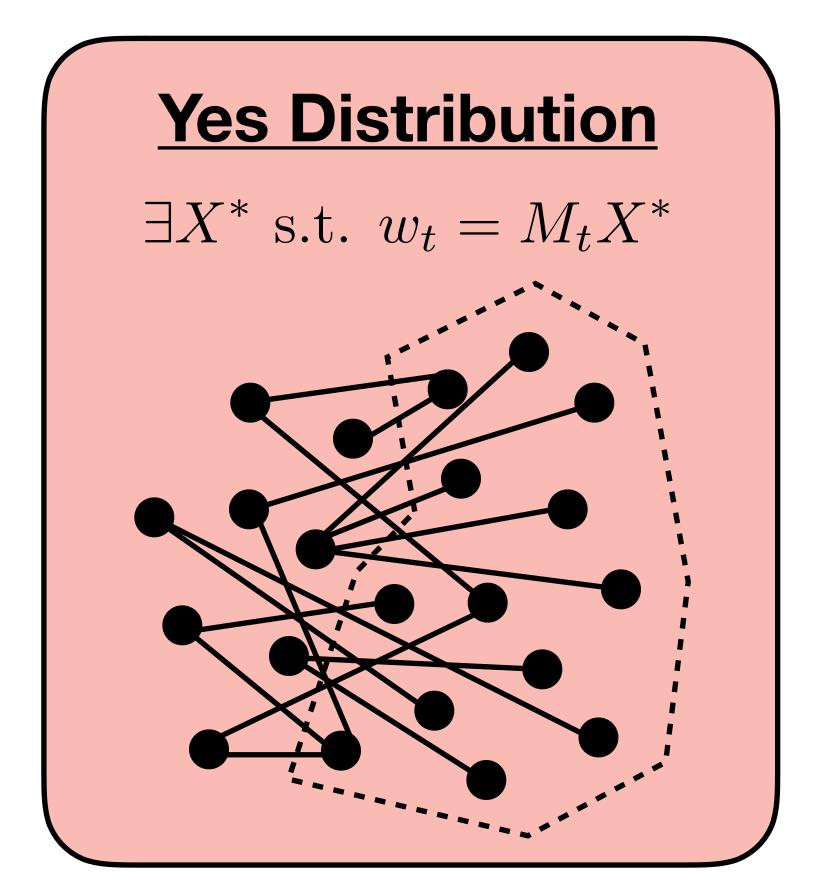
• Think of each row of M_t as a random edge and w_t picks the edges.

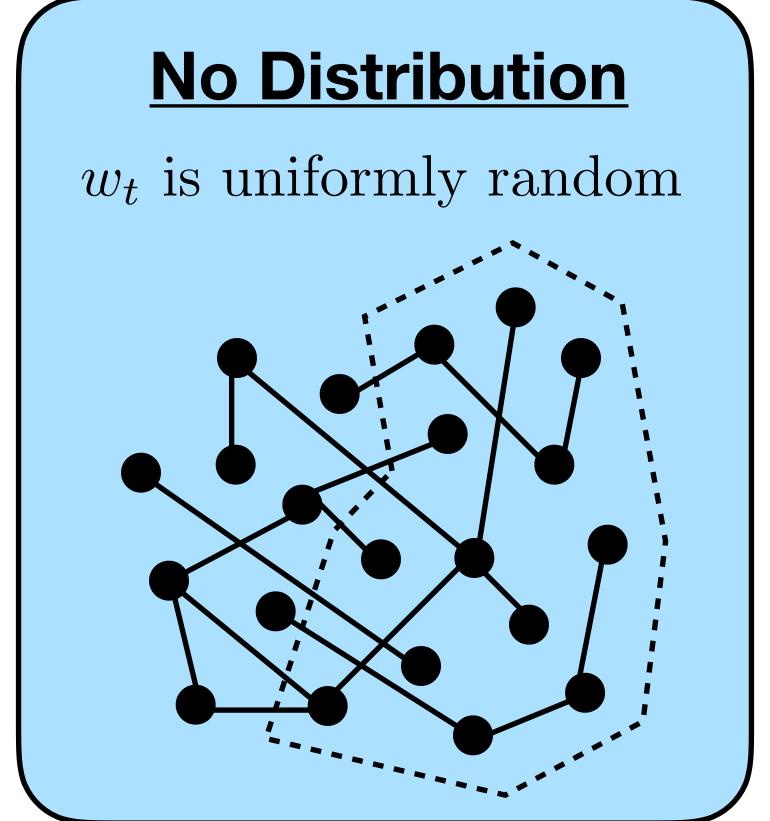




• Each player possesses a subset of the edges.

• Think of each row of M_t as a random edge and w_t picks the edges.

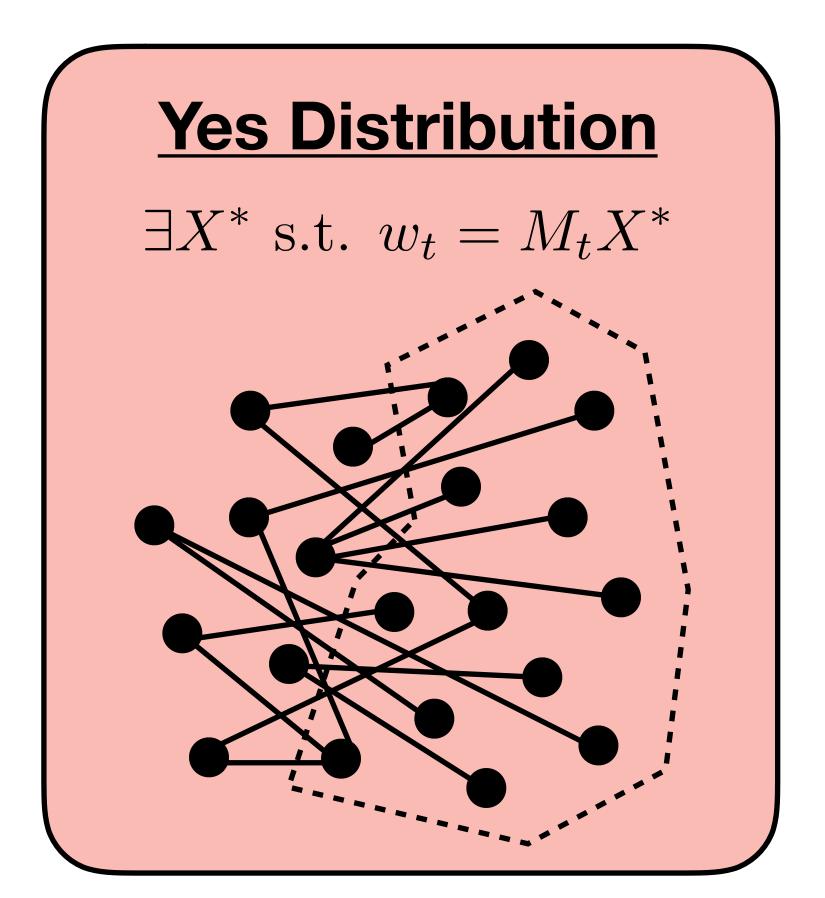


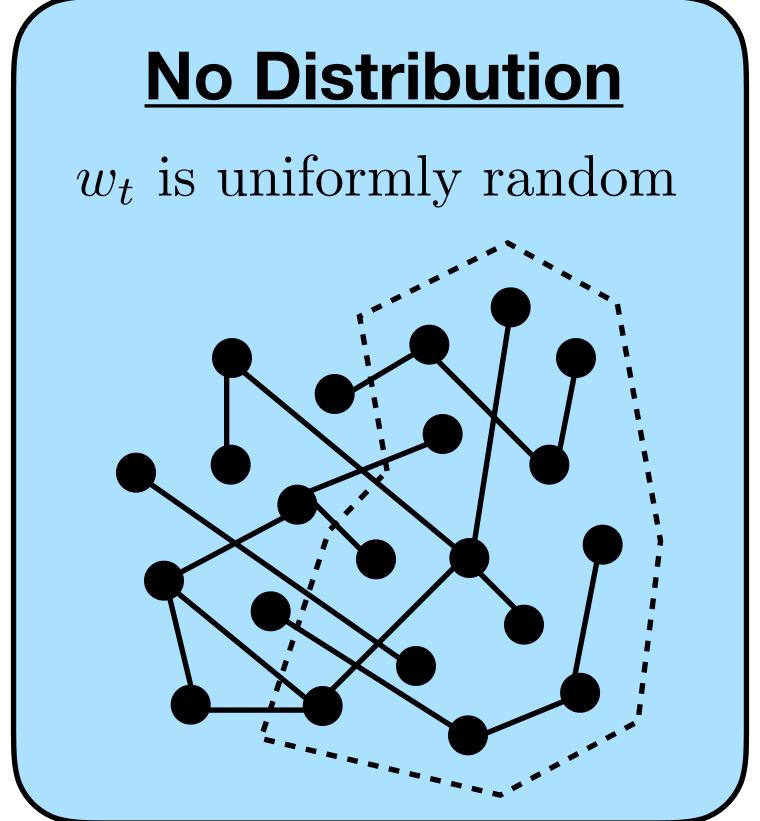


Yes' Distribution

• Each player possesses a subset of the edges.

• Think of each row of M_t as a random edge and w_t picks the edges.



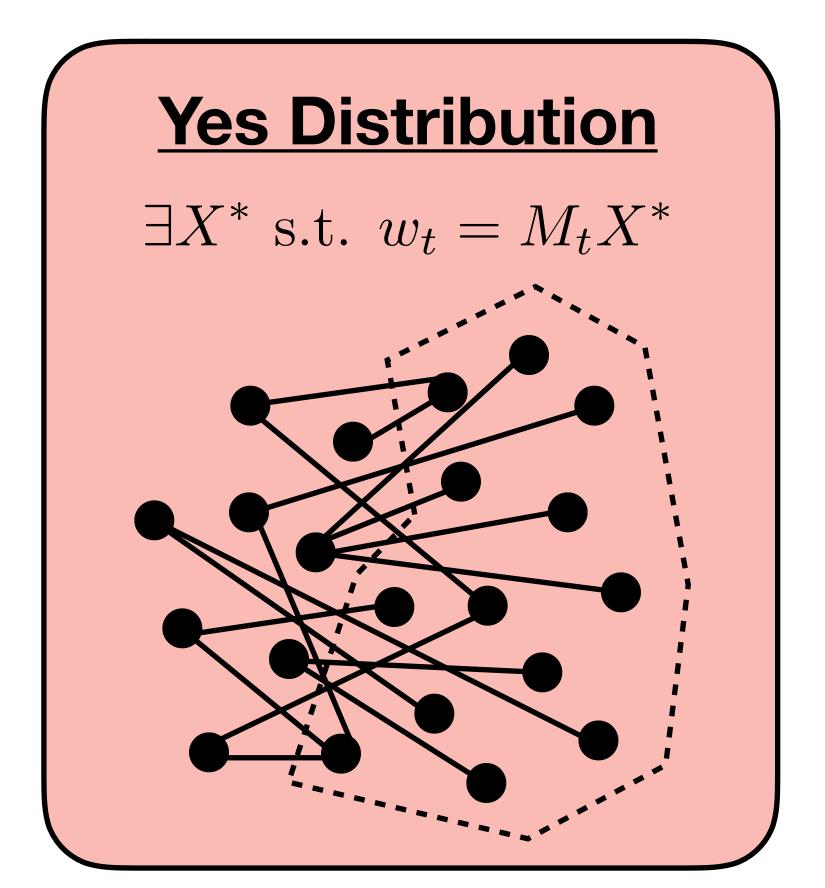


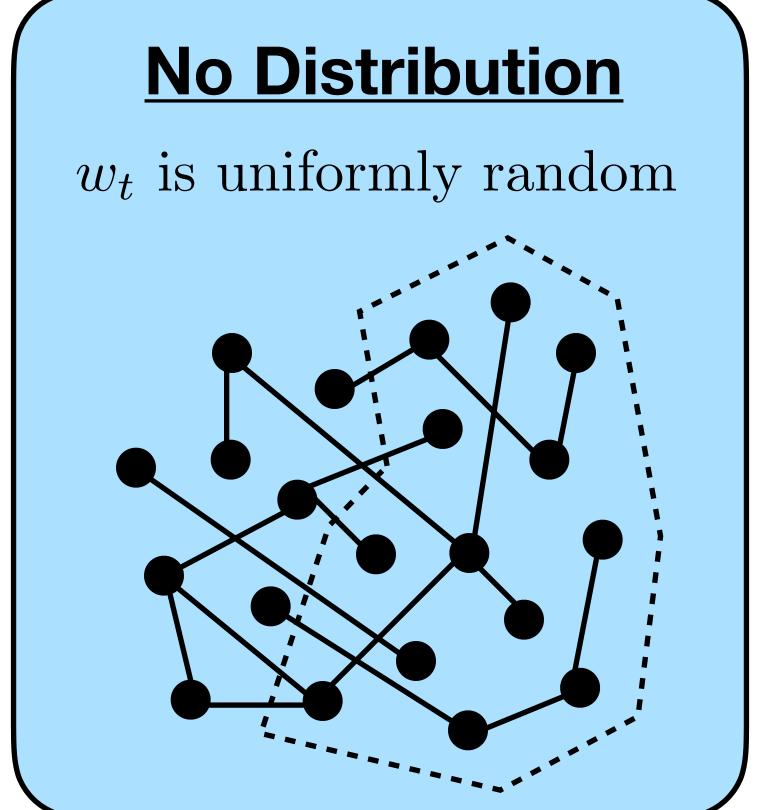
Yes' Distribution

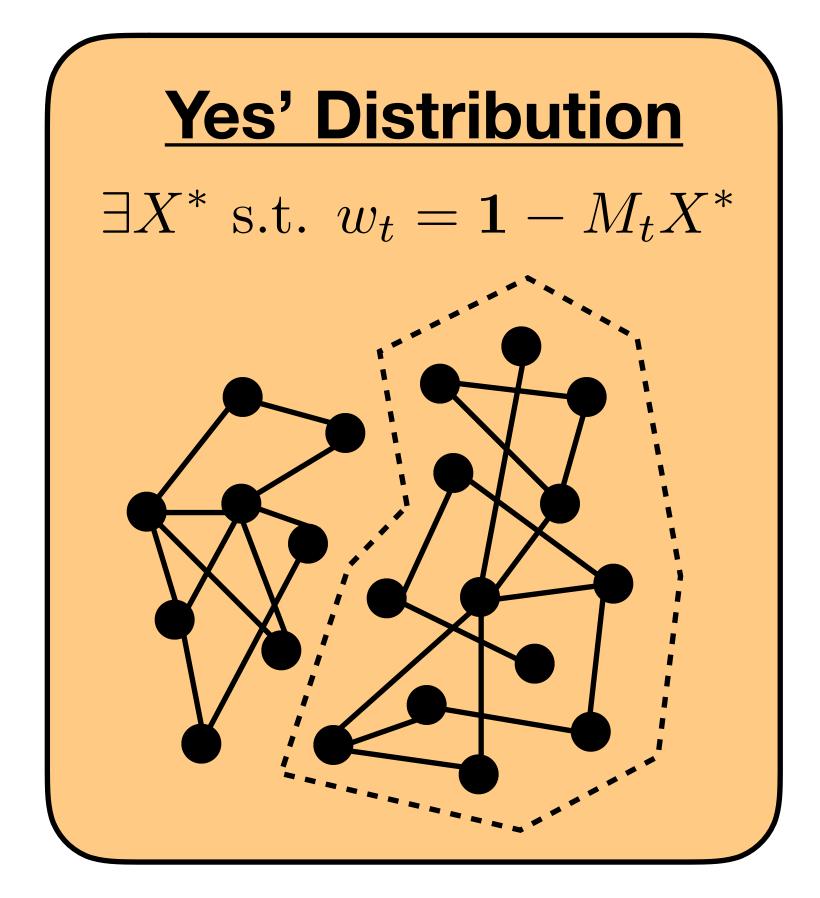
 $\exists X^* \text{ s.t. } w_t = \mathbf{1} - M_t X^*$

• Each player possesses a subset of the edges.

• Think of each row of M_t as a random edge and w_t picks the edges.







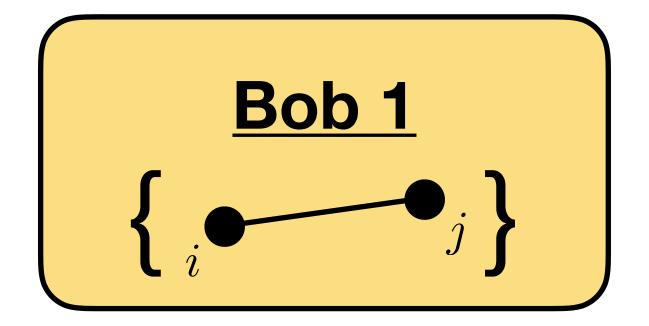
Each player possesses a subset of the edges.

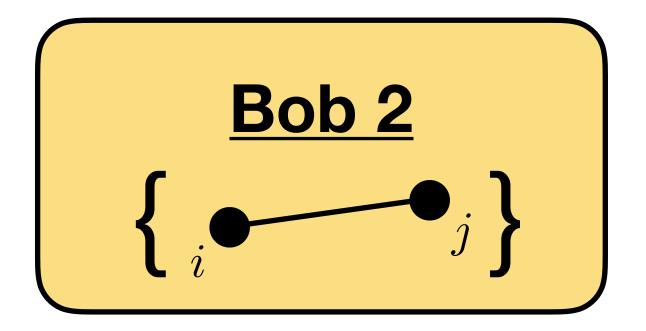
 $\frac{\text{Bob 1}}{w_1 \in \{0, 1\}^{0.01n}}$

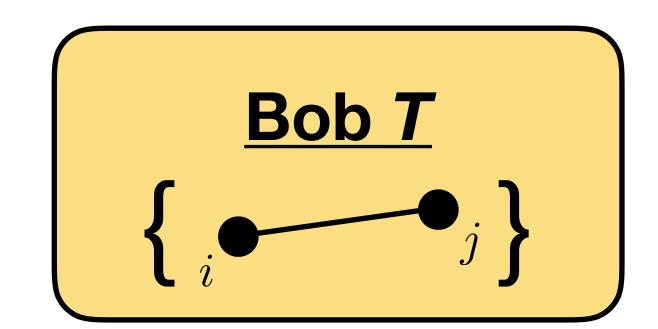
 $\frac{\text{Bob 2}}{w_2 \in \{0, 1\}^{0.01n}}$

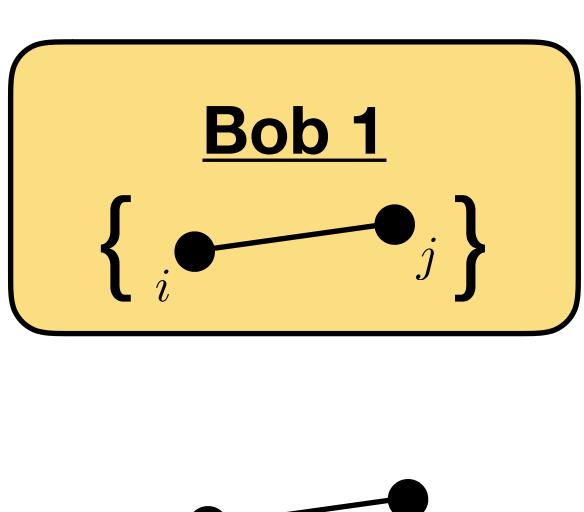
Bob T

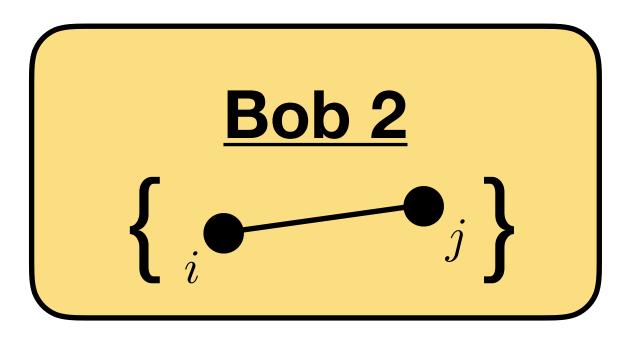
 $w_T \in \{0, 1\}^{0.01n}$

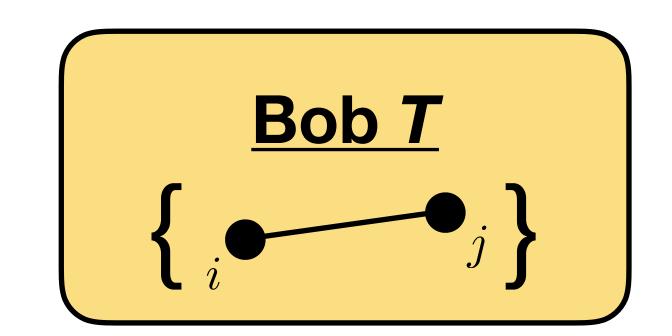


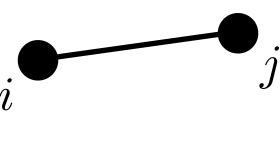


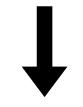




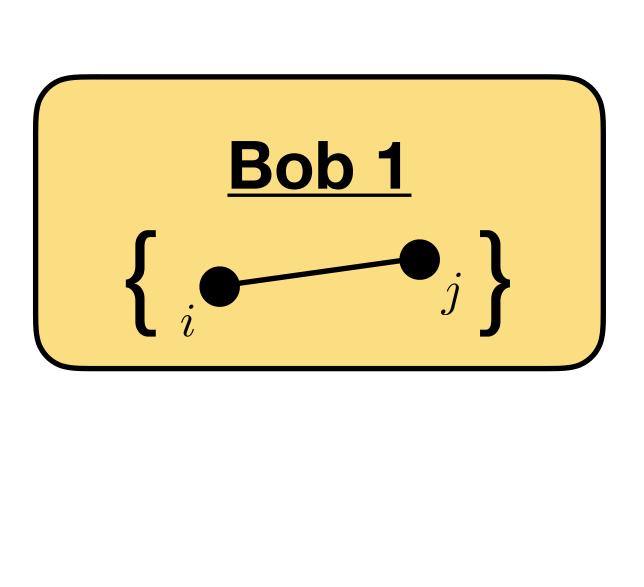


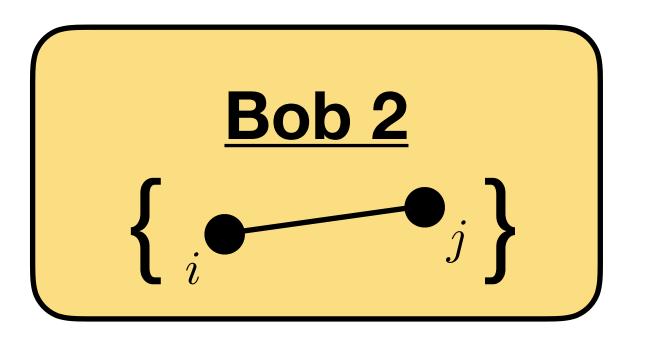


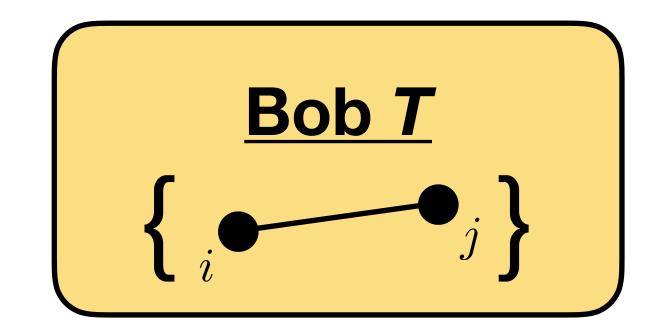


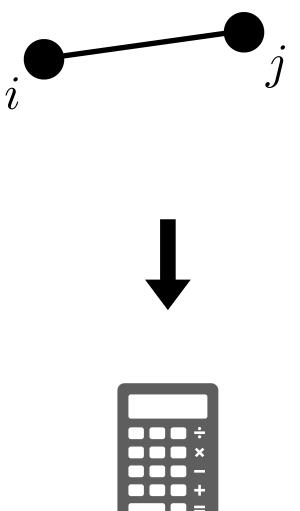


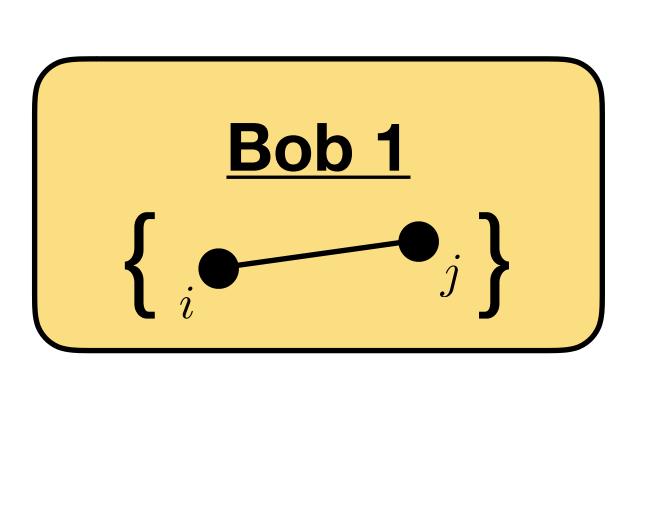


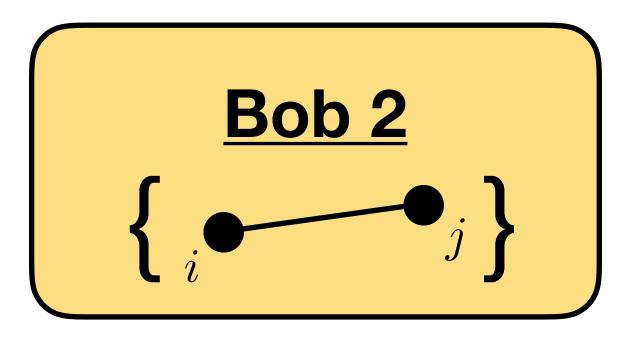


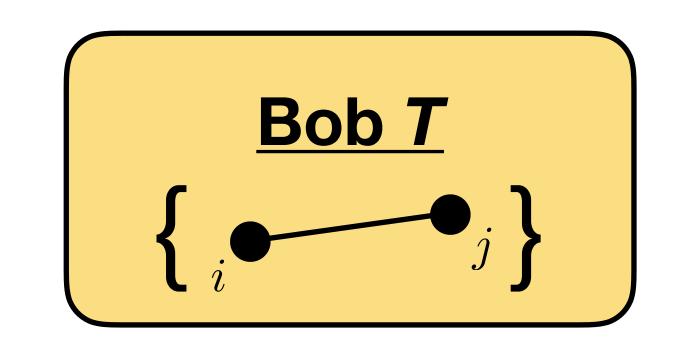


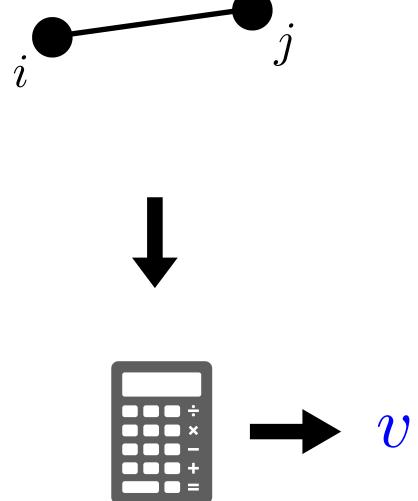


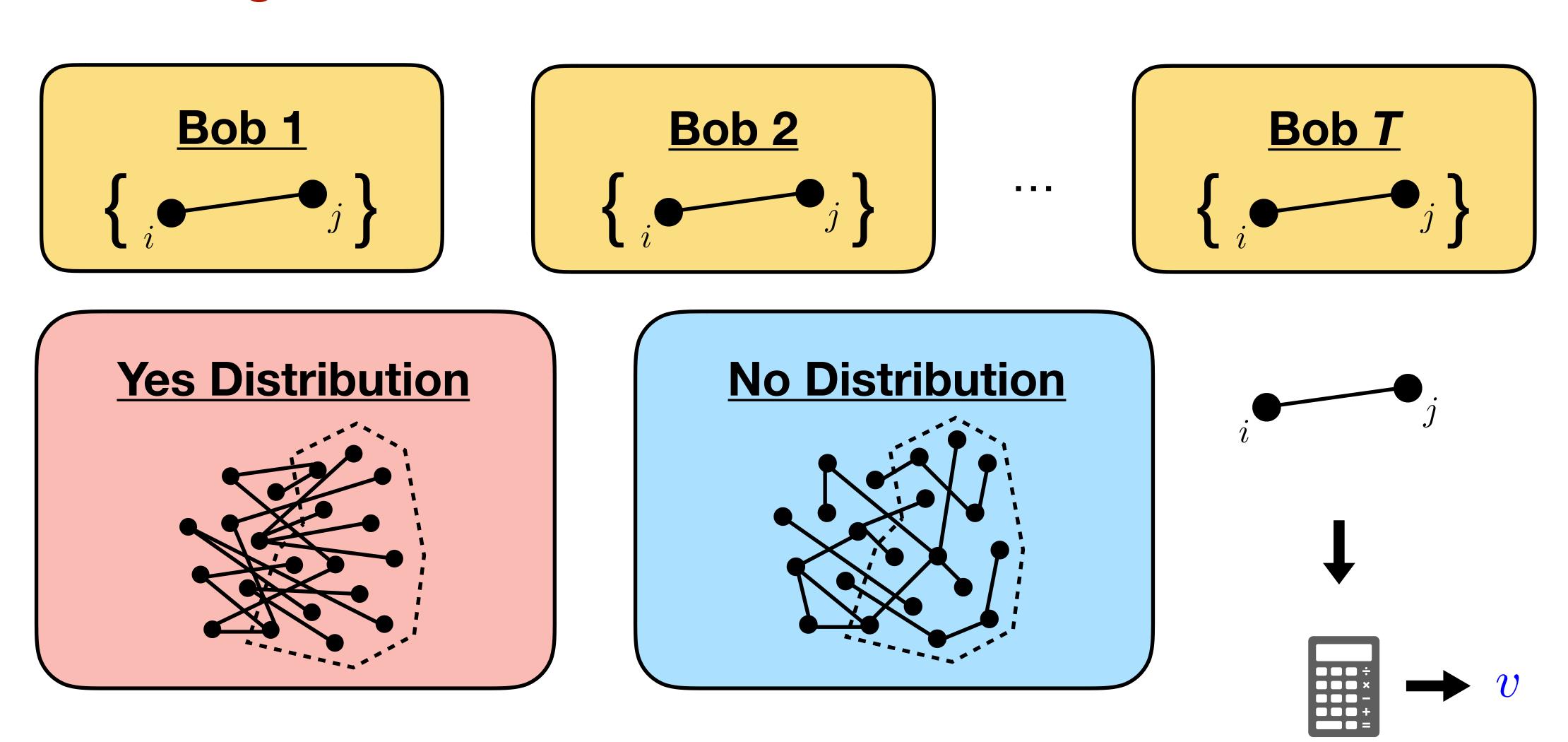


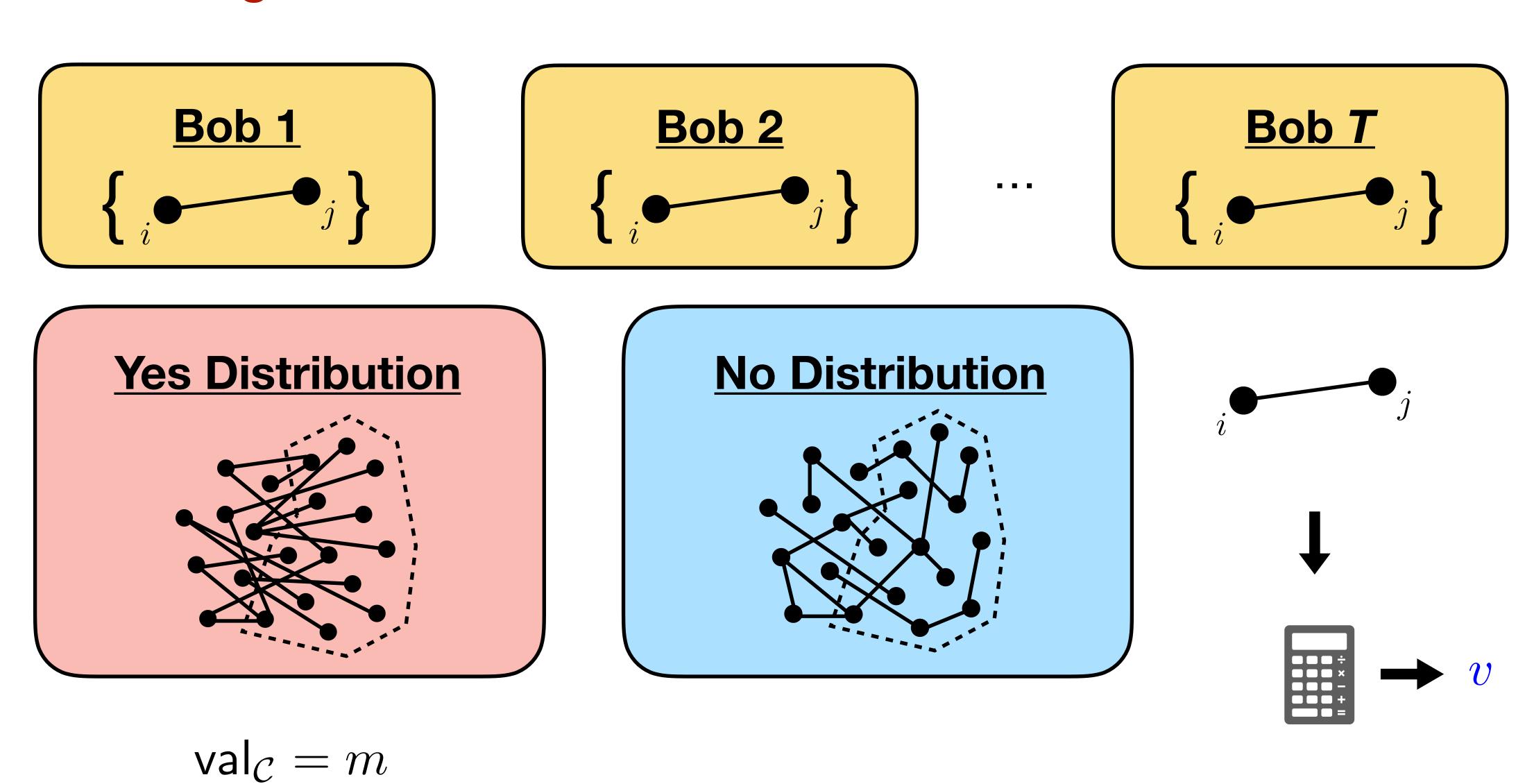


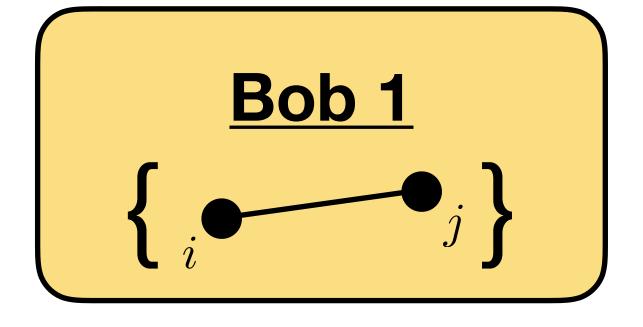


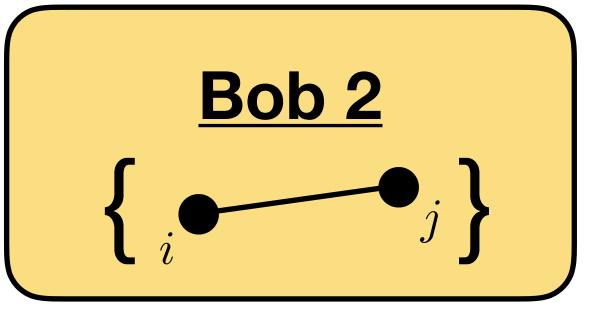


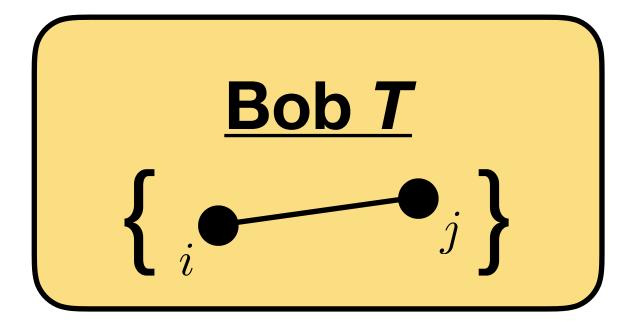


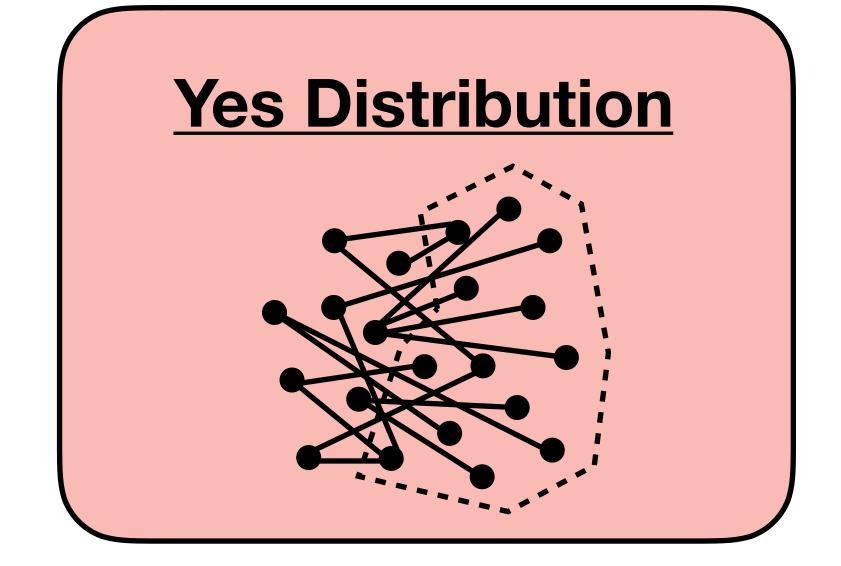




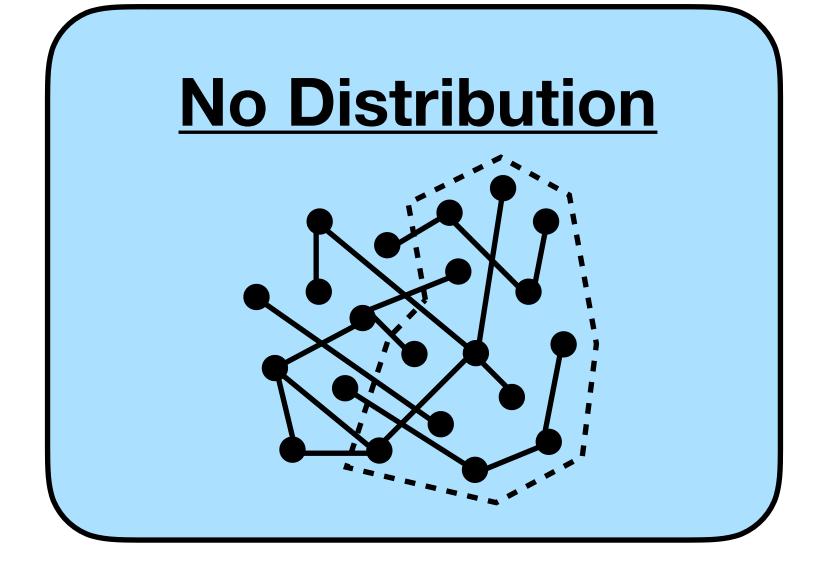




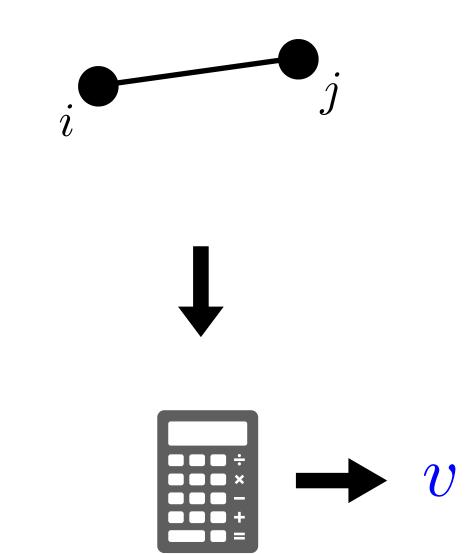


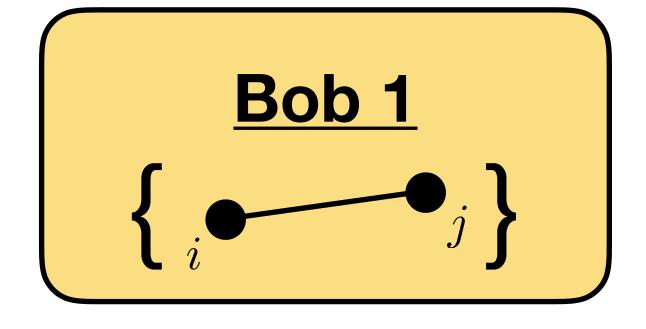


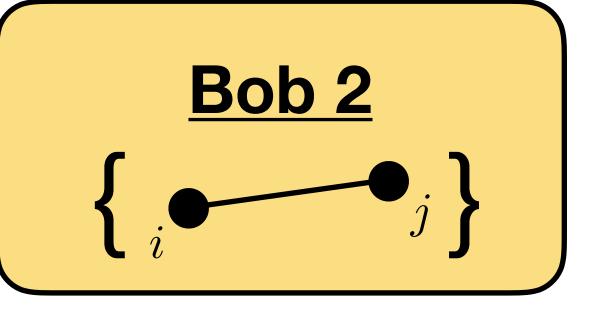
$$\mathsf{val}_\mathcal{C} = m$$

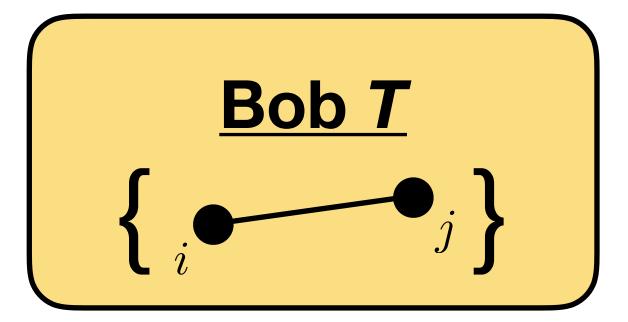


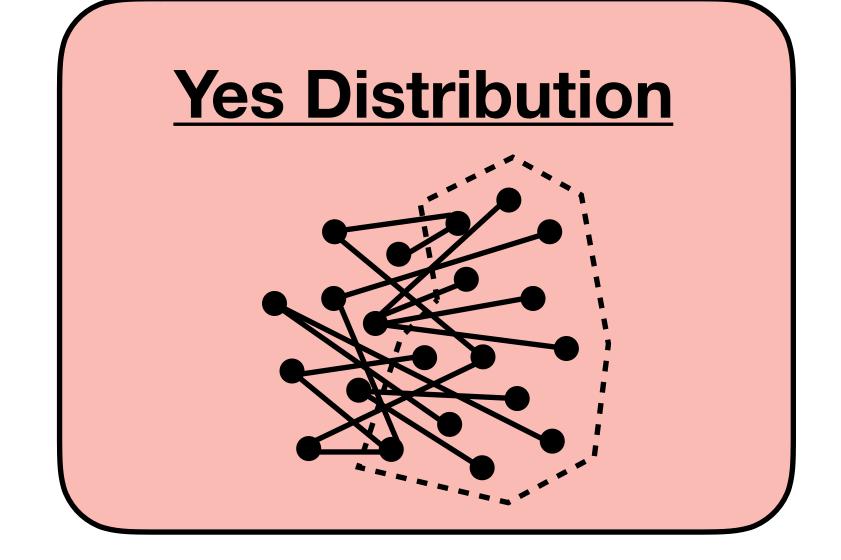
$$\mathsf{val}_{\mathcal{C}} < \left(\frac{1}{2} + o(1)\right) \cdot m$$



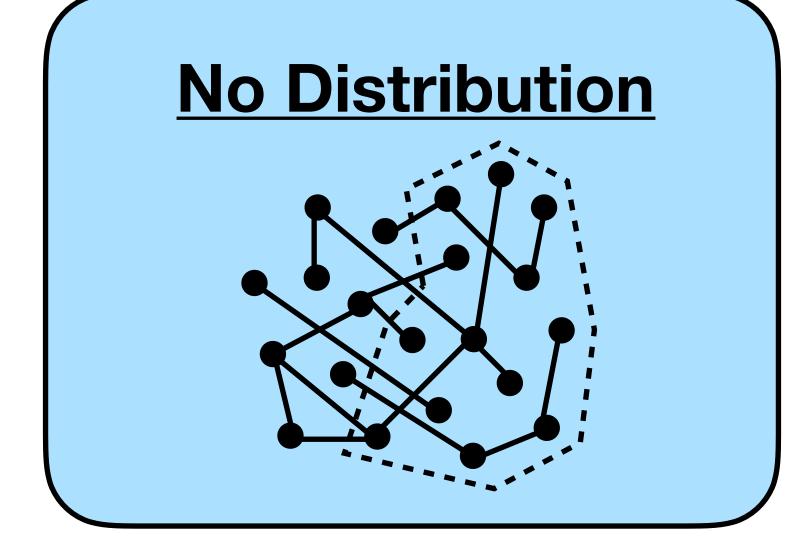




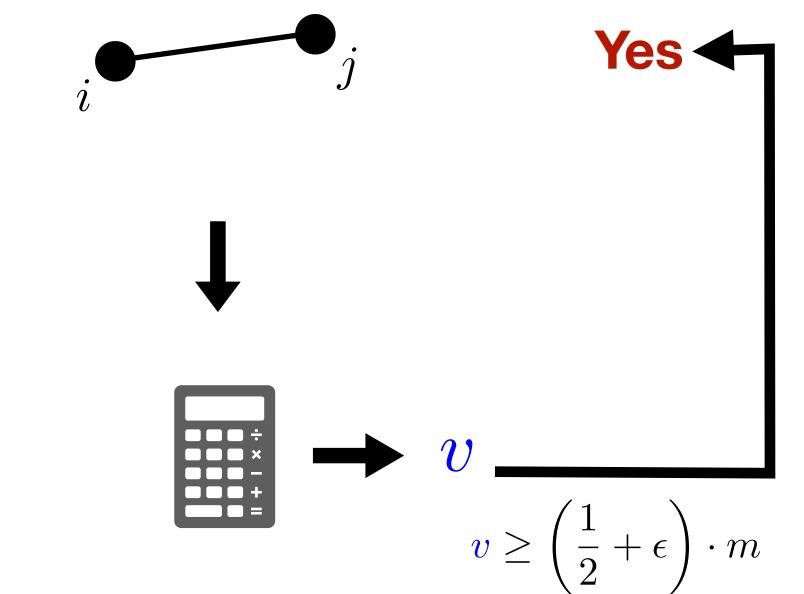


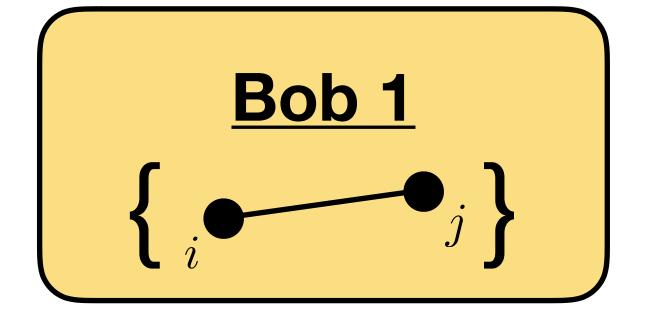


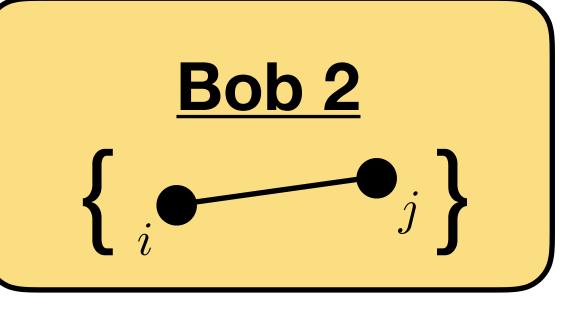
$$\mathsf{val}_\mathcal{C} = m$$

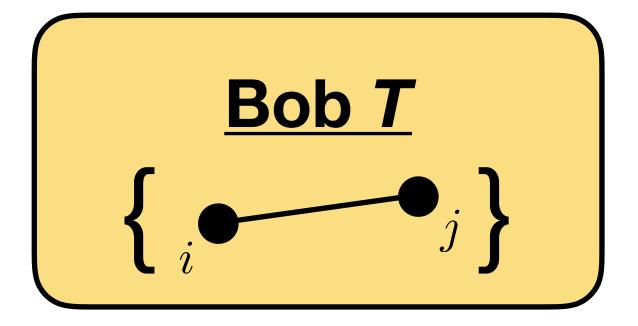


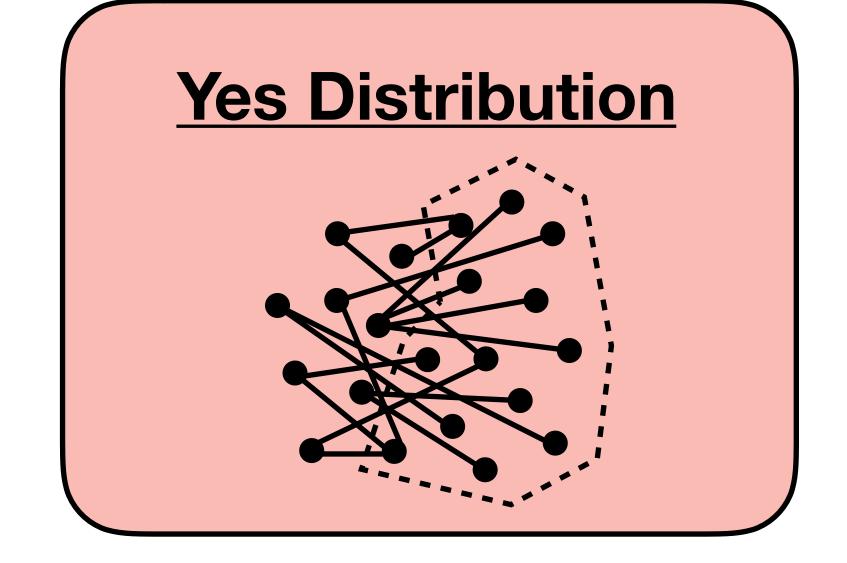
$$\mathsf{val}_{\mathcal{C}} < \left(\frac{1}{2} + o(1)\right) \cdot m$$



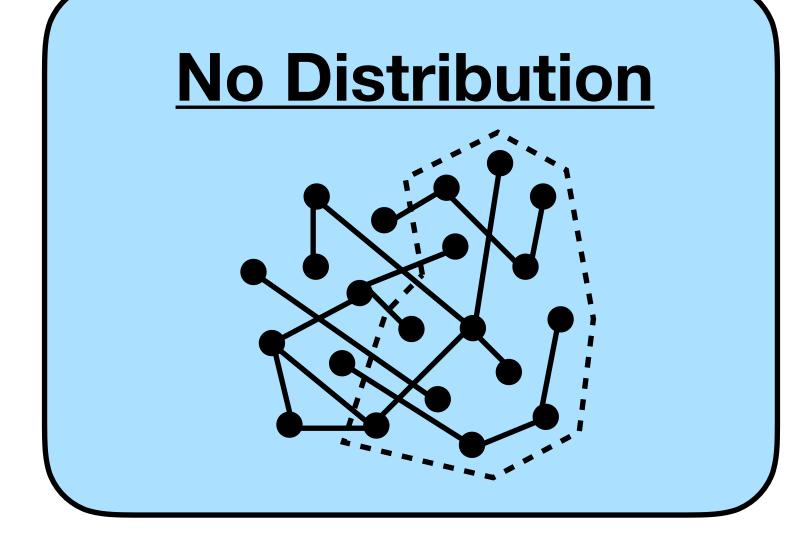




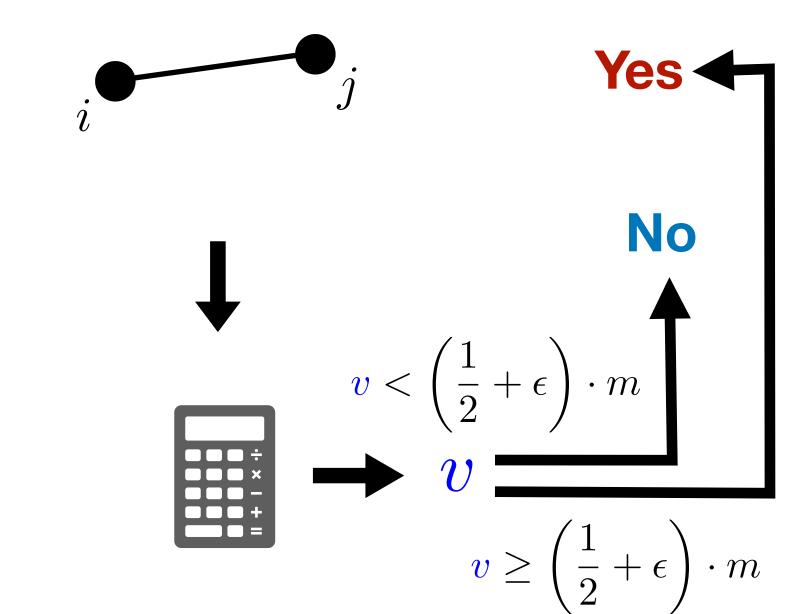




$$\mathsf{val}_\mathcal{C} = m$$

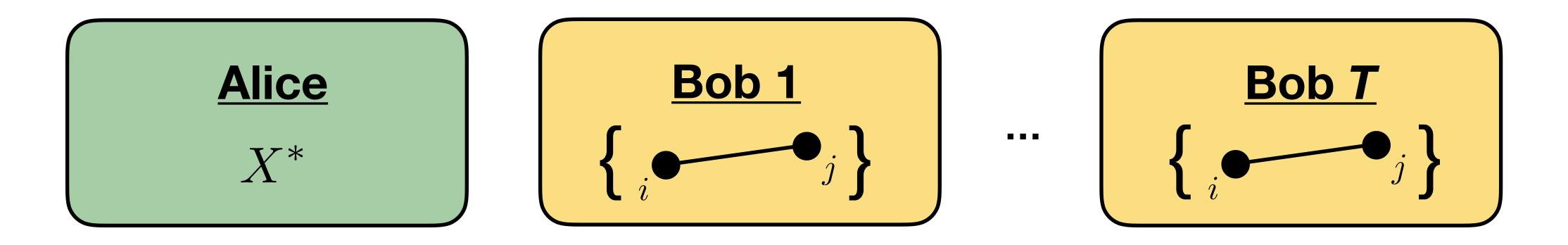


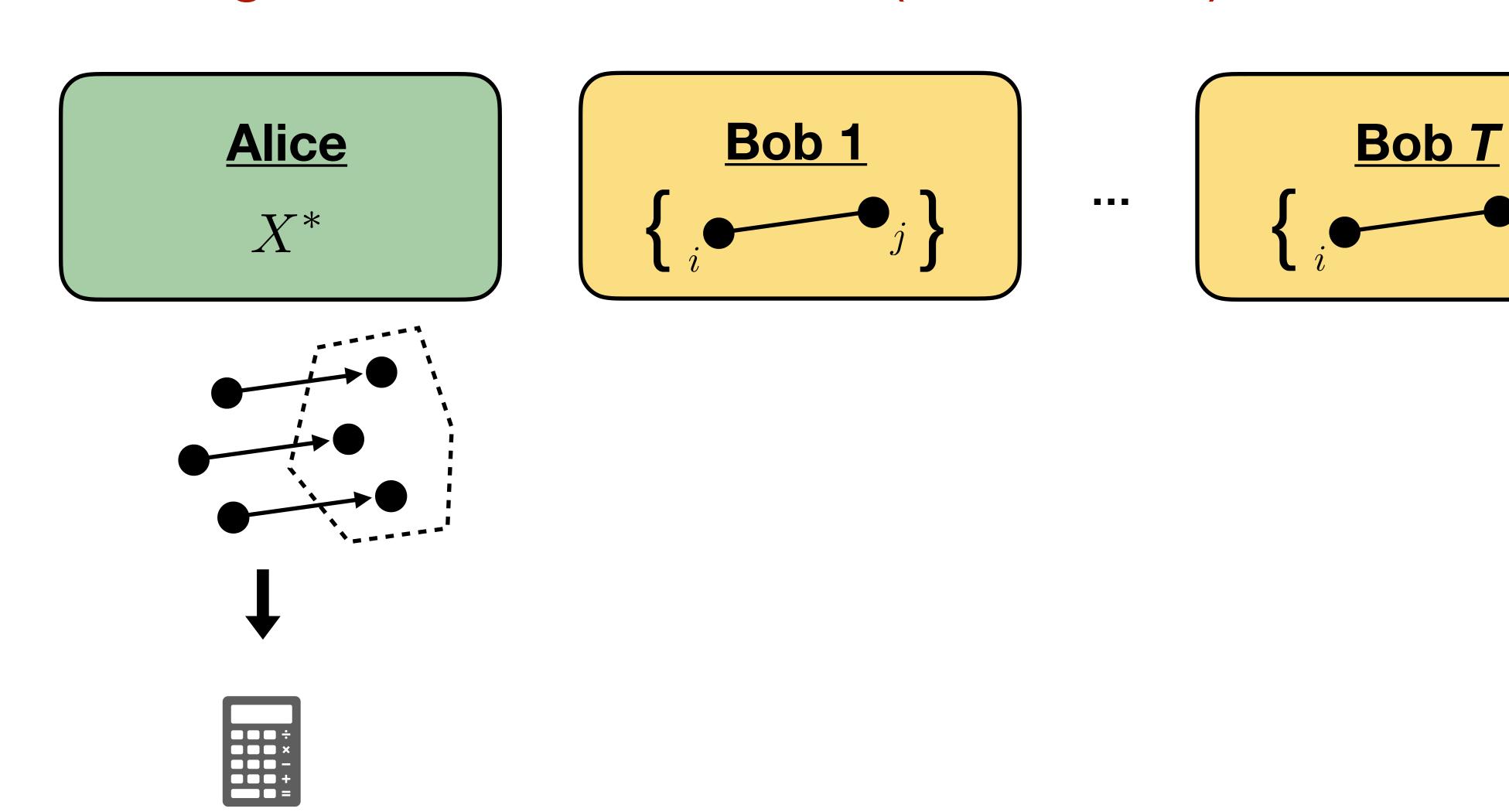
$$\mathsf{val}_{\mathcal{C}} < \left(\frac{1}{2} + o(1)\right) \cdot m$$

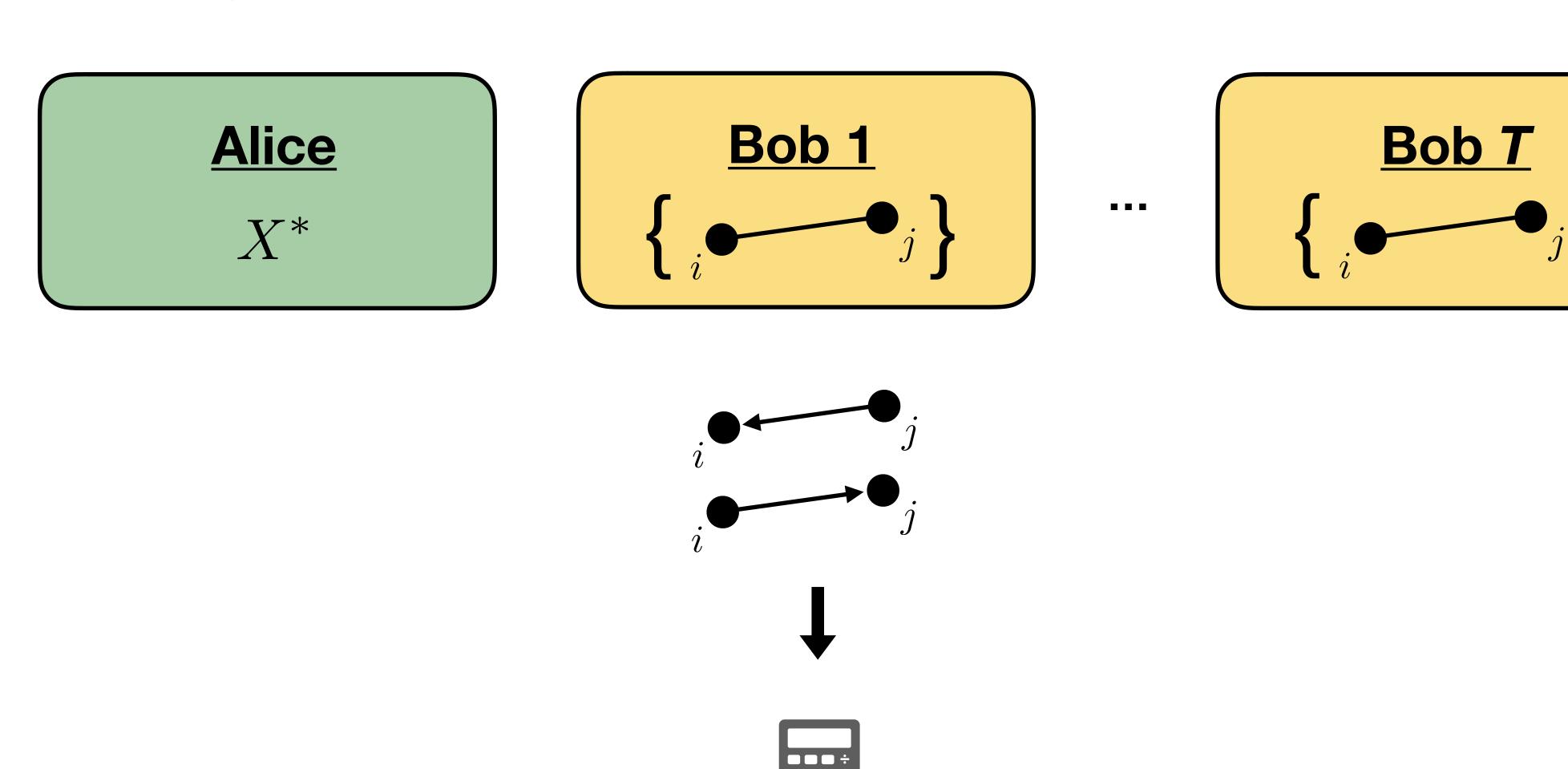


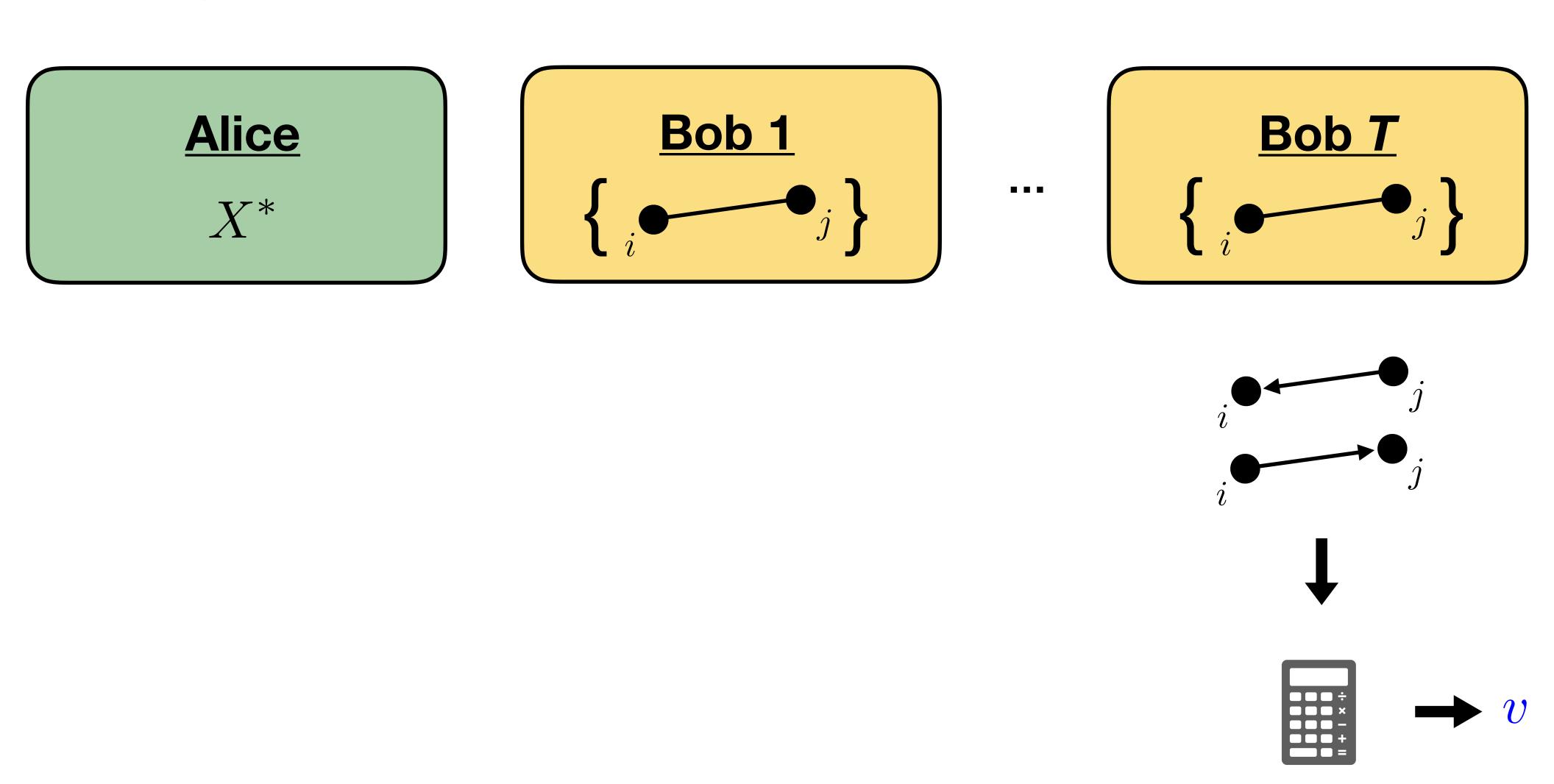
Boolean 2CSP

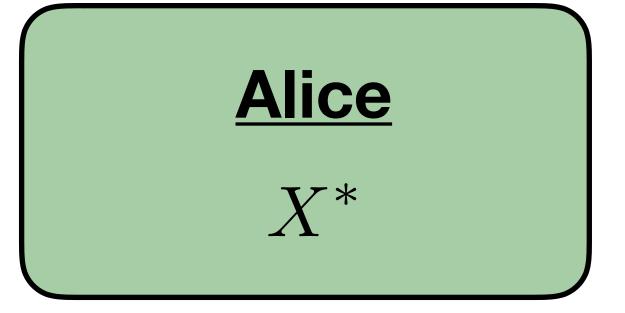
Λ	$\alpha_{f \Lambda}$	Previous	Reference
2XOR	$\frac{1}{2}$	$\frac{1}{2}$	Trivial
2EOR	$rac{3}{4}$	$\left[\frac{3}{4},1\right]$	Trivial
2AND	$\frac{4}{9}$	$\left[rac{2}{5},rac{1}{2} ight]$	Biased sampling
20R	$\frac{\sqrt{2}}{2}$	$\left[\frac{1}{2},1\right]$	Biased sampling

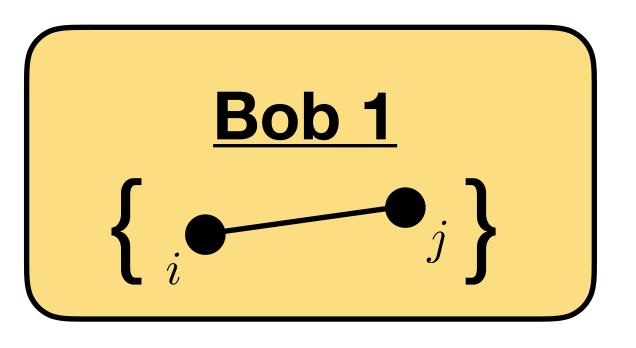


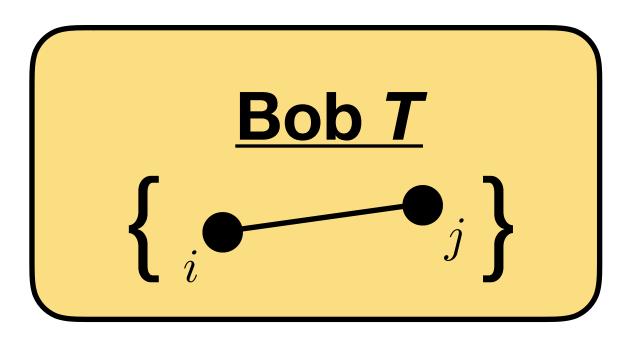


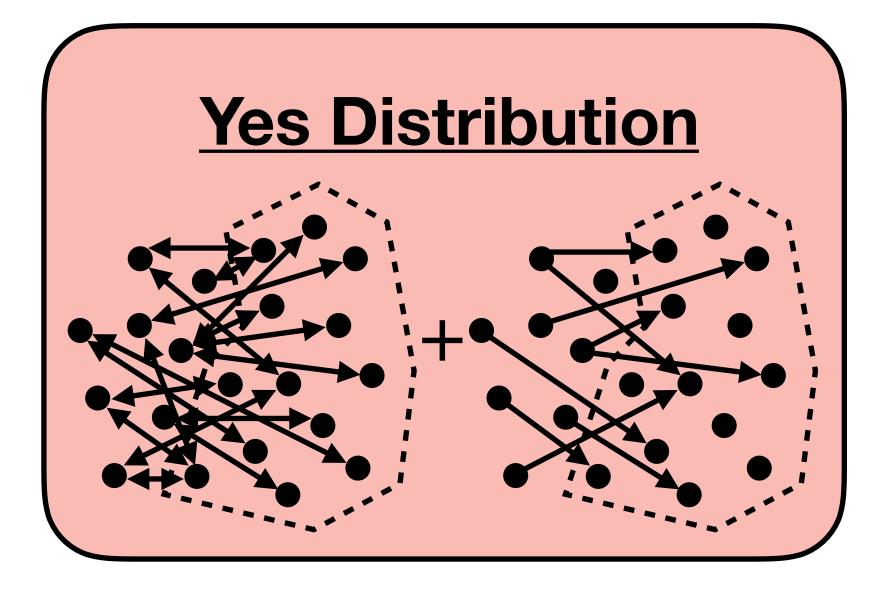


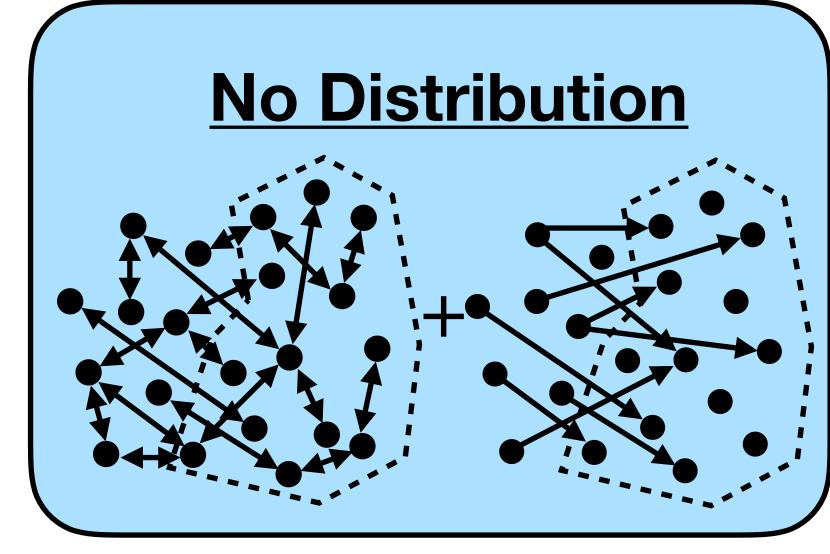


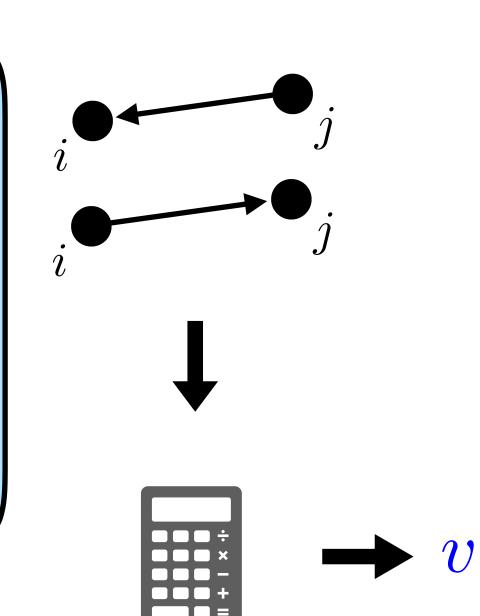






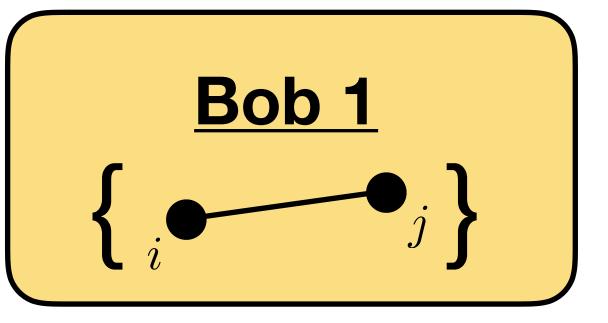




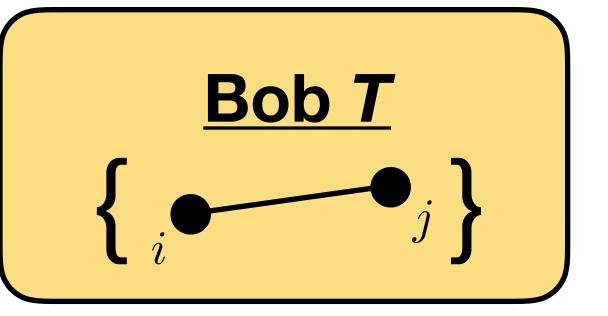


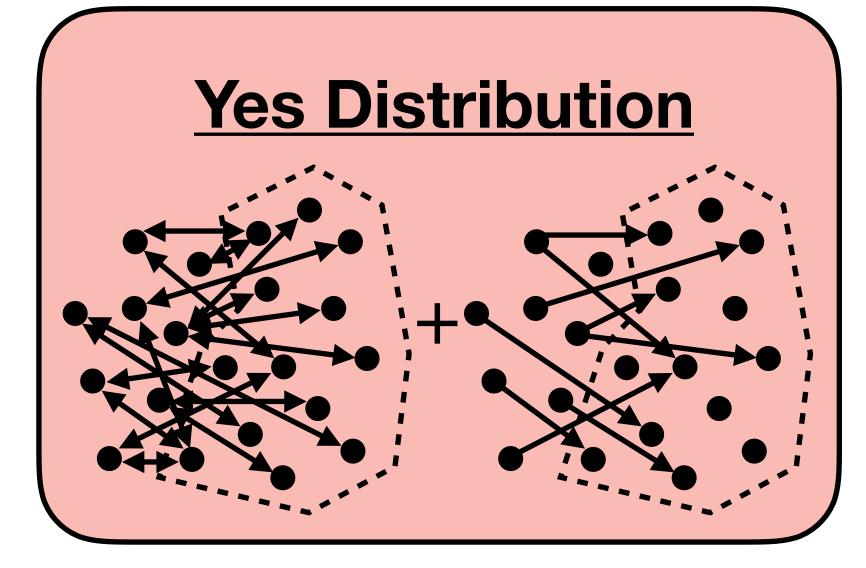


 X^*

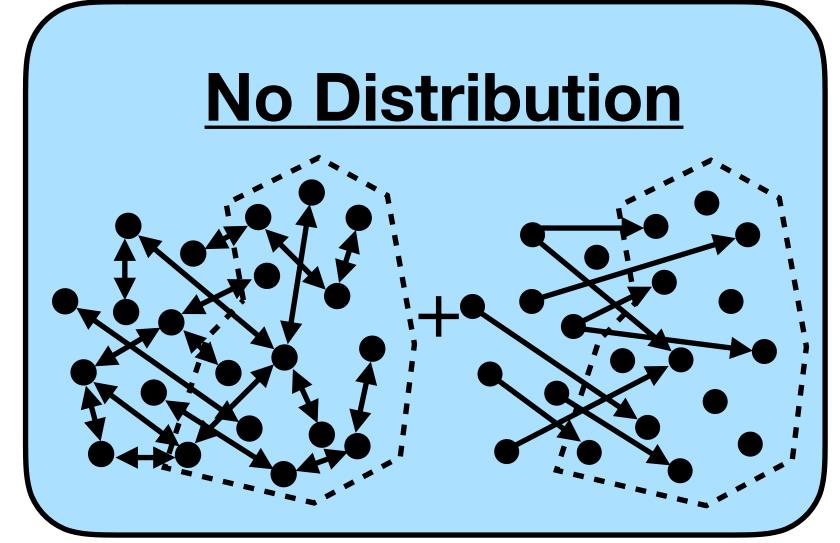


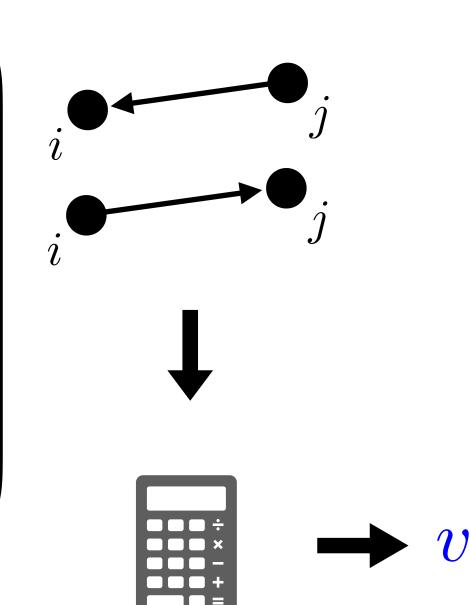
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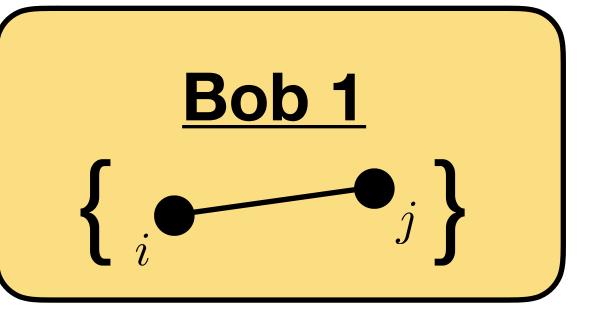


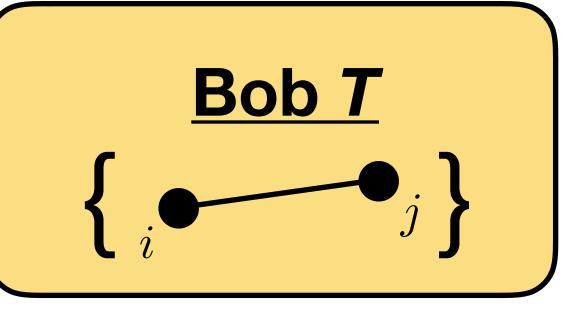
$$\operatorname{val}_{\mathcal{C}} \ge \left(1 - o(1)\right) \left(\frac{m}{2} + \frac{B}{4}\right)$$



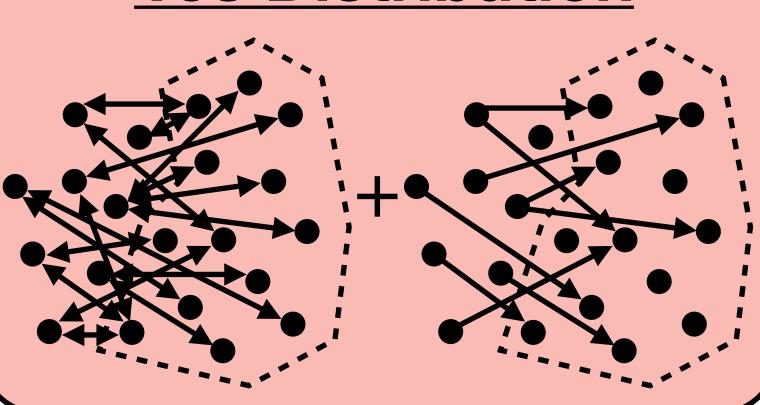




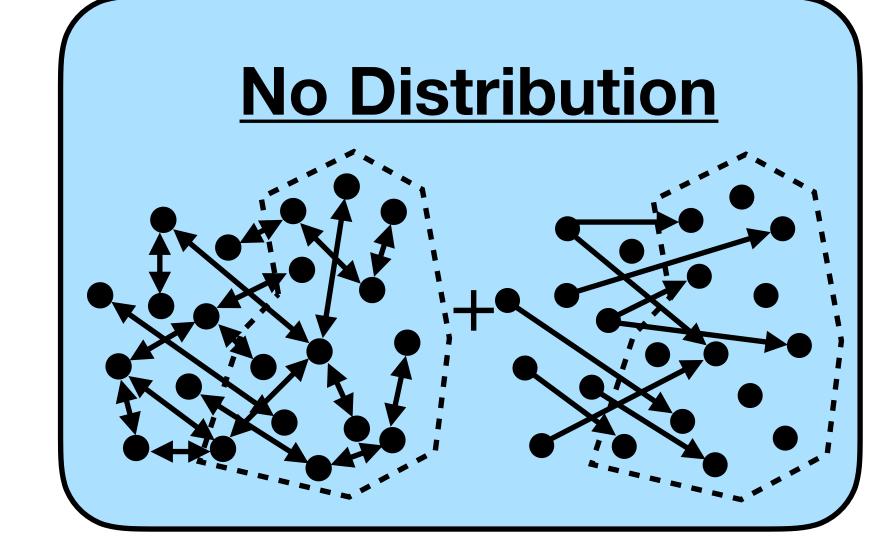




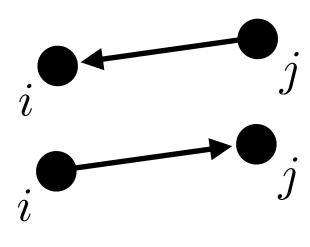
Yes Distribution

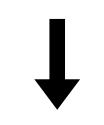


$$\operatorname{val}_{\mathcal{C}} \geq \left(1 - o(1)\right) \left(\frac{m}{2} + \frac{B}{4}\right)$$

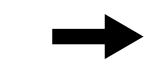


$$\operatorname{val}_{\mathcal{C}} \geq \left(1 - o(1)\right) \left(\frac{m}{2} + \frac{B}{4}\right) \operatorname{val}_{\mathcal{C}} < \left(1 + o(1)\right) \left(\frac{m}{4} + \frac{B^2}{16(m - B)}\right)$$

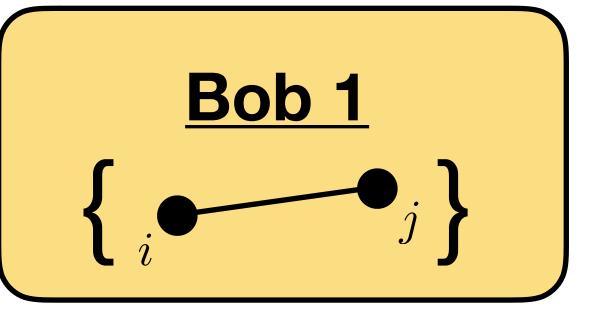


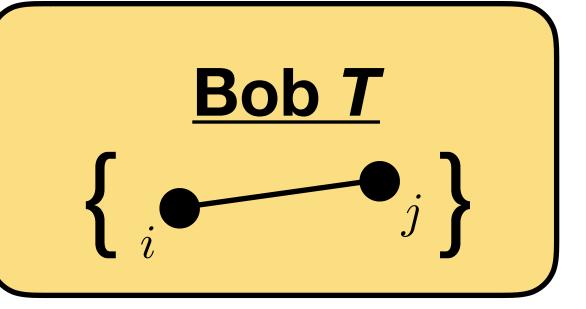


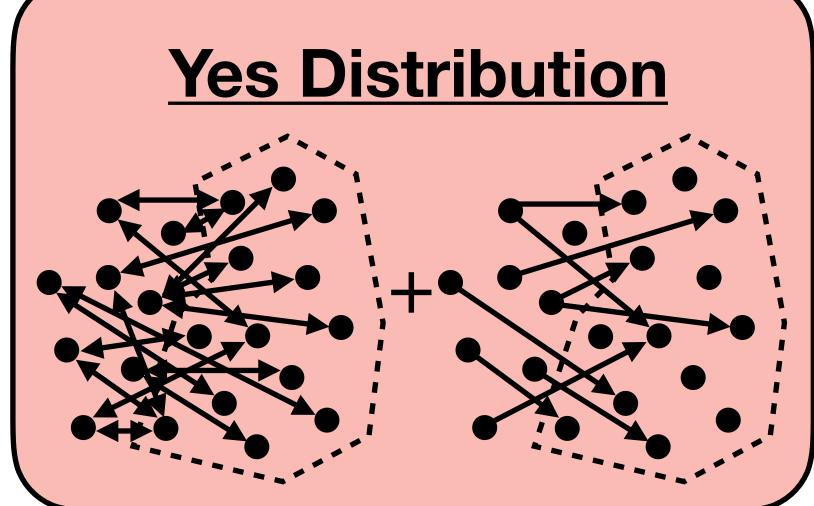




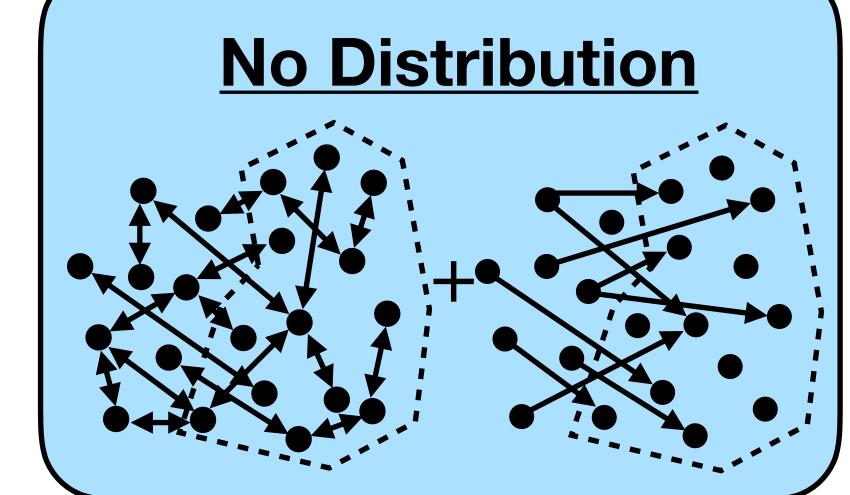




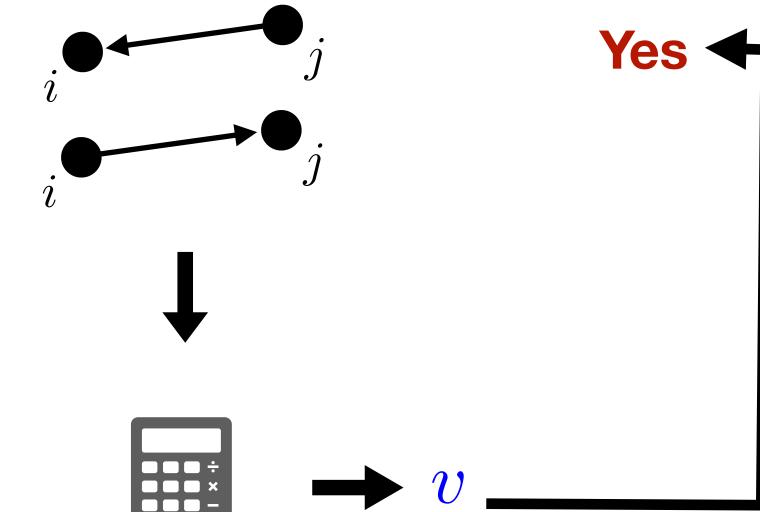




$$\operatorname{val}_{\mathcal{C}} \geq \left(1 - o(1)\right) \left(\frac{m}{2} + \frac{B}{4}\right)$$

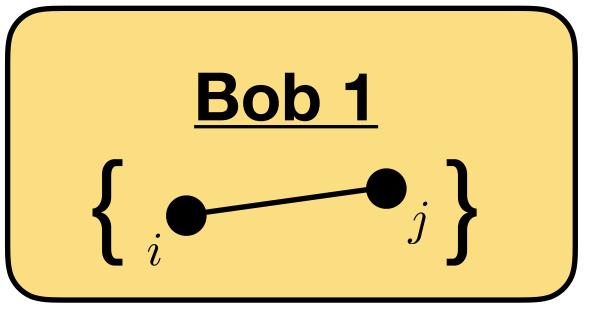


$$\operatorname{val}_{\mathcal{C}} \geq \left(1 - o(1)\right) \left(\frac{m}{2} + \frac{B}{4}\right) \operatorname{val}_{\mathcal{C}} < \left(1 + o(1)\right) \left(\frac{m}{4} + \frac{B^2}{16(m - B)}\right)$$

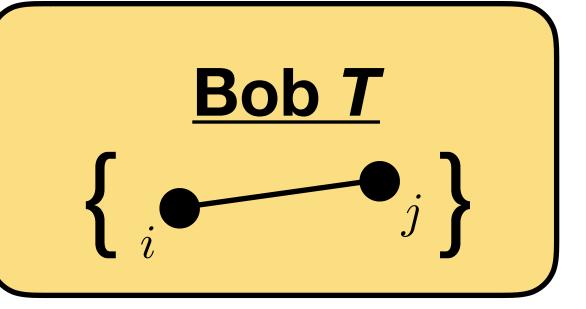




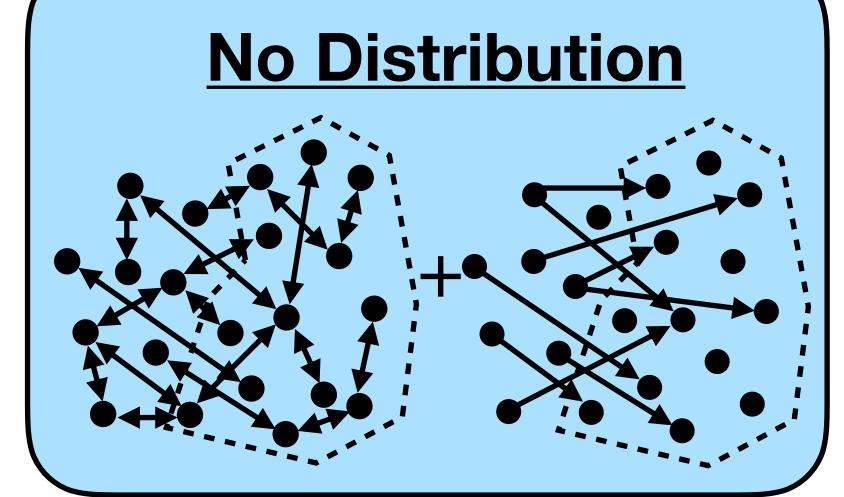
 X^*

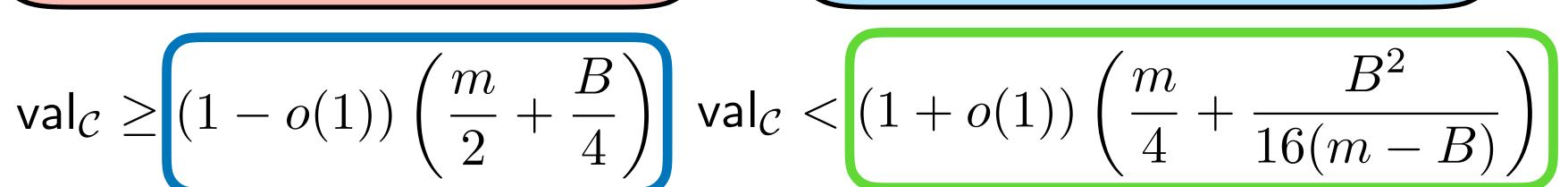


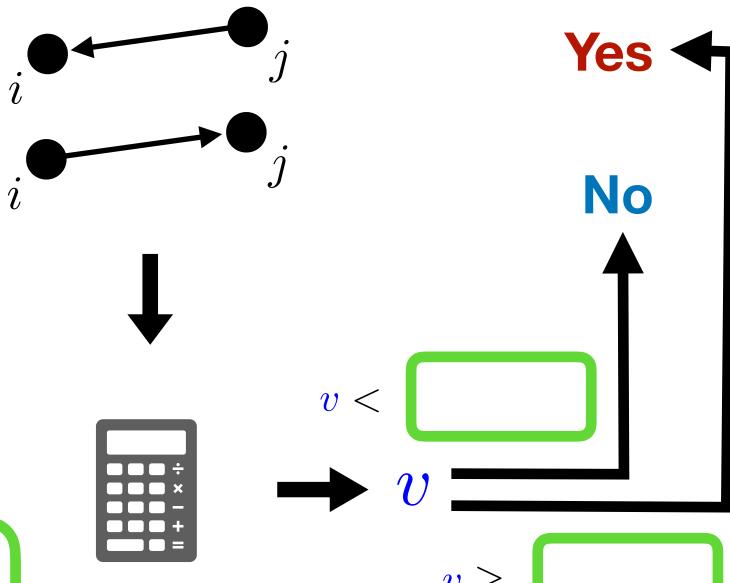
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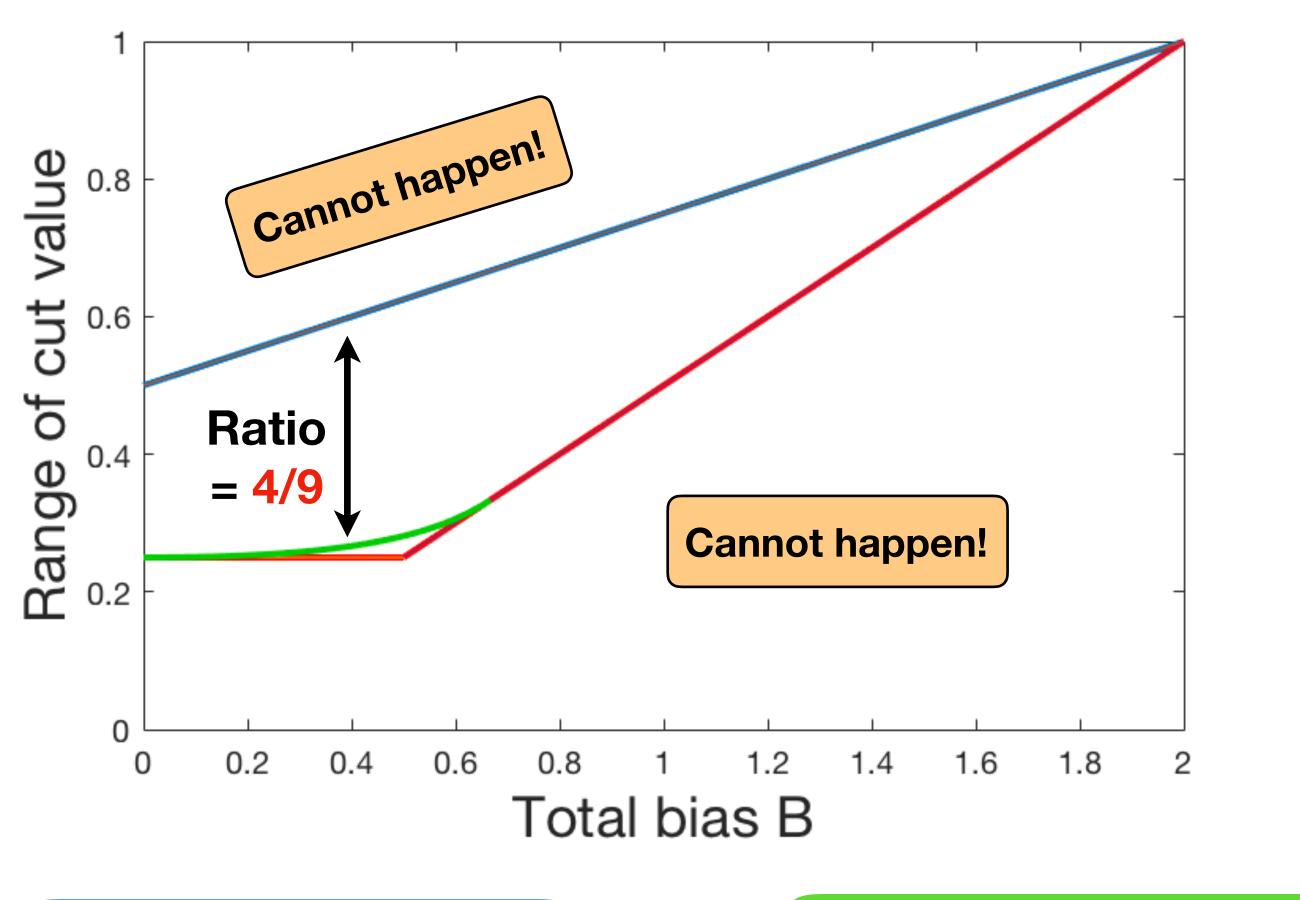


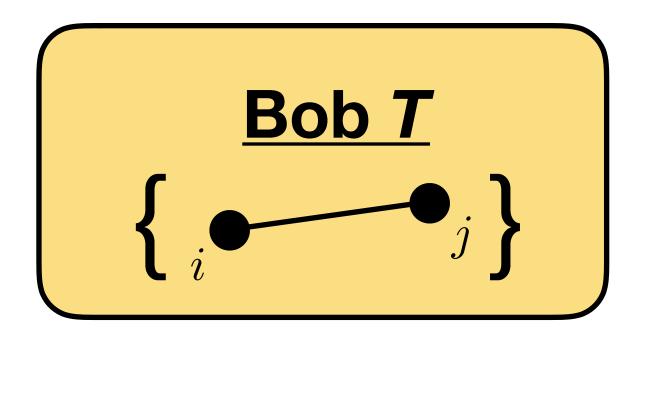
Yes Distribution + The second of the second

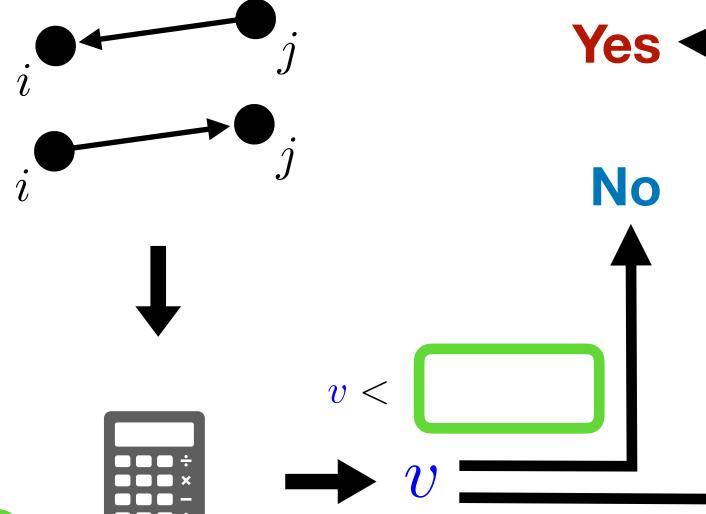












$$\operatorname{val}_{\mathcal{C}} \geq \left(1 - o(1)\right) \left(\frac{m}{2} + \frac{B}{4}\right) \operatorname{val}_{\mathcal{C}} < \left(1 + o(1)\right) \left(\frac{m}{4} + \frac{B^2}{16(m - B)}\right)$$

Boolean 2CSP

Λ	α_{Λ}	Previous	Reference	
2XOR	$\frac{1}{2}$	$\frac{1}{2}$	Trivial	
2EOR	$\frac{3}{4}$	$\left[rac{3}{4},1 ight]$	Trivial	
2AND	$\frac{4}{9}$	$\left[rac{2}{5},rac{1}{2} ight]$	Biased sampling	
20R	$\frac{\sqrt{2}}{2}$	$\left[rac{1}{2},1 ight]$	Biased sampling	





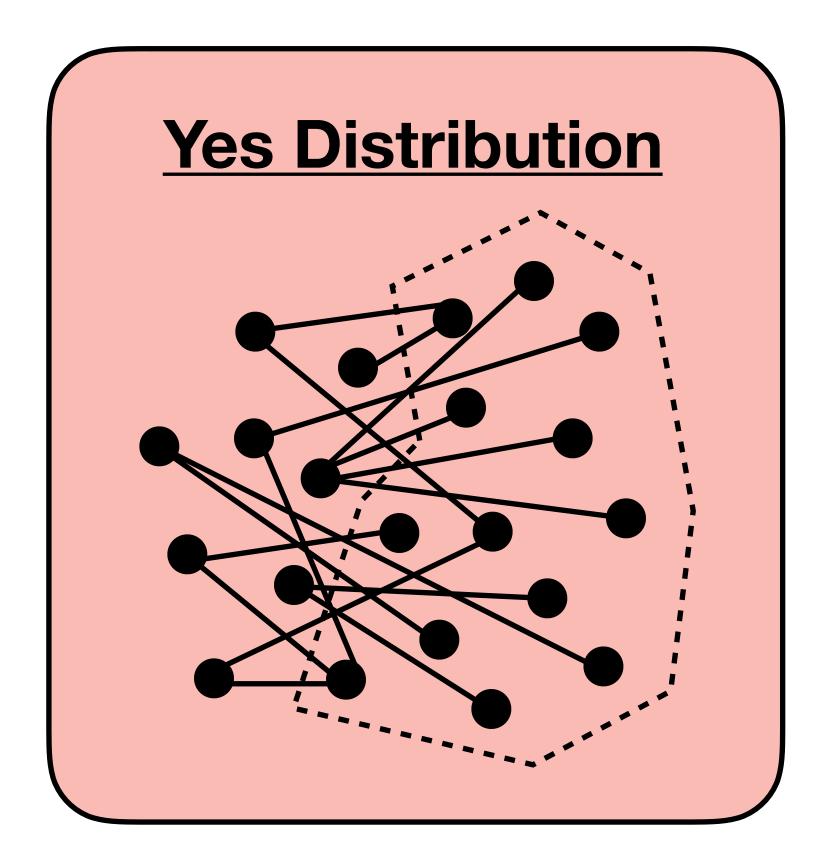
Summary of the DBHP Technique

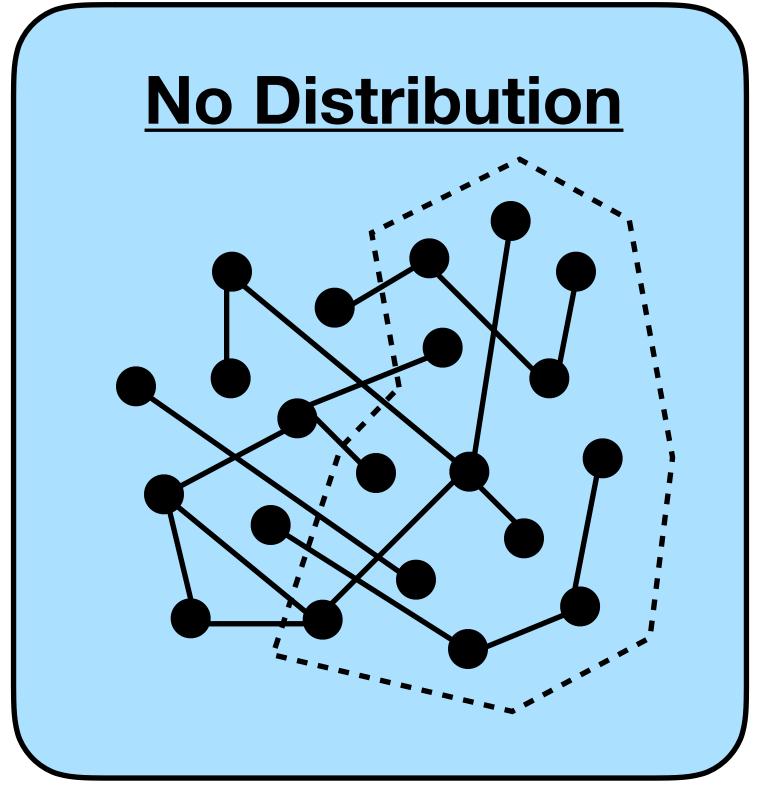
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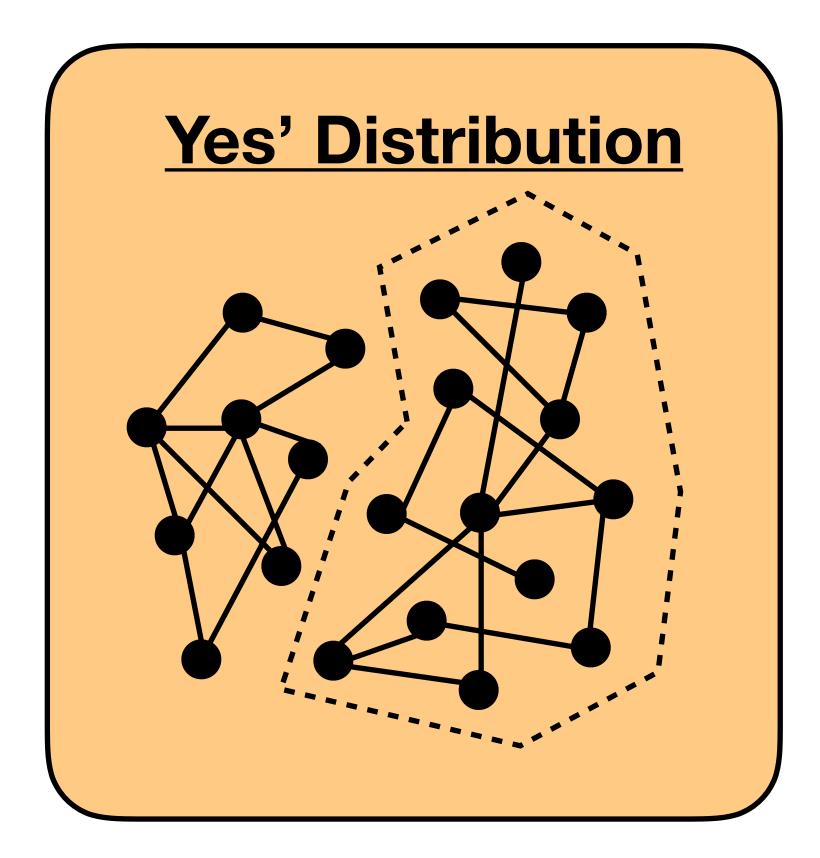
• Step 1: Identify the gap instances for Max-CSP of type Λ.

Summary of the DBHP Technique

- Step 1: Identify the gap instances for Max-CSP of type Λ .
- Step 2: Connect one of the three distributions of DBHP to the gap instances.







Theorem

For any boolean 2CSP of type Λ , there exist $\alpha_{\Lambda}, \tau_{\Lambda}$ such that $\forall \epsilon > 0$,

- (i) there's a $(\alpha_{\Lambda} \epsilon)$ -approx. in $O(\log n)$ space and
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XOR	$\frac{1}{2}$	1	[KK19]
AND	$\frac{4}{9}$	$\frac{1}{2}$	This work
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Can be extended to Max k-SAT!

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Local random sampling is optimal!

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Future Directions

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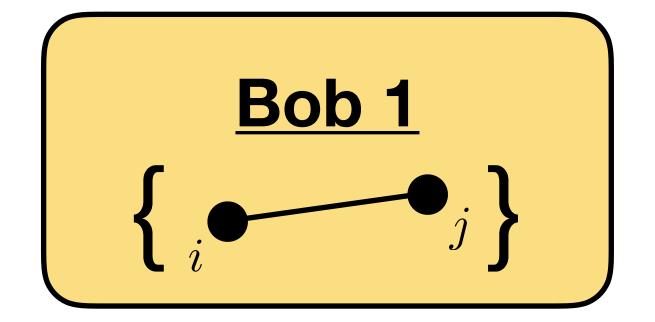
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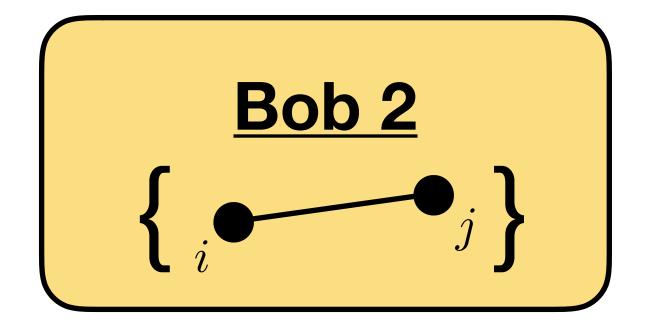
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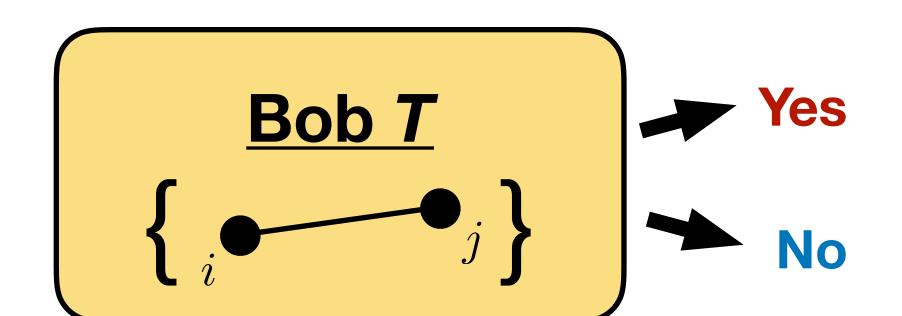
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Thanks for your attention, questions?

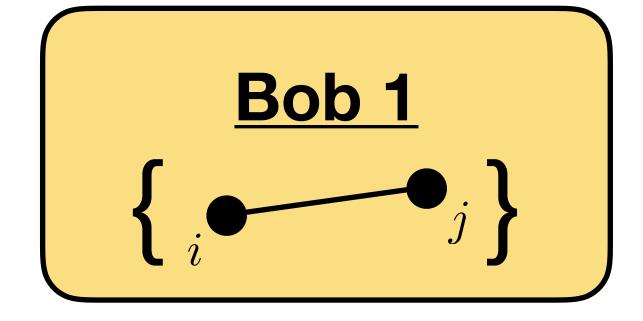


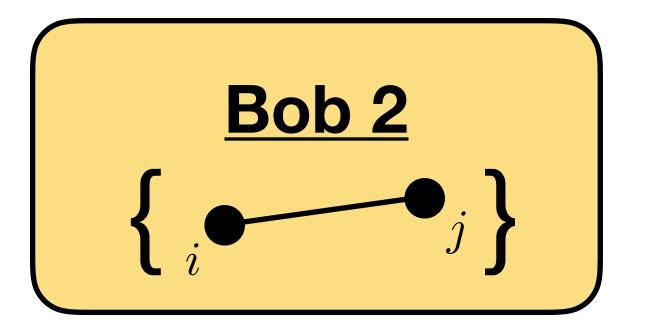


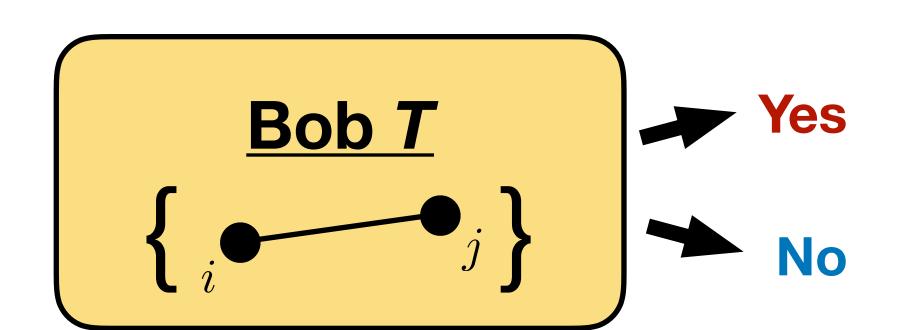




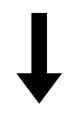






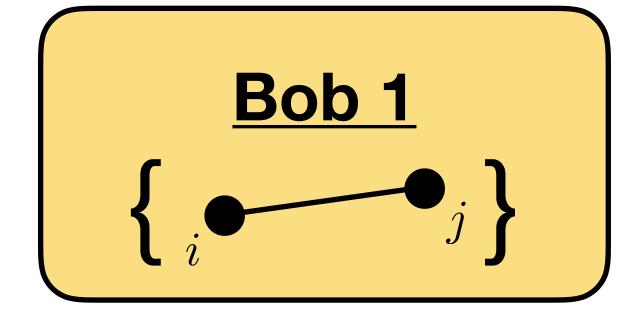


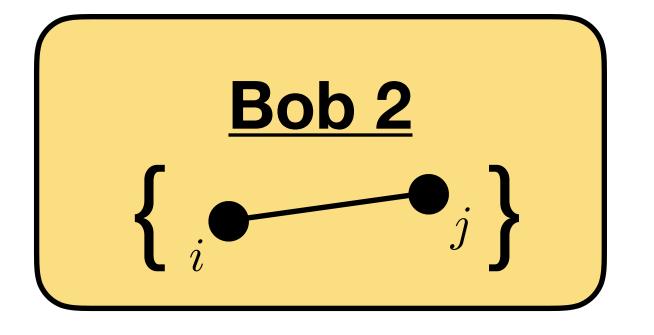
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 $\neg x_i \lor \neg x_j$

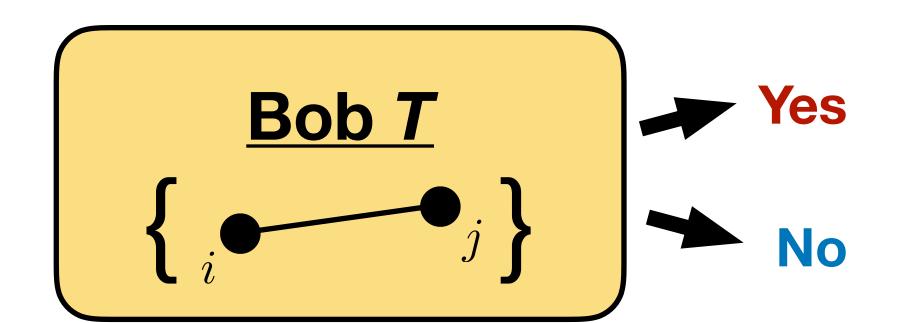




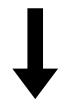






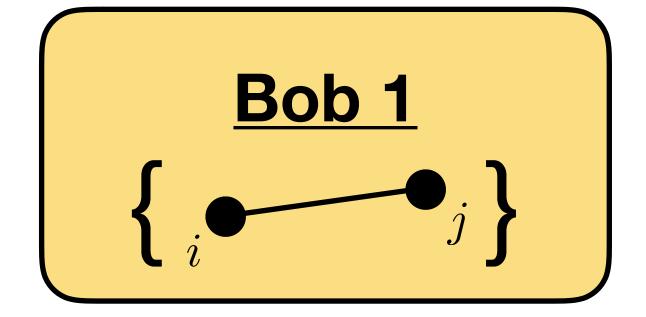


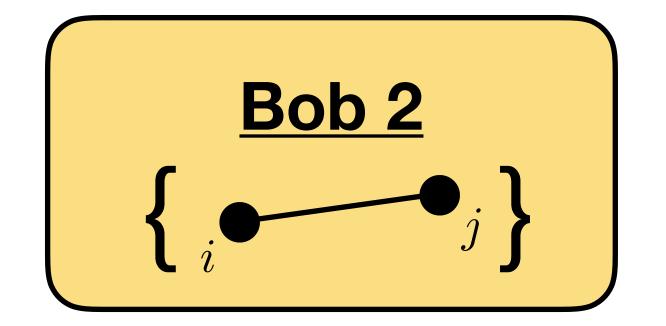
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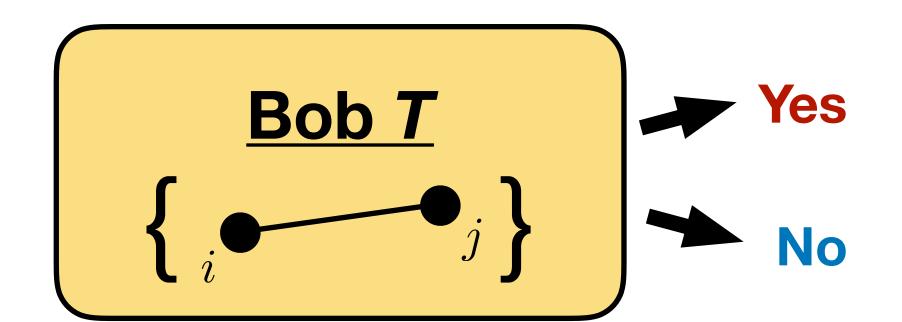






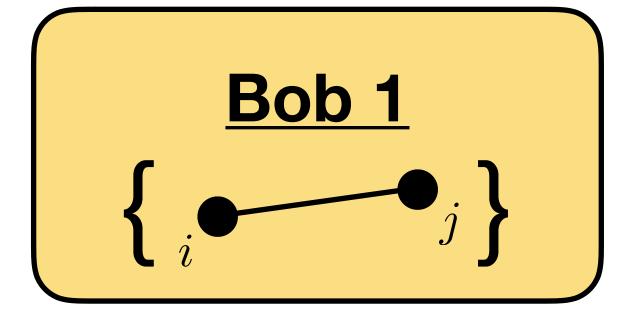


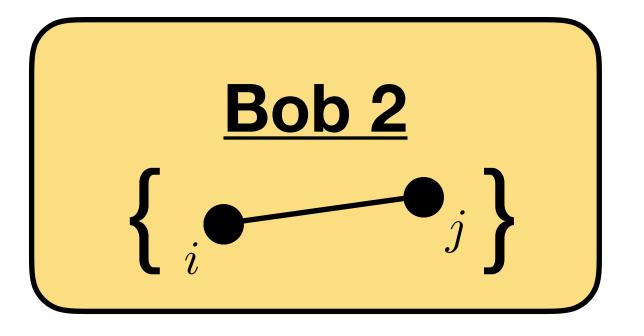


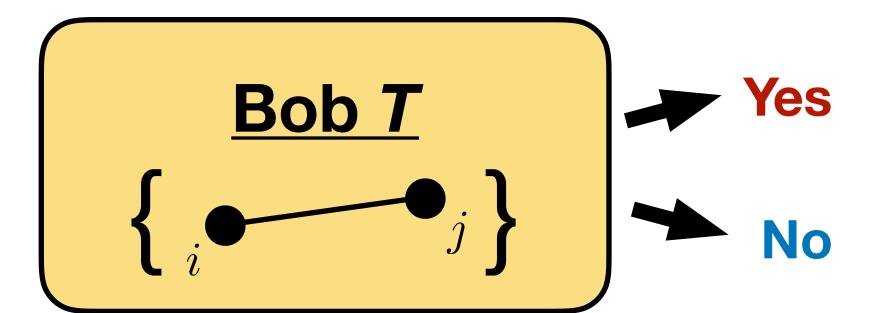


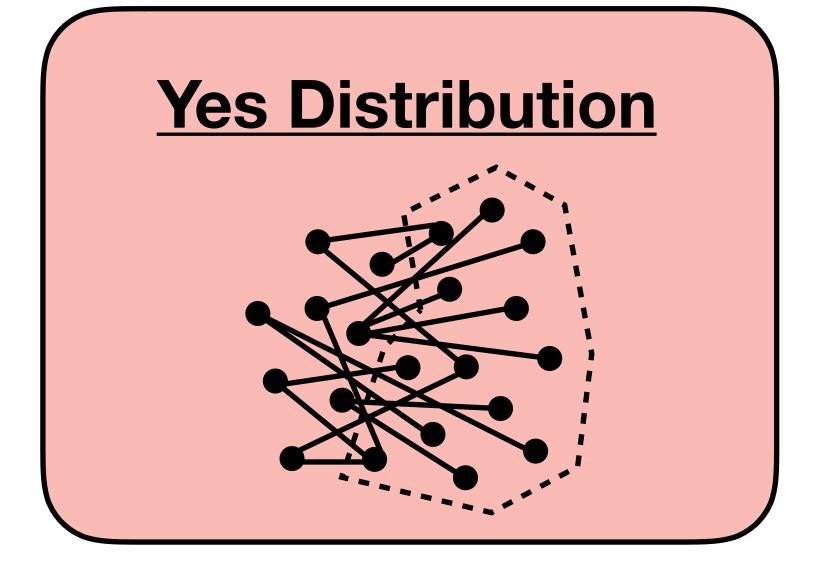
$$x_i \lor x_j$$
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 \blacksquare

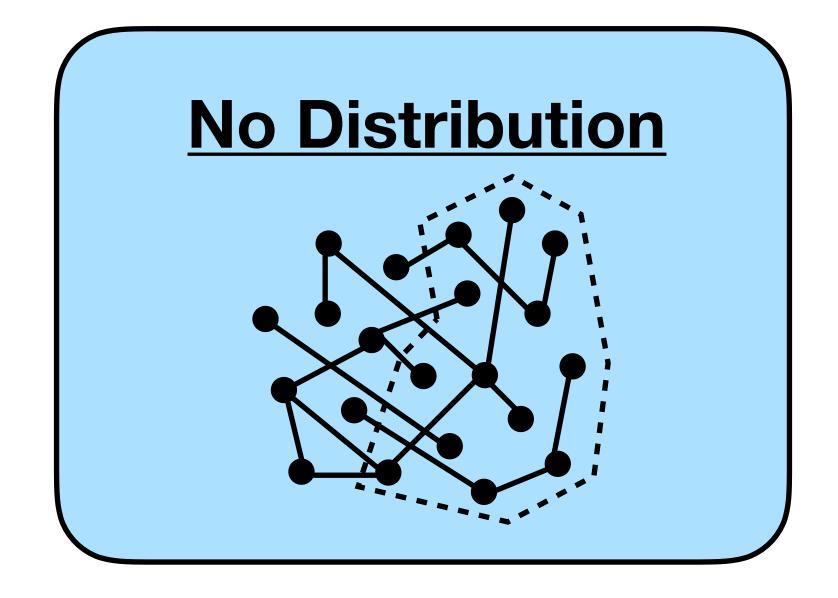


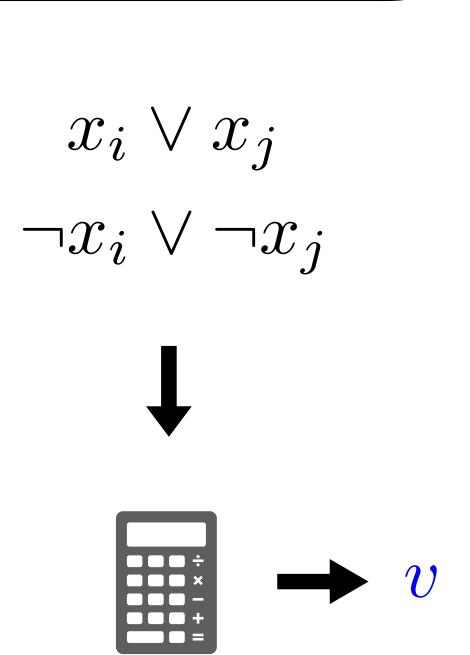




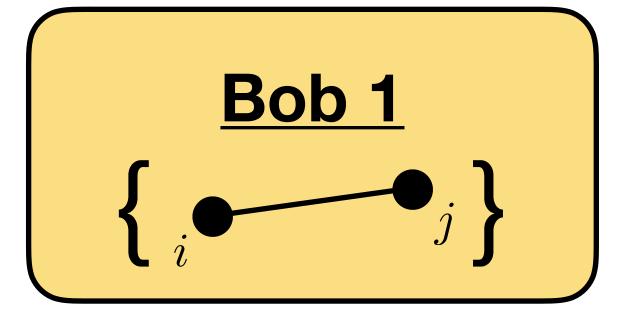


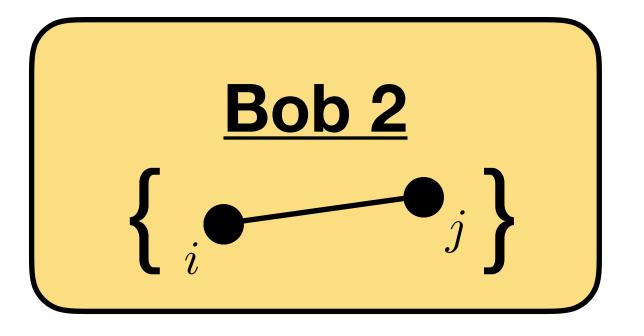


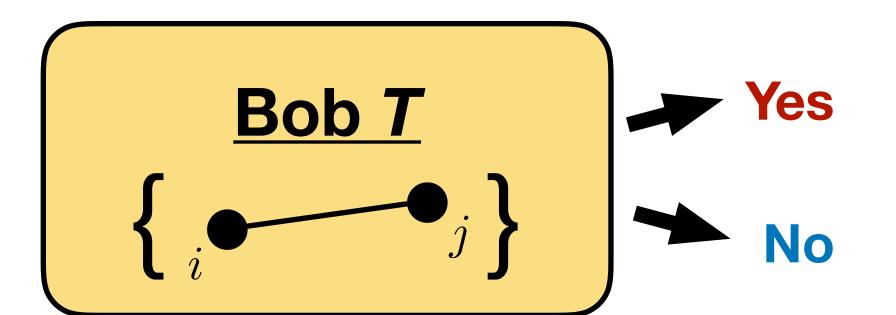


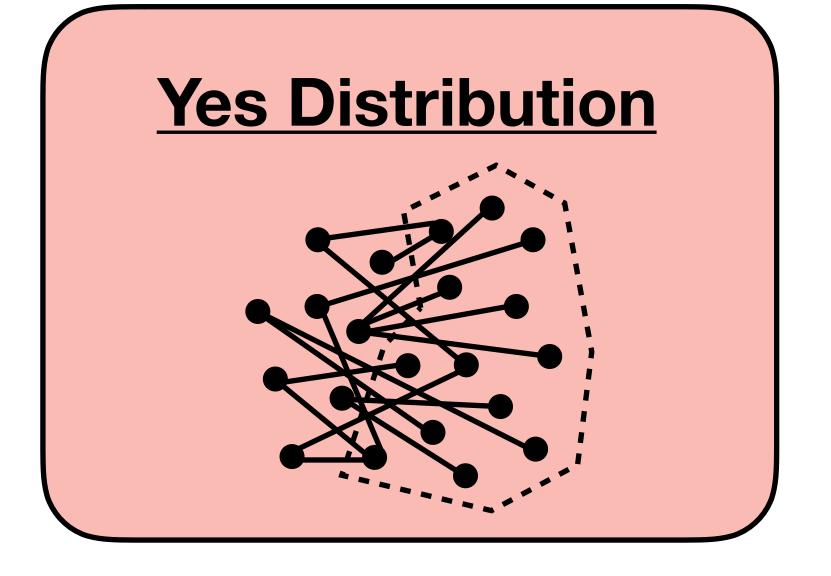


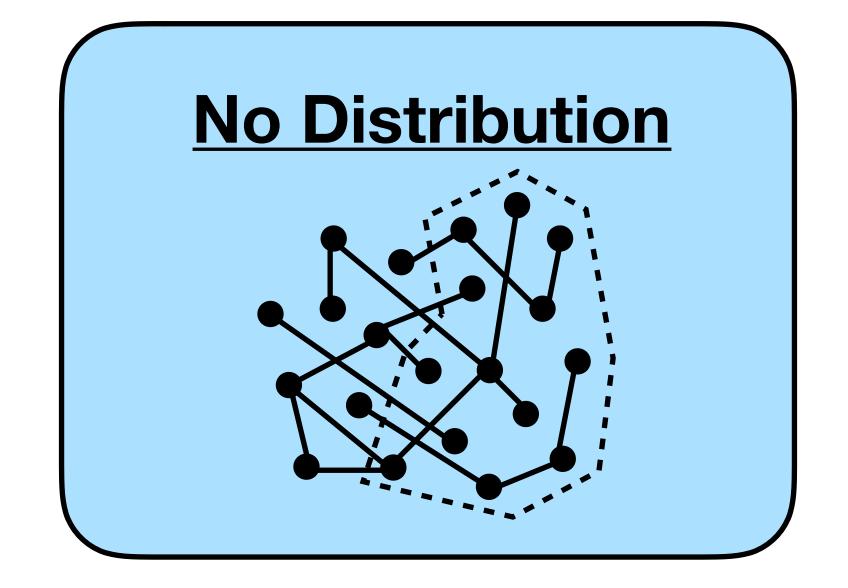


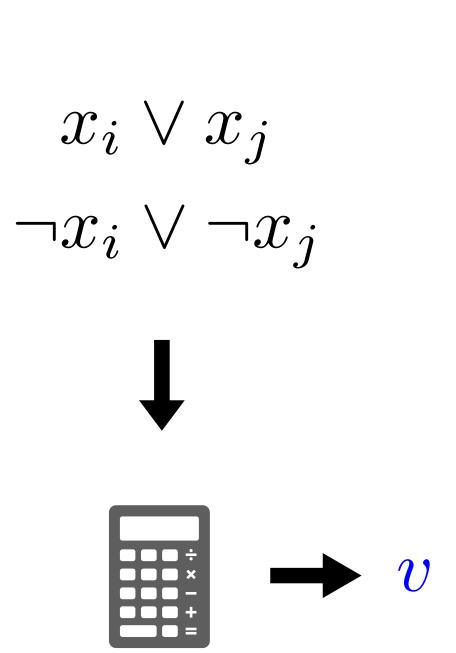






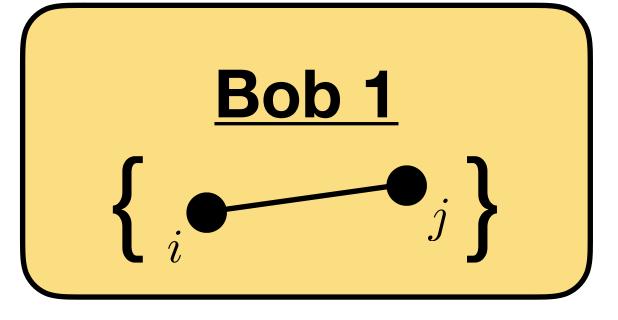


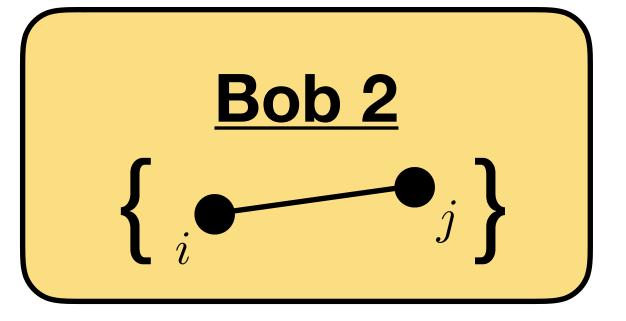


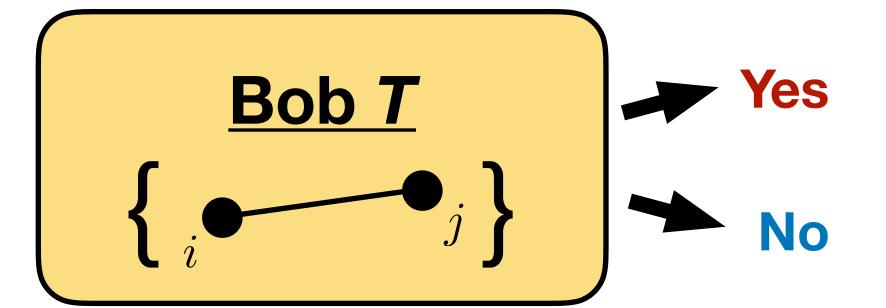


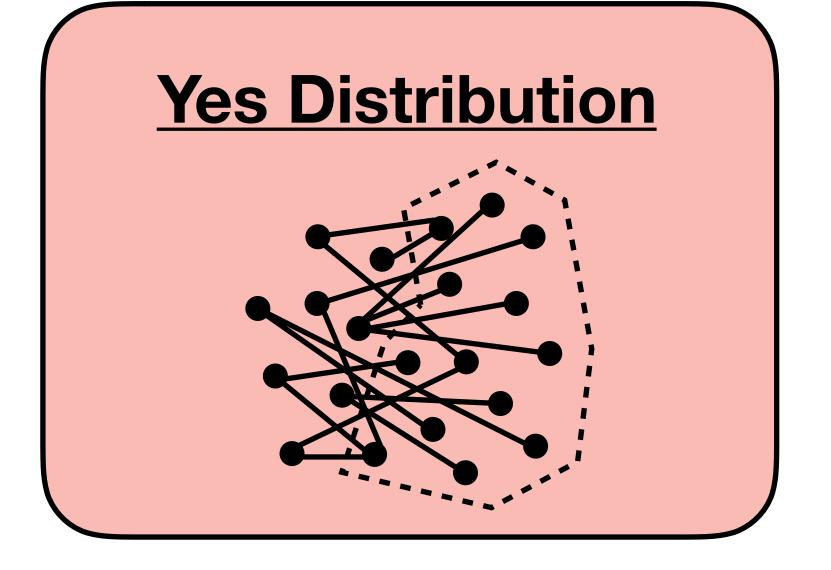
$$\mathsf{val}_\mathcal{C} = m$$



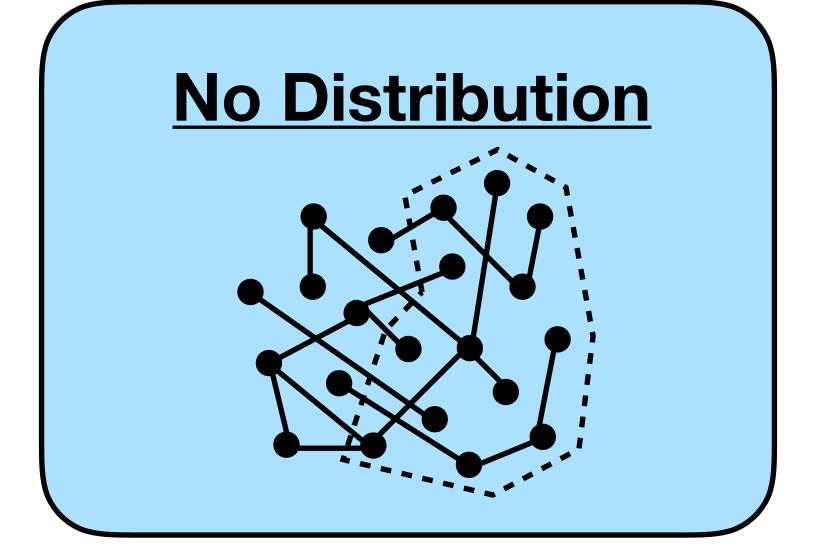








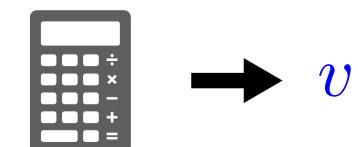
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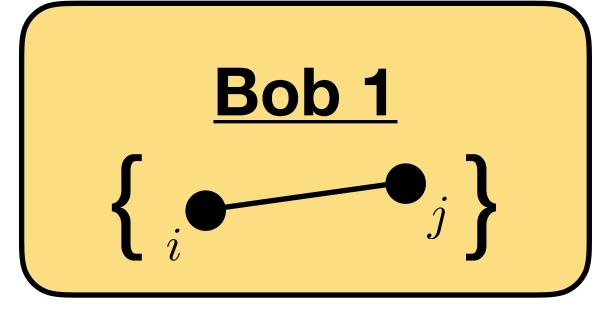
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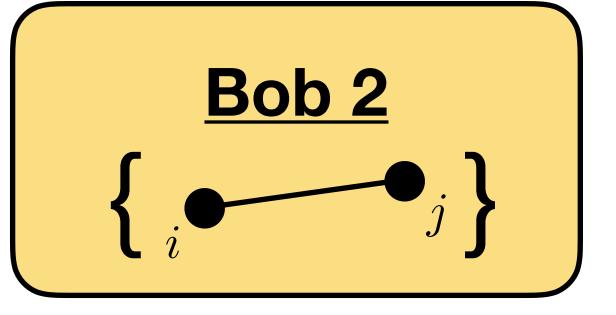
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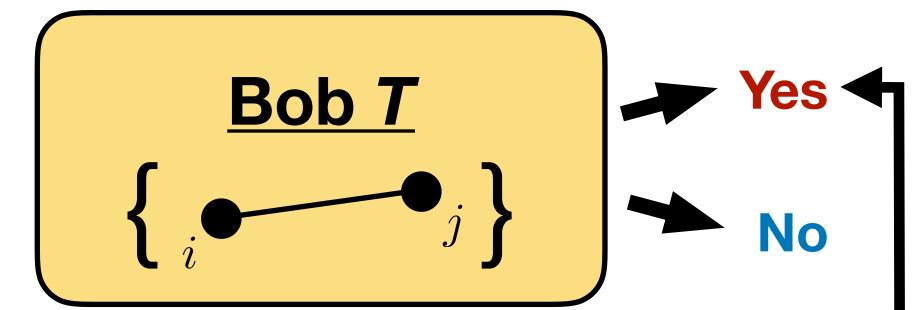




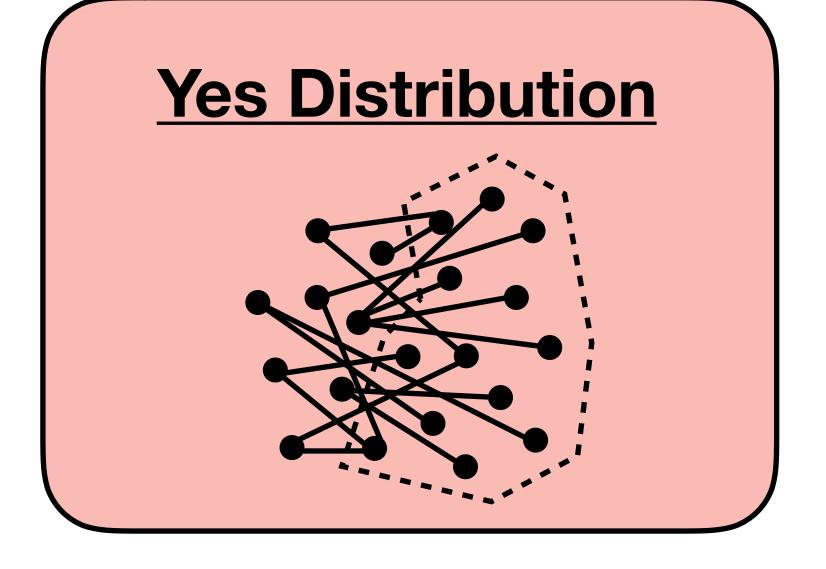


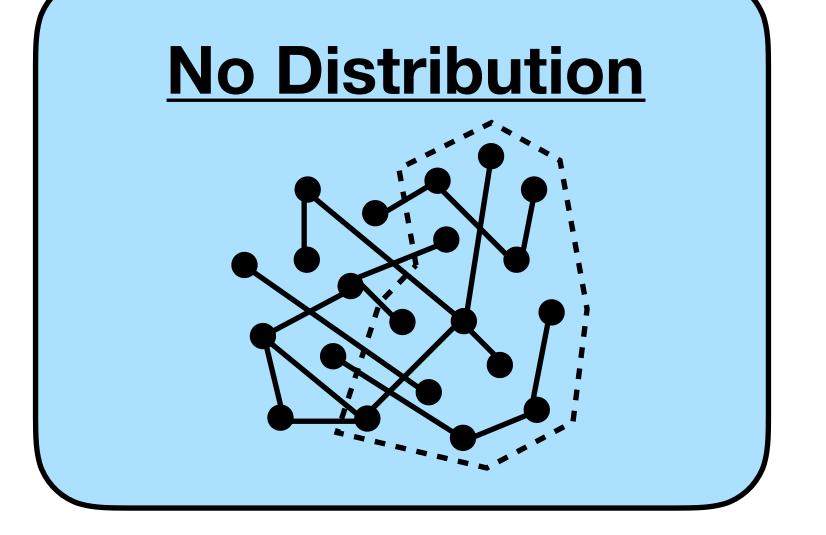






 $x_i \vee x_j$





$$\neg x_i \lor \neg x_j$$

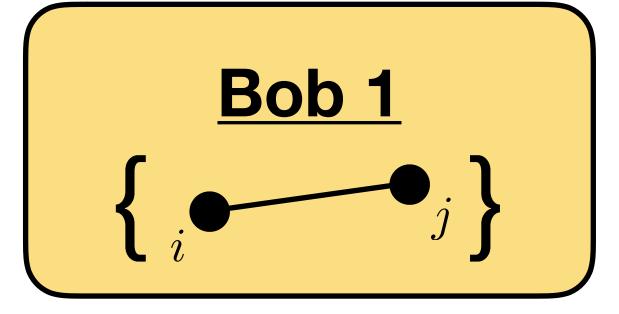
$$\downarrow$$

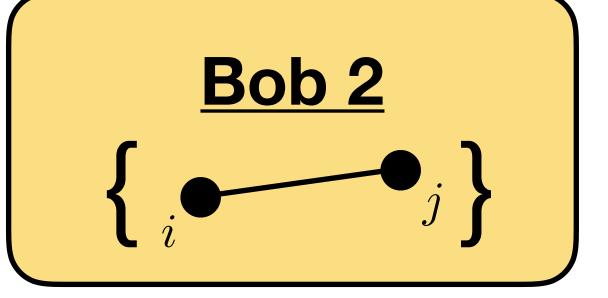
$$v \ge \left(\frac{3}{4} + \epsilon\right) \cdot m$$

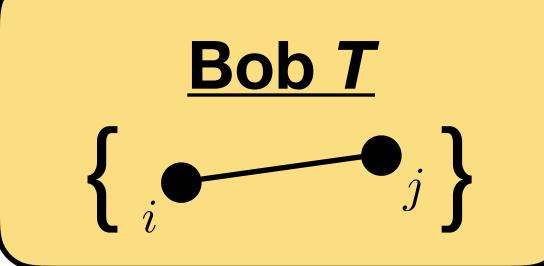
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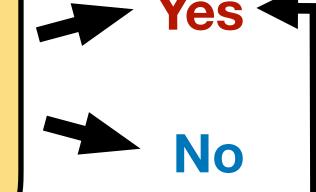
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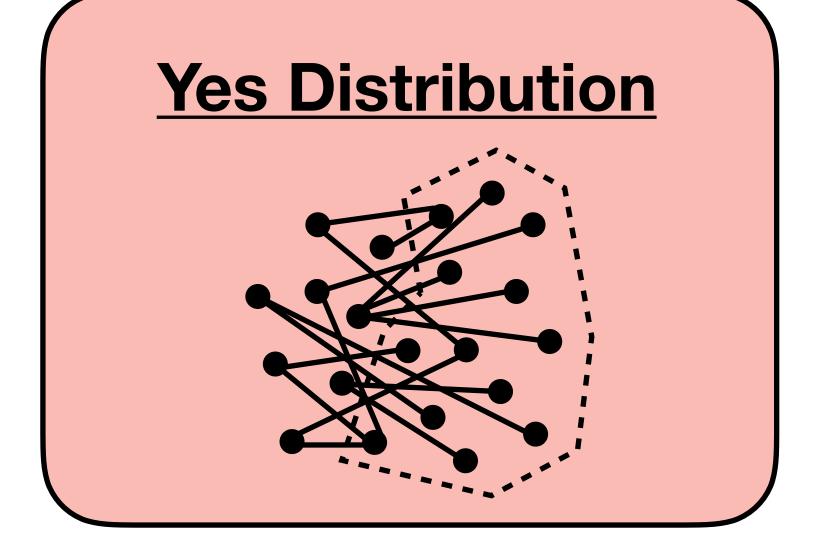




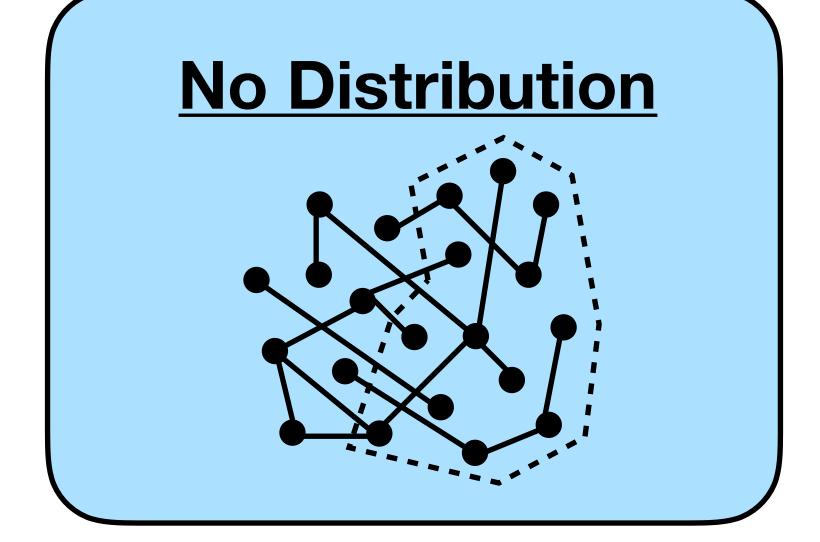




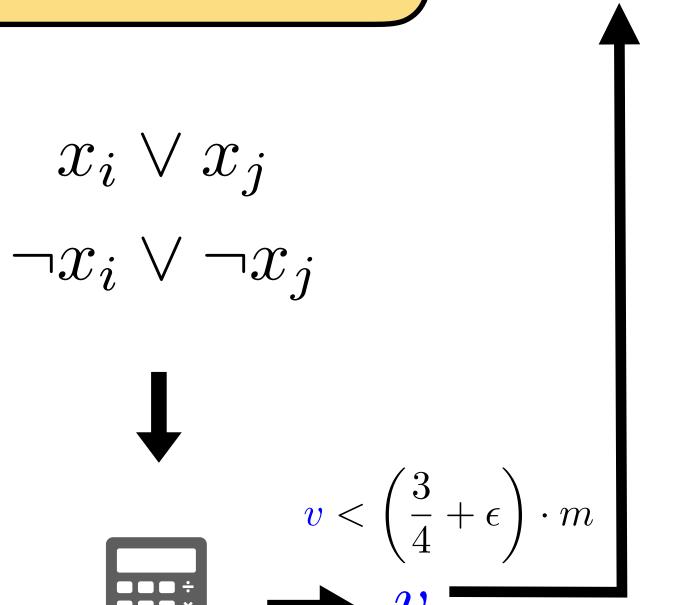
 $\frac{\mathbf{v}}{2} \geq \left(\frac{3}{4} + \epsilon\right) \cdot m$



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$$\begin{cases} \{x_i\} & \{\neg x_i \lor \neg x_j\} \\ \operatorname{val}_{\mathcal{C}} < \left(\frac{\sqrt{2}}{2} + o(1)\right) \cdot m \end{cases}$$

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$$\left\{x_i\right\} \ \left\{ \neg x_i \lor \neg x_j \right\}$$

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$$\left\{ x_i \right\} \; \left\{ \neg y_i \lor \neg y_j \right\}$$

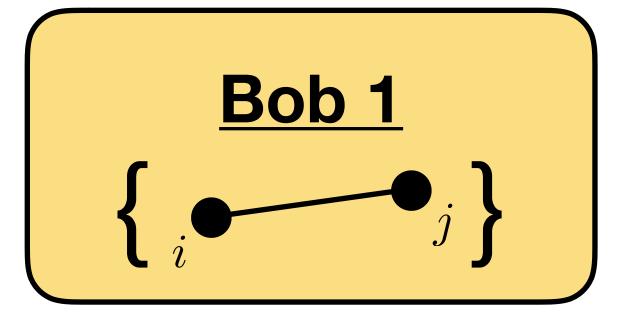
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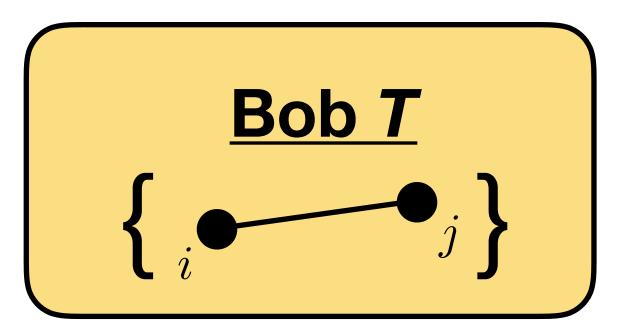




Alice

 X^*

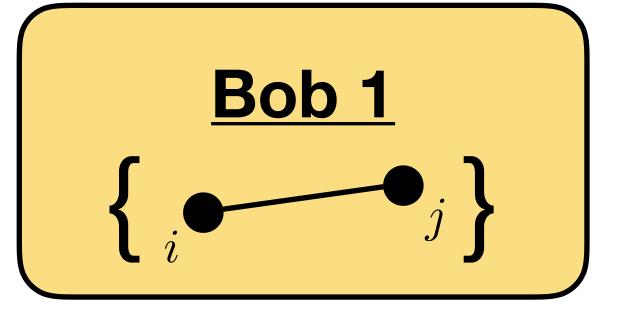




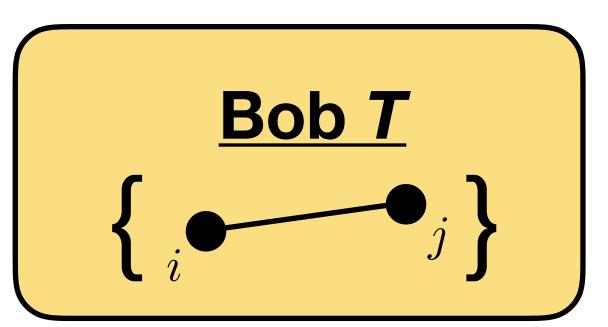


<u>Alice</u>

 X^*

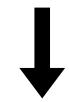


. . .



 x_i

 $\neg x_j$

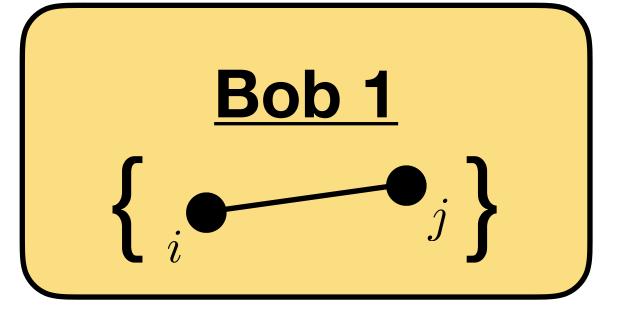


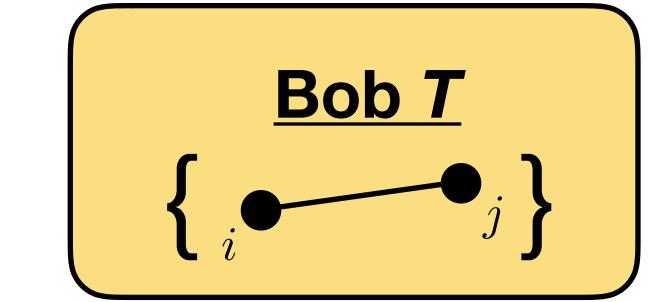




Alice

 X^*



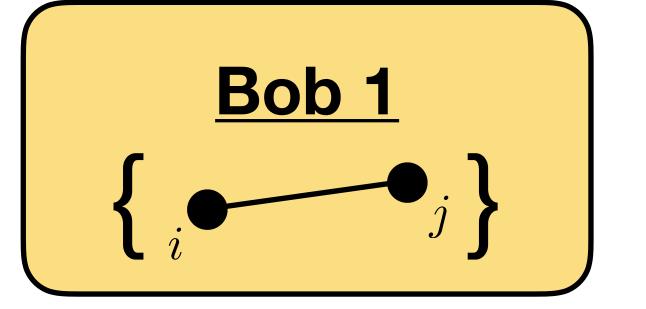


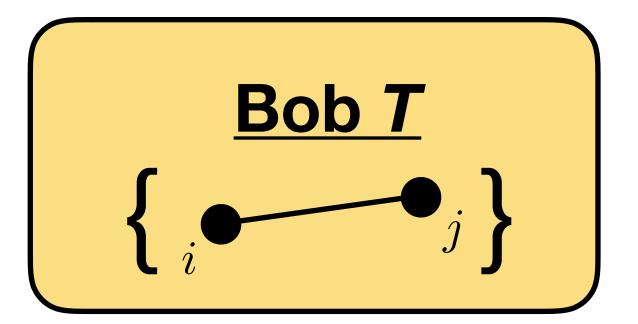
$$x_i \lor x_j$$
 $(\neg x_i) \lor (\neg x_j)$
 \downarrow





 X^*

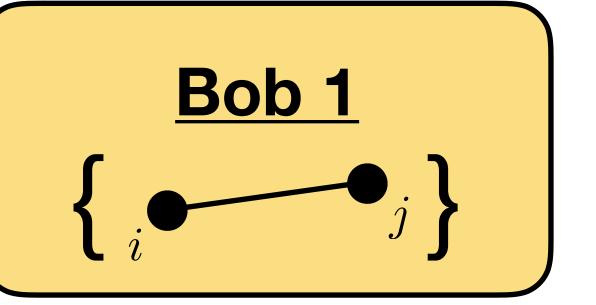


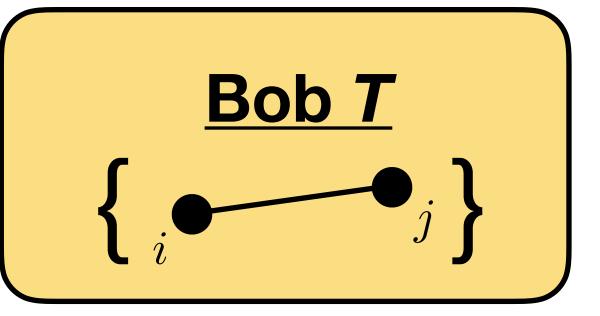


$$x_i \lor x_j$$
 $(\neg x_i) \lor (\neg x_j)$
 \downarrow

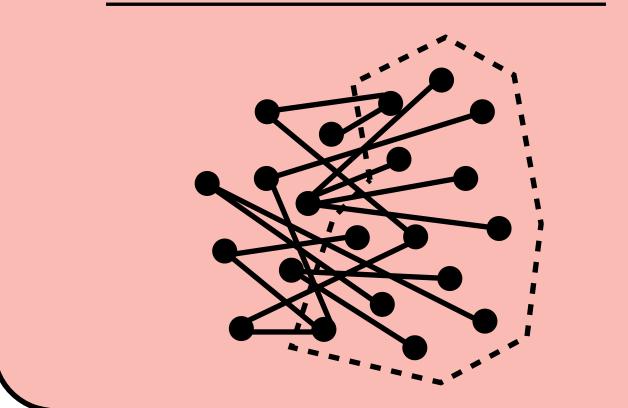




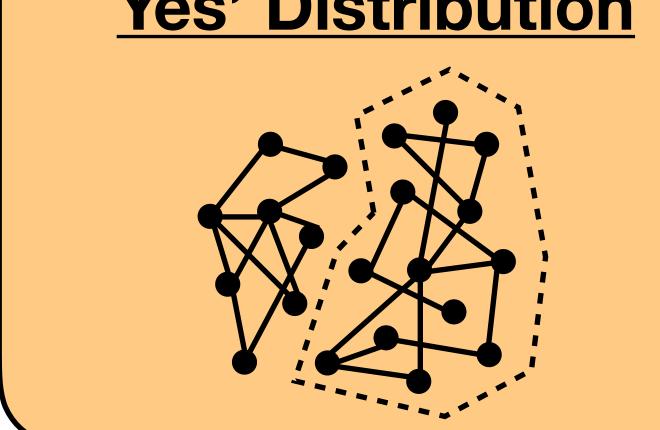




Yes Distribution

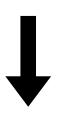




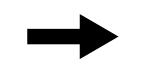


$$x_i \vee x_j$$

$$x_i \lor x_j$$
 $(\neg x_i) \lor (\neg x_j)$



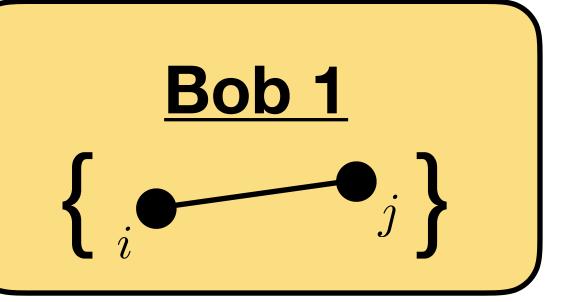




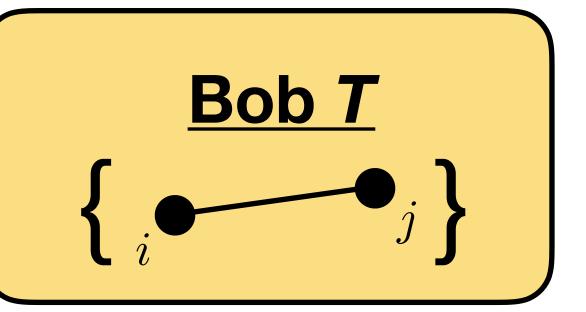


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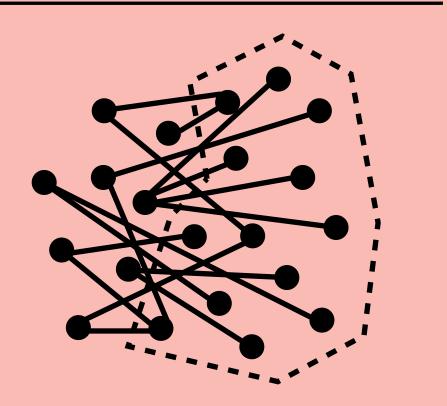
 X^*



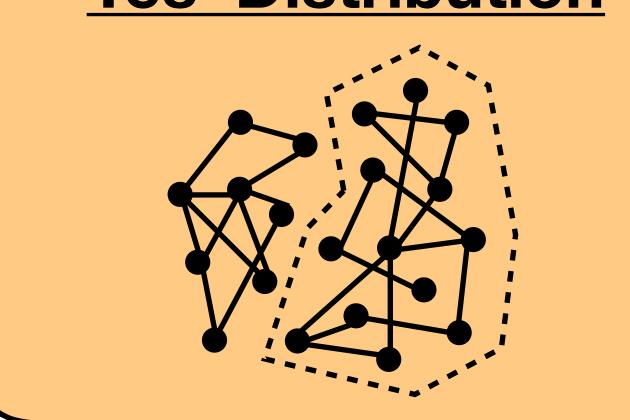
. . .



Yes Distribution

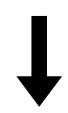


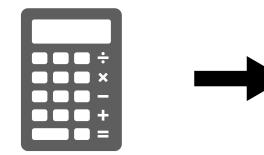




$$x_i \vee x_j$$

$$(\neg x_i) \lor (\neg x_j)$$





$$\mathsf{val}_{\mathcal{C}} < \left(\frac{\sqrt{2}}{2} + o(1)\right) \cdot m$$

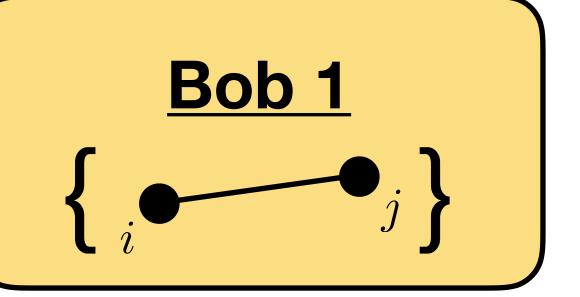
$$\mathsf{val}_{\mathcal{C}} = m$$



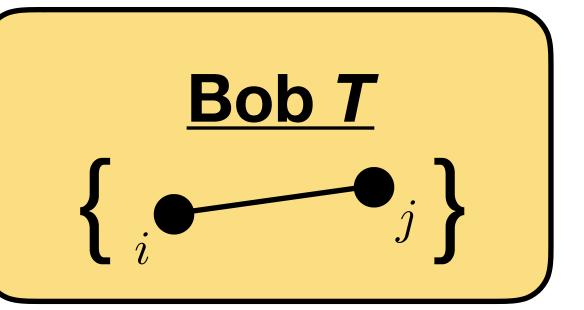
Yes -

Alice

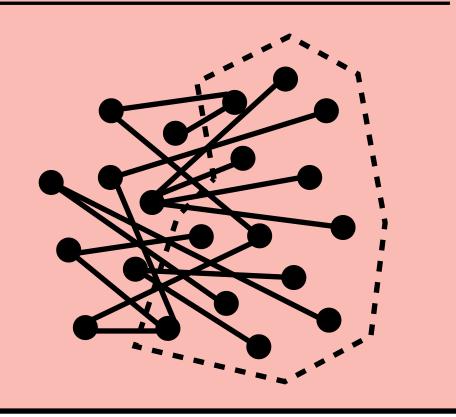
 X^*



. .

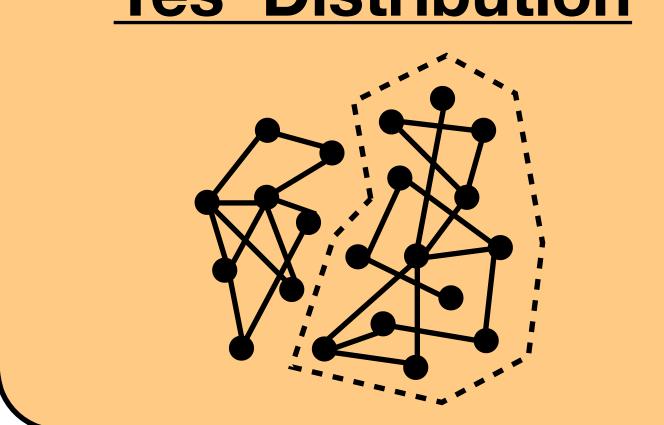


Yes Distribution



$$\mathsf{val}_{\mathcal{C}} < \left(\frac{\sqrt{2}}{2} + o(1)\right) \cdot m$$

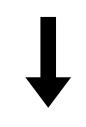
Yes' Distribution



$$\mathsf{val}_\mathcal{C} = m$$

$$x_i \lor x_j$$

$$(\neg x_i) \lor (\neg x_j)$$



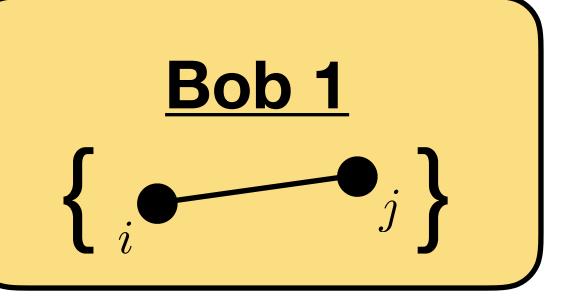
$$\mathbf{v} < \left(\frac{\sqrt{2}}{2} + \epsilon\right) \cdot m$$



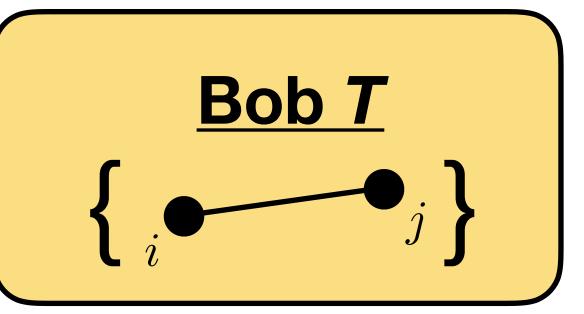


Alice

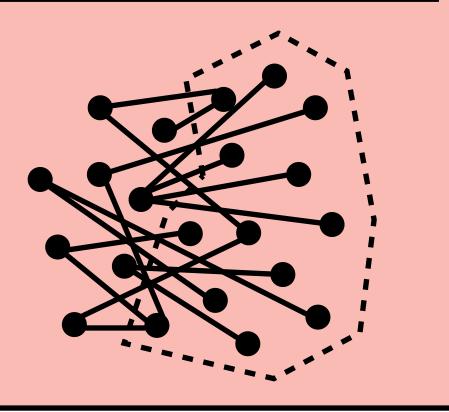
 X^*



. . .

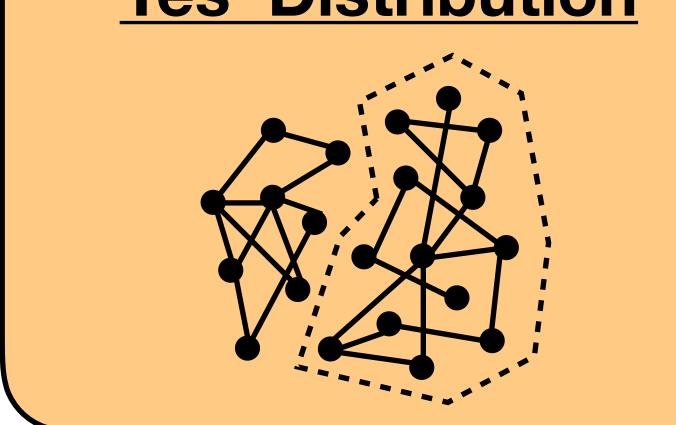


Yes Distribution



$$\mathsf{val}_{\mathcal{C}} < \left(\frac{\sqrt{2}}{2} + o(1)\right) \cdot m$$

Yes' Distribution



$$\mathsf{val}_\mathcal{C} = m$$

$$x_i \lor x_j$$
 Yes \leftarrow ($\neg x_i$) \lor ($\neg x_j$) No $v < \left(\frac{\sqrt{2}}{2} + \epsilon\right) \cdot m$ $v \ge \left(\frac{\sqrt{2}}{2} + \epsilon\right) \cdot m$